

**Final Report** 

# STATISTICAL ANALYSIS OF TERRAIN BACKGROUND MEASUREMENTS DATA

AD A 0 7758 Infrared and Optics Division

**MARCH 1977** 

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Optical Signatures Program Naval Weapons Center China Lake, California

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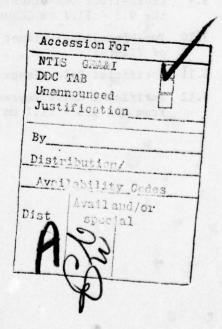
UNCLASSIFIED TY CLASSIFICATION OF THIS PAGE (When Data Entered) the infrequent occurrence of small areas of high intensity which cause seekers and trackers false alarm problems. Area/intensity statistics are reported for two of the scenes.

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#### INTRODUCTION AND SUMMARY

There is a need for both target and background data for the design of sensors to detect and track targets against sky, cloud, and terrain backgrounds. The objective of this backgrounds analysis program is to develop backgrounds data useful to systems designers. The first phase of the program, which has been completed [Reference 1], was to survey the available backgrounds data and compile an index - bibliography of pertinent information. In general there is considerable data on terrain backgrounds but much less on sky and cloud backgrounds. Data is especially lacking for two-dimensional high spatial resolution data on clouds in the spectral bands of interest. In this second phase of the program we have selected a variety of terrain backgrounds for which high spatial resolution multispectral data are available. A variety of statistical measures have been derived from these data and are presented in this technical report. These include the conventional statistical parameters of means, standard deviations, histograms, Wiener (power) spectra, and spectral correlations as well as new area/intensity statistics which are particularly relevant in view of recent advances in sensor and processor technology. Additional efforts to assess the utility of the various background statistical measures will be reported in future technical reports.

Conventional background statistics have in the past been adequate since in many instances there is a high contrast between the target and background. In such instances, the highest intensity background points determine the highest threshold setting necessary to eliminate all false alarms and the histograms provide estimates of how the detection probability and false alarm rate vary with threshold setting. However, today there is a need for higher order background statistics because of the increased sophistication of background rejection techniques employed

<sup>[1]</sup> J. Beard, J. Braithwaite, R. Turner, Infrared Background Survey and Analysis, Environmental Research Institute of Michigan, Ann Arbor, June 1976.

with large detector arrays and imaging or scanning sensors. Although the power spectrum is a background statistic which does vary with the spatial distribution of radiances in the scene, it is clearly an inadequate background descriptor for most of today's problems. Small areas of high radiance produce most of the false alarms in today's sensors, and the power spectrum does not distinguish between scenes with many low intensity areas and those with a few high intensity areas. This is a well known fact and a result which is evident from the background modeling work of R. Clark Jones and the early working group on infrared backgrounds, WGIRB [Reference 2].

Hence, in addition to the conventional statistics on terrain backgrounds, we have also developed area/intensity statistics as a statistical measure that is more directly useful to the sensor designer in estimating detection probabilities and false alarm rates with today's sensor and processor technology. The statistics developed are the probabilities that regions (of various sizes, shapes, and orientations) will occur in the scene above a specified radiance threshold. The region descriptors are area, major and minor axes, and the angular orientation for an elliptical area that is equivalent, in geometric area and ratio of second moments, to each contiguous region above the radiance threshold. For most scenes the number of regions and their areas decrease as the threshold is raised, while the number of small regions above any preset threshold varies from one scene to the next. These area/intensity statistics are analogous to the more familiar pulse length statistics for one-dimensional records.

The statistical parameters for the occurrence of areas and intensities in the various background scenes are not only directly useful for estimating sensor performance but may also be useful in simulating whole classes of backgrounds. The equivalent ellipses at each threshold can be positioned to simulate the actual scene from which they were

<sup>[2]</sup> R. Clark Jones, Dr., The Study of IR Backgrounds by the Wiener Spectrum Method, Polaroid Corporation, Cambridge, Massachusetts, December 1959.

derived, or repositioned at random to simulate many scenes having the same area/intensity statistics. Such simulations of backgrounds do reproduce many of the spatial characteristics of the original scene as is shown by example in this report.

Seven scenes were selected for analysis in this program representing a wide range of backgrounds; two residential scenes (Flint-1 and Baltimore), an industrial scene (Flint-2), a mountainous structured terrain (Mill Creek, OK), a natural busy terrain of trees and hills with numerous shadows (Black Hills, S. D.) and two mountainous unstructured terrains (Pisgah Crater, CA and Mono Lake, CA). These were collected with the ERIM airborne multispectral scanner system with a nominal 5 to 10 foot spatial resolution in spectral bands including 1.0-1.4 μm, 1.5-1.8 μm, 2.0-2.6 μm, 4.5-5.5 μm, and 9.3-11.7 μm. Conventional statistics including means, standard deviations, histograms, and spectral correlations are reported here and calibrated data tapes are available to qualified users for additional statistical analysis and simulation. In addition to these statistics, Wiener (power) spectra and area/intensity statistics are reported for two spectral bands of Flint-l and Mill Creek. An actual simulation of the Flint-l scene in the 9.3-11.7 um spectral band has also been created with equivalent ellipses and is compared with the true background scene.

The remainder of this report is broken down into four sections: Section 2 presents the ERIM calibrated multispectral airborne scanner system; Section 3, the procedures used for calibration and statistical analysis with selected examples; Section 4, a brief discussion of the results of the analysis; and Section 5, a summary with recommendations. The complete data and statistics package is contained in Appendix II.

#### THE MULTISPECTRAL SCANNER\*

Two multispectral scanner systems have been in use at ERIM since 1968. The newer M-7 scanner was used at the time the Flint, Baltimore, and Mill Creek data was generated while its predecessor the M-5 scanner was used in gathering the Pisgah Crater, Black Hills, and Mono Lake data. These two scanners are similar so that only the M-7 will be discussed in detail with the difference between the two systems elaborated on at the end of this section.

The M-7 scanner, covering a wavelength range from 0.33 to 14.0 micrometers, can operate in up to 19 different bands of the ultraviolet, visible, and infrared regions. Of these bands, 12 can be selected for tape recording at any one time on a 14-track analog tape machine. More recently a digital recording system has been added. As many as five separate radiation reference sources may be recorded sequentially along with the ground video once each scan line. The total system, including boresight cameras, is usually operated in a Douglas C-47 aircraft.

The simplified diagrams of Figure 2.1 illustrate a typical line scanner and its method of airborne use. As shown in the optical schematic at the top of the figure, the scanner basically consists of an optical telescope with its narrow field of view redirected by a rotating flat mirror. This mirror causes the system to scan in a plane perpendicular to the longitudinal axis of the aircraft. A radiation detector in the focal plane of the telescope converts the focused beam of radiation to an electrical signal. The optical system's field-of-view (ground resolution element) first scans laterally across the aircraft ground track through an opening in the bottom of the aircraft. Then before making the next ground scan, it scans radiation references (not shown) which are internal to the scanner. By the time the next scan begins, the aircraft has moved forward, thus subsequent line scans build upon one another to produce a continuous strip image of the terrain beneath the aircraft.

<sup>\*</sup> The ERIM Airborne Multispectral Data Collection is described in the ERIM 190901-1-F report prepared by Philip G. Hasell, Jr. under contract NAS 9-9304. The multispectral scanner as described in that report, is presented here in order to familiarize the reader with the multispectral scanner system used to collect the data which is being processed on this program.

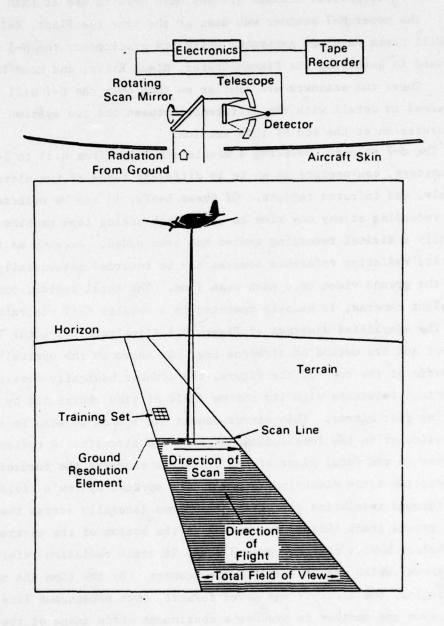


FIGURE 2.1 AIRBORNE MULTISPECTRAL SCANNER OPERATION

The multispectral scanner evolved from this single-channel scanner concept. This evolution required replacement of the single detector element with a system of beamsplitters, dispersing optics, and spectral filters. Figure 2.2 shows the optical configuration of the current M-7 multispectral scanner. A key feature in this design is its flexibility for accepting different radiation reference sources and new detector assemblies. Weight and space savings were sacrificed to provide this flexibility, which allows increased opportunities for adaptation to a diverse number of data gathering modes. Such flexibility is an important attribute for a general-purpose experimental system.

The radiation intercepted by the 5-inch-diameter collecting aperture is directed into the Dall-Kirkham telescope, which has a 3-inch-diameter secondary mirror. The incoming radiation prevented from entering the telescope by this secondary mirror is directed upward by a folding mirror to Detector Position 1. This 3-inch-diameter collecting aperture operates over the broad band of 0.3 to 14.0 µm. To provide thermal data at this position, a focusing lens designed for the 8.0-14.0 µm band is used in combination with a cooled HgCdTe detector. A dichroic mirror mounted ahead of this lens diverts ultraviolet and visible radiation onto a photomultiplier detector which is filtered so the energy it receives for recording is restricted to a narrow preselected band.

The radiation collected by the effective 4-inch aperture of the Dall-Kirkham telescope is folded into a dichroic mirror which reflects radiation below 1.0  $\mu m$  but transmits that of longer wavelengths. The radiation thus transmitted is focused onto three separately filtered indium arsenide detector elements in Position 2 by lens achromatized for the 1.0 to 2.6  $\mu m$  region. This dichroic and lens can be readily changed for different detector configurations.

Radiation at wavelengths shorter than 1.0  $\mu m$  is focused onto the entrance slit of a prism spectrometer at Detector Position 3. The spectrometer divides and directs visible and near-infrared radiation

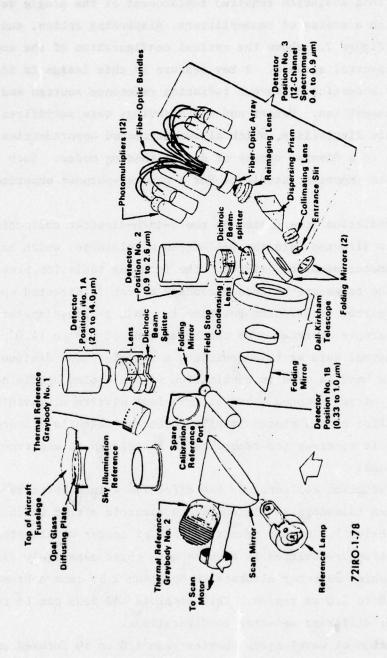


FIGURE 2.2 OPTICAL SCHEMATIC OF ERIM EXPERIMENTAL MULTISPECTRAL SCANNER, M7

through a fiber-optic image slicer to as many as twelve photomultiplier tubes. (In the current configuration the radiation goes to nine separate photomultipliers.)

The radiation reference sources are positioned in line with the scan mirror, so that each source is "seen" and registered sequentially once each scan line. Currently, five reference sources are being used: an NBS lamp packaged to simulate a point source; one ambient and two temperature-controlled graybody thermal references that fill the collecting aperture; and a sky illumination reference consisting of an opal glass diffusing plate mounted in the top of the aircraft. Through electronic control of the lamp and graybodies and by means of attenuating optical filters for the sky illumination, the radiation from all but the ambient temperature reference sources is under operator control. During data collection, all internal sources are monitored and recorded manually by the operator. To assure their validity as references, these sources are calibrated periodically against external standards in the laboratory.

The complete airborne scanner system is diagrammed in Figure 2.3. Terrain radiation enters the scanner at the bottom left; radiation detectors in the scanner assembly register this input along with that of the reference sources. The electrical signals comprising detector video outputs are amplified in preamplifiers before being transmitted to the operator console where the operator monitors them and adjusts amplifier gain to the proper level for tape recording. To confirm satisfactory recording, he is also able to monitor signals reproduced from the tape record. The system linearly transforms input radiation to voltage analogs which are recorded on the magnetic tape. The scanner system can generate video signals in up to nineteen different spectral bands over a wavelength range extending from 0.33 to 14.0  $\mu$ m. Any twelve of these bands may be tape recorded at any one time on a 14-track analog tape machine; the other two tape recorder tracks are used for housekeeping purposes.

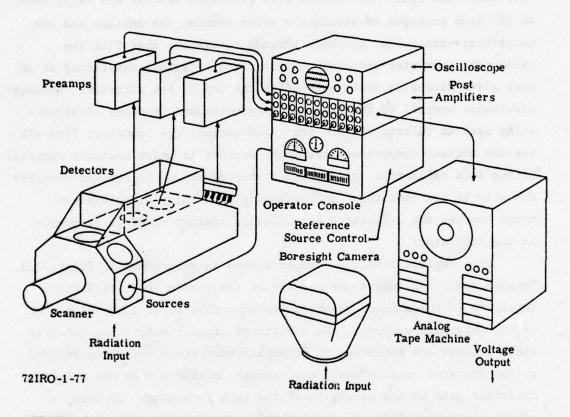


FIGURE 2.3 ERIM EXPERIMENTAL MULTISPECTRAL SCANNER SYSTEM

The airborne system (Figure 2.3) also includes an array of boresight cameras utilizing various film-filter combinations. These aerial cameras produce film records often useful in the subsequent analysis of the scanner data.

Electrical voltage representations of single line scans for the thermal and non-thermal wavelength bands are shown in Figure 2.4. Note that although the detectors in all positions view, in sequence, each of the radiation references as well as the terrain (see "ground scan"), only the graybody references apply to every wavelength band. These graybody references (#1 and #2 and thermal ambient) serve as temperature calibration sources for the thermal detectors and also as a dark level source for the shorter-wavelength non-thermal detectors. The remaining sources (lamp and sky) serve as references for the non-thermal bands (as shown). For indexing purposes, synchronization references are generated by the scanner and recorded with the video signals. The marker pulse refers to the scan position relative to the internally mounted radiation references; the roll-stabilized pulse refers to ground scan nadir with aircraft roll motion removed.

Table 2.1 lists significant parameters of the M-7 scanner system. The scanner views the terrain during 90° of its scan, providing an external field of view (FOV)  $\pm$  45° from nadir. A nominal 0.1°C NEAT and a 1% NEAp are achieved.\* The system operates at either of two constant scan speeds - 60 or 100 scans per second. Electronic bandwidth is tape-recorder-limited to a range of dc to 90 kHz. Table 2.2 identifies those detector assemblies currently in use with the system. Where there is a choice of detectors, the first-listed unit is the one commonly used.

The M-5 scanner, shown schematically in Figure 2.5, is a double-ended scanner using a double "axe-blade" scanning mirror to direct radiation to the two ends. In most respects it is the same as the M-7 except that the data collected from the two ends of the scanner

<sup>\*</sup>NE $\Delta t$  = Noise Equivalent change in Temperature NE $\Delta \rho$  = Noise Equivalent change in reflection

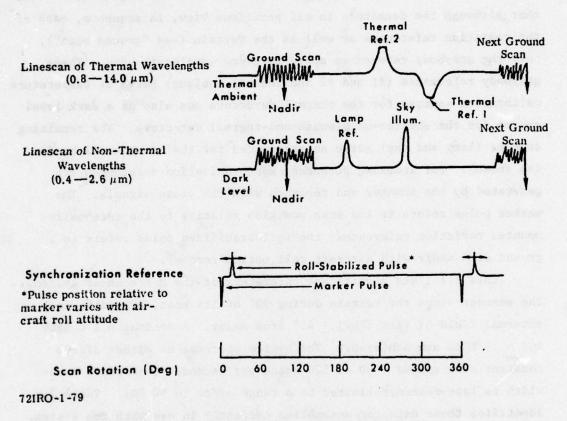


FIGURE 2.4 SCANNER VOLTAGE OUTPUT VERSUS TIME

### TABLE 2.1

# M7 SCANNER PERFORMANCE CHARACTERISTICS

12 Spectral Bands in UV, Visible and IR Regions
90° External FOV (+45° from nadir)
2 mrad Maximum Spatial Resolution
0.1°C Nominal Thermal Resolution
1% Nominal Reflectance Resolution
Five Radiation Reference Ports
5-inch Diameter Collector Optics
Scan Rate of 60 or 100 scans/sec
DC to 90 kHz Electronic Bandwidth
Roll-Stabilized Imagery

TABLE 2.2

DETECTOR CONFIGURATIONS FOR ERIM M-5 AND M-7 SCANNER SYSTEMS

osition 3 <sup>‡</sup>	1.1.m)*	Band IFOV (mrad)		0.65-0.80 2.5 2.5	0.60-0.70 2.5 2.5	0.55-0.64 2.5 2.5	0.52-0.59 2.5 2.5	0,49-0.55 2.5 2.5	0.45-0.51 2.5 2.5	0.40-0.47 2.5 2.5		0.67-0.94 2 2	0.62-0.70 2 2	0.58-0.64 2 2	0.55-0.60 2 2	0.52-0.57 2 2	0.50-0.54 2 2	0.48-0.52 2 2	0 16 0 40
Detector Position 3 <sup>‡</sup>	(0.4 .m-1.1 .m)	B Detector (1	PM9-1 0.83	0.65	0.60	0.5	0.52	0.49	1.0	0.40	00	PNI 12-1 0.67	9.0	0.58	0.5	0.5	0.50	9.48	970
21		IFOV (mrad)	2.0 . 4.0	2.0 × 4.0		2.0 × 4.0	2.0 . 4.0			2.0 < 4.0	2.0 . 4.0	2.0 < 4.0		2.6 . 2.6	2.6 × 2.6		1.0-2.6 3.0 < 3.0		40×40
Detector Position 2 <sup>‡</sup>	(1.1 m-14 m)	Band (_m)	2.0-2.6			2.0-2.6	1.0-1.4	-10	;	2.0-2.6	1.5-1.8	1.0-1.4	or	2.0-2.6	1.0-1.8	or	1.0-2.6	or	2.0-15.0
Detecto	1.13	Detector	In.As 3-5			InSb 3-6				In.As 3-6				HgCdTe 2-3 2.0-2.6			InAs 1-2		HordTe 1-2 2.0-15 0 4.0 × 4.0
	m).	IFOV (mrad)	3.0 . 3.0																
	Position 1B (0.3.m-0.7 am)	Band (µm)	-																
Detector Position 1 <sup>t</sup> (0.3 am-15.0 am)	Po (0.3	Detector	UVPM1-3																
		(mrad)	3.1 · 3.1	9.9 . 9.9		21 . 28	21 . 21			20 × 20	20 20	20 . 20		3.3 . 3.3					
Det	Position 1A	Band (am)	2.0-11.8	2.0-15.0		20109	9.4-12.1		or	2.0 -9.1	8.7 10.7	9.9-14.0	or	2.0-12.0					

Notes: \*Bandpass established by replaceable dichroic mirror.

\*\*Bandpass established by external optical filter.

fAny band between 0.3 im and 0.7 im may be selected by external optical filter.

tany one of the detectors shown may be installed in the position shown. Any 12 channels of a given configuration may be selected for FM recording on magnetic tape.

HgCdTe 3-1

HgCdTe 1-5

HgCdTe 1-3 HgCdTe 1-2

Detector

HgCdTe 2-2

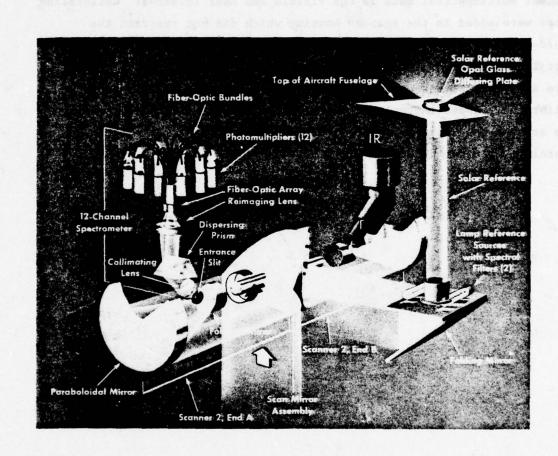


FIGURE 2.5 ERIM M-5 MULTISPECTRAL SCANNER

are 90° out of phase. Two M-5 scanners in the aircraft were used to collect data. Essentially the same detector assemblies were used with the M-5 as are used with the M-7 system. One M-5 scanner was used to collect multispectral data in the visible and near infrared. Calibration lamps were added in the scanner housing which did not restrict the field-of-view below the aircraft. Another M-5 scanner was used to collect thermal data, and "hot" and "cold" graybody thermal references were added at the scanner aperture so the thermal IR channels could be calibrated. These thermal plates extended into the field-of-view of the scanner below the aircraft so that the video was limited to approximately  $\pm$  20° from nadir.

# PROCEDURES AND SELECTED EXAMPLES

The multispectral scanner data selected for terrain backgrounds statistical analysis on this program were recorded on analog magnetic tape, and these analog tapes were converted to high density digital tapes. The general pre-processing procedure used to create calibrated data tapes is discussed in Section 3.1 with a detailed discussion of the procedures used for each scene being presented in Appendix I. The statistical measures derived from the data are described in Section 3.2; point statistics in Section 3.2.1 and correlative statistics in Section 3.2.2. Three types of correlative statistics are discussed. These include spectral correlations between pairs of bands; area/intensity statistics and the development of the equivalent elliptical area concept; and oneand two-dimensional Wiener (power) spectra. In Section 3.3 an example is shown in which the original background scene is actually replaced by the equivalent elliptical areas and most of the spatial information is preserved.

Examples of each type of statistical data are presented in Section 3, with the complete summary of terrain backgrounds statistical data included as Appendix II.

#### 3.1 PREPROCESSING OF SCANNER DATA

Output from the ERIM scanners was converted to high-density-digital tapes in which each data value is recorded as an 8-bit integer ranging in value from 0 to 255. Each channel (wavelength band) is recorded on a separate tape channel and the amplifier gains adjusted so that all data values fall in the 0 - 255 range. On this tape the scan lines for a single M-7 scanner channel or reflective IR M-5 scanner channel consists of 790 data points of which the first 646 are scene elements (pixels) covering the range -45° to +45° with respect to nadir while the remaining 144 points are calibration values, 24 data points

for each of 6 calculation sources. For the thermal M-5 scanner channels the scanner elements cover pixels 162 to 484 with pixels 1 - 161 and 485 - 646 being used for the graybody thermal sources.

Before the scanner data may be used to generate scene statistics some pre-processing is required:

- 1) The high density digital tapes must be converted to computer compatible tapes:
- 2) Each channel must be calibrated in temperature or radiance using the calibration data at the end of each scan line;
- Averaging was employed to reduce oversampling and to equalize any differences in the fields-of-view of the various detectors; and
- 4) A set of calibrated, formatted tapes must be generated.

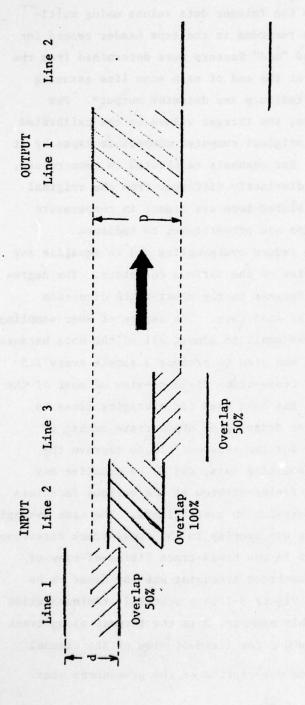
The first of these processes, conversion of high density tapes to computer compatible tapes, has been accomplished using the conversion facilities at Bendix Aerospace Systems Division in Ann Arbor and the MIDAS computer system at ERIM. The result of this conversion process was a low density (800 BPI) tape for each of the scenes desired. Using these tapes, the remainder of the pre-processing (2,3, and 4) was performed using a computer code written for the University of Michigan's AMDAHL computer system. It is the set of calibrated tapes generated from this code that are used for all image processing.

The data values appearing on the calibrated tapes are themselves integers, ranging from 0 to 255, but these integers have been modified so that a linear relationship exists between them and the apparent scene radiance or temperature. The data in the near IR channels was converted to equivalent radiance in uw/cm²·sr·µm). The equivalent radiance is the value of the spectral radiance at the center wavelength of the filter produced by a 2850 K NBS lamp source filling the sensor aperture and giving the same detector response. The data in the thermal IR channels was converted to apparent temperature in degrees Kelvin. The apparent temperature is the temperature of a blackbody filling the sensor aperture producing the same detector response.

A table of apparent temperatures and their corresponding band radiances is included as Table I-1 in Appendix I. The radiance (or temperature) is recovered from the integer data values using multiplicative and additive factors recorded in the tape header record for each channel. These "mult" and "add" factors were determined from the calibration sources appearing at the end of each scan line assuming a linear relationship between radiance and detector output\*. For channels calibrated in radiance, the integer values on the calibrated tape differ from those on the original computer compatible tapes by at most a zero level correction. For channels calibrated in temperature, however, the new integers are distinctly different from the original values since those on the calibrated tape are linear in temperature while those on the original tape are proportional to radiance.

Averaging was employed to reduce oversampling and to equalize any differences in the fields-of-view of the various detectors. The degree of oversampling was generally largest in the along-track direction because of the constant (60/sec) scan rate. The degree of over sampling in the cross-track direction was small in almost all of the data because a 3.8 x 10 /sec. sampling rate was used to produce a sample every 2.5 mr to correspond to the 2.5 mr cross-track field-of-view of most of the detectors. The technique that has been used for averaging lines to reduce oversampling, rather than dropping an appropriate number of alternate lines, was developed for two reasons: 1) to improve the signal-to-noise ratio in the resulting data, and 2) to equalize any differences in the along-track fields-of-view of the various detectors for calculating the spectral correlation coefficients. The same averaging technique can be used to reduce any overlap in the cross-track direction and to equalize any differences in the cross-track fields-of-view of the various detectors, but cross-track averaging was not found to be necessary in any of the data. Figure 3-1 is a schematic representation In this example, D is the largest along-track of the procedure used\*. field-of-view of the channels and d the field-of-view of the channel

<sup>\*</sup> See Appendix I for a detailed description of the procedures used.



Output Line 1 = {0.5 (Input Line 1) + 1.0 (Input Line 2)
+ 0.5 (Input Line 3)}/2.0

FIGURE 3-1 SCHEMATIC REPRESENTATION OF THE PROCEDURES USED FOR FIELD-OF-VIEW AVERAGING

being averaged. The averaging was done by summing the radiances of the scan line times their overlap with the desired output line and dividing by the sum of the overlap factors. If the scan lines for the largest field-of-view were themselves overlapped, non-overlapped fields-of-view were generated by taking as output lines those with fields-of-view D each of which was displaced by D as in the right side of Figure 3-1. Overlap factors were then determined in an identical manner between the original scan lines with field-of-view D and this set of non-overlapped output lines.

After calibration and field-of-view averaging, a new data tape was generated. To be compatible with existing data processing systems, this tape was written in ERIM-7094 format which consists of 36-bit words each of which contain 4 data values. The individual scan lines were written with the channels interleaved with 646 9-bit data points per channel per scan line. The "mult" and "add" factors required for calibration of the data were written in the tape header record along with necessary format information. These tapes could then be used directly as input to new or existing statistics generation programs.

## 3.2 STATISTICS DEFINITIONS

Several sets of statistics have been generated for each of the chosen scenes. These may broken down into two groups:

- Point statistics: Those defined by individual data points in a single channel; and
- Correlative and area statistics: Those requiring calculation of correlation effects for a scene either in a single channel or between channels.

#### 3.2.1 POINT STATISTICS: MEANS AND STANDARD DEVIATIONS

The point statistics generated were the mean and standard deviation for each channel and a histogram of the data value distributions of these channels. To determine the degree of homogenity that existed, the total scene was broken down into sub-areas and the point statistics

generated for these sub-areas as well as for the total area. In practice, the sub-area statistics were generated first and the total area statistics derived from them.

The mean value for sub-area  $\eta$  in Channel J  $(\overline{x(J)}_{\eta})$  was evaluated using

$$\overline{\mathbf{x}(\mathbf{J})_{\eta}} = \frac{1}{N_{\eta}} \sum_{i=1}^{N_{\eta}} \mathbf{x}(\mathbf{J})_{i}$$
 (1)

where  $x(J)_i$  is the data value of pixel i in Channel J and  $N_\eta$  is the total number of data points in the sub-area. Using the same notation the standard deviation,  $\sigma(J)_n$ , is given by

$$\sigma^{2}(J)_{\eta} = \left(\frac{N_{\eta}}{N_{\eta} - 1}\right) \left\{\frac{1}{N_{\eta}} \sum_{i=1}^{N_{\eta}} x^{2}(J)_{i} - \overline{x(J)}_{\eta}^{2}\right\}$$
(2)

The corresponding total scene values in Channel J are then related to those of the sub-areas through the following relations

$$\overline{x(J)} = \frac{1}{N} \sum_{n} N_{\eta} \overline{x(J)}_{\eta}$$

and (3)

$$\sigma^{2}(J) = \left(\frac{N}{N-1}\right) \left\{ \frac{1}{N} \sum_{\eta} N_{\eta} \left[ \left(\frac{N_{\eta}-1}{N_{\eta}}\right) \sigma^{2}(J)_{\eta} + \overline{x(J)}_{\eta}^{2} \right] - \overline{x(J)} \right\}$$

where N is the number of points in the total scene. Typical examples of these statistics, generated from the Flint-1 data, are given in Table 3-1. In this scene the sub-areas had on the order of 77,000 data points while the total scene had approximately 464,000 points.

At the same time that these statistics were generated, the number of data points having each of the possible data values (0 to 255) was tabulated and this tabulation used to generate histograms for the scene. Representative sub-areas and total area histograms for the 9.3 to 11.7  $\mu$ m channel of Flint-1 are shown in Figures 3-2 and 3-3 respectively.

SUB-AREA AND TOTAL AREA MEANS AND STANDARD DEVIATIONS FOR FLINT-1 All entries have units of  $\mu w/(cm^2 \cdot sr. \mu m)$  except for the 9.3-11.7  $\mu m$  band which is in degrees Kelvin. TABLE 3-1.

TOTAL		1273	364		173	83		36	10		294	3.1
SUB-AREA 6		1231	355		125	73		30	80		293	2.7
SUB-AREA 5		1312	355		159	80		35	6		294	3.1
SUB-AREA 4		1191	344		192	80		36	10		295	3.3
SUB-AREA 3		1306	424		164	82		34	11		294	2.6
SUB-AREA 2		1278	355		180	74		38	7		295	3.5
SUB-AREA 1		1280	347		230	77		41	11		295	2.7
	1.0 - 1.4 нт	Mean	Std. Dev.	1.5 - 1.8 µm	Mean	Std. Dev.	2.0 - 2.6 µm	Mean	Std. Dev.	9.3 - 11.7 им	Mean	Std. Dev.

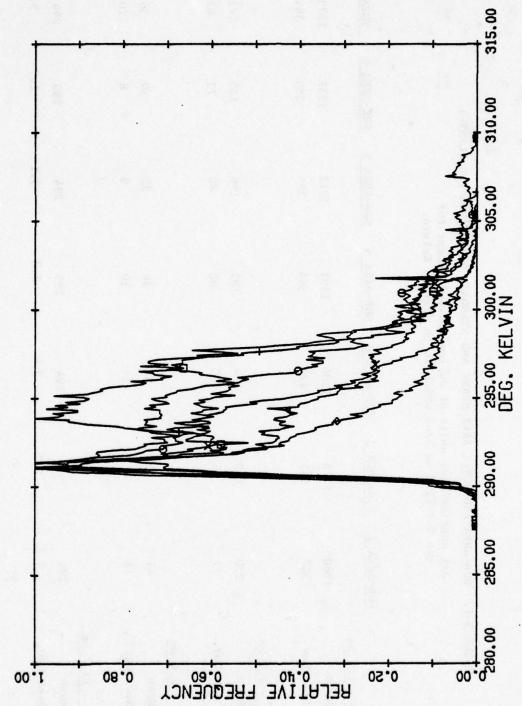
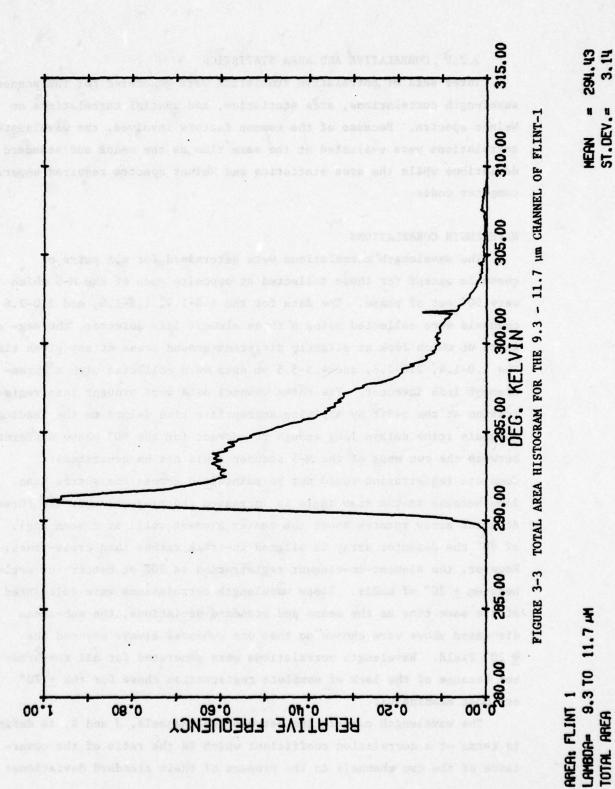


FIGURE 3-2 SUBAREA HISTOGRAMS FOR THE 9.3 - 11.7 µm CHANNEL OF FLINT-1

AREA: FLINT 1 LAMBOR= 9.3 TO 11.7 AM SUBAREAS



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#### 3.2.2 CORRELATIVE AND AREA STATISTICS

Three sets of correlative statistics were generated for the scenes: wavelength correlations, area statistics, and spatial correlations or Weiner spectra. Because of the common factors involved, the wavelength correlations were evaluated at the same time as the means and standard deviations while the area statistics and Weiner spectra required separate computer codes.

#### WAVELENGTH CORRELATIONS

The wavelength correlations were determined for all pairs of channels except for those collected at opposite ends of the M-5 which were 90° out of phase. The data for the 1.0-1.4, 1.5-1.8, and 2.0-2.6 µm channels were collected using a three element InAs detector, the segments of which look at slightly different ground areas at any given time. The 1.0-1.4, 2.0-2.6, and 4.5-5.5  $\mu$ m data were collected with a threeelement InSb detector. The three channel data were brought into registration at the nadir by applying appropriate time delays to the leading channels (time delays long enough to correct for the 90° phase difference between the two ends of the M-5 scanner could not be generated). Complete registration could not be maintained across the entrie scan line because as the scan angle is increased the projection of the three detector array rotates about the center element until at a scan angle of 90° the detector array is aligned in-track rather than cross-track. However, the element-to-element registration is 50% or better for angles between + 20° of nadir. Since wavelength correlations were calculated at the same time as the means and standard deviations, the sub-areas discussed above were chosen so that one sub-area always covered the + 20° field. Wavelength correlations were generated for all sub-areas but because of the lack of complete registration those for the + 20° are most meaningful.

The wavelength correlation between two channels, J and K, is defined in terms of a correlation coefficient which is the ratio of the covariance of the two channels to the product of their standard deviations:

$$COR(J,K) = \frac{COV(J,K)}{\sigma(J)\sigma(K)}$$
(4)

where COR(J,K) is the correlation coefficient for the two channels,  $\sigma(J)$  and  $\sigma(K)$  their standard deviations, and COV(J,K), the J-K element of the covariance matrix for a given sub-area , is defined as

$$COV(J,K)_{\eta} = \frac{N_{\eta}}{N_{\eta} - 1} \left\{ \frac{1}{N_{\eta}} \sum_{i=1}^{N_{\eta}} x(J)_{i} x(K)_{i} - \overline{x(J)_{\eta}} \overline{x(K)_{\eta}} \right\}$$
 (5)

where all symbols are the same as those of Equations 1 and 2. The reason for the simultaneous evaluation of Equations 2 and 5 is obvious: the square of the standard deviation  $\sigma^2(J)$  is the autocovariance or the covariance of a given channel with itself COV(J,J).

An example of the correlation coefficients for the infrared channels of Flint-1 are given in Table 3-2.

## AREA/INTENSITY STATISTICS

Since means, standard deviations, and histograms do not give any information about the positions of data values in the scene or possible clustering of these values, area statistics have been generated by determining contiguous regions of the scene for which the enclosed points had values greater than some prescribed threshold [Reference 3]. Once these regions had been defined, their geometric centroids, areas, and second moments were determined and these parameters used to define a set of equivalent elliptical areas. The output from this procedure was, for each threshold level, a tabulation of centroids, tilt angles and semi-major and minor axes defining the equivalent ellipses.

The semi-major and semi-minor axes of the equivalent ellipses were taken coincident with the principal axes of the regions they represented. If  $I_x^c$  and  $I_y^c$  are the second moments of a region about the centroid and  $I_{xy}^c$  its product of inertia, the angle of rotation of the principal axes relative to a fixed x-y coordinate system is given by

<sup>[3]</sup> W. G. Burge, W. L. Brown, A study of Waterfowl Habitat in North Dakota Using Remote Sensing Techniques, Report No. 2771-7-F, Willow Run Laboratories, University of Michigan, Ann Arbor, July 1970.

TABLE 3-2
CORRELATION COEFFICIENTS FOR THE TOTAL AREA OF FLINT-1

Spectral Correlation	1.0-1.4 μm	1.5-1.8 μm	2.0-2.6 μm	9.3-11.7 μm
1.0- 1.4 μm	1.000			
1.5- 1.8 µm	0.392	1.000		
2.0- 2.6 µm	0.303	0.603	1.000	
9.3-11.7 μm	-0.455	0.048	0.177	1.000

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$$\alpha = \frac{1}{2} \tan^{-1} \left\{ \frac{2I_{xy}^{c}}{I_{y}^{c} - I_{x}^{c}} \right\}$$
 (6)

(7)

where  $\alpha$  is in radians. The second moments of the region about the <u>principal</u> axes are then given by

$$I_{x'} = \left(\frac{I_x^c + I_y^c}{2}\right) + \left(\frac{I_x^c - I_y^c}{2}\right) \cos 2\alpha - I_{xy}^c \sin 2\alpha$$

and

$$I_y$$
, =  $\left(\frac{I_x^c + I_y^c}{2}\right) - \left(\frac{I_x^c - I_y^c}{2}\right) \cos 2\alpha + I_{xy}^c \sin 2\alpha$ 

Since the area and the second moments of an arbitrary region cannot be simultaneously matched using an ellipse, equality was demanded between the geometric areas and the <u>ratios</u> of the principal moments. If the semi-major and semi-minor axes of the ellipse are defined as a and b respectively and the a-axis is aligned with the larger of the principal axes of the region, these equalities give

$$a^2 = \frac{A}{\pi} \sqrt{\frac{I_1}{I_2}}$$

and (8)

$$b^2 = \frac{A}{\pi} \sqrt{\frac{I_2}{I_1}}$$

where A is the area of the region and  $I_1$  and  $I_2$  are the moments given by Equation 7 with  $I_1>I_2$ . If  $I_y$ , of Equation 7 is the larger of the moments, the a-axis of the ellipse is oriented at an angle  $\alpha$  with respect to the fixed x-axis; if  $I_x$ , is larger, the a-axis is at an angle  $\alpha+\pi/2$ . An example of the equivalent elliptical areas generated for the 9.3 - 11.7  $\mu$ m channel of Flint-1 is shown in Figures 3-4 through 3-7. Each of these figures represents the areas found for data values

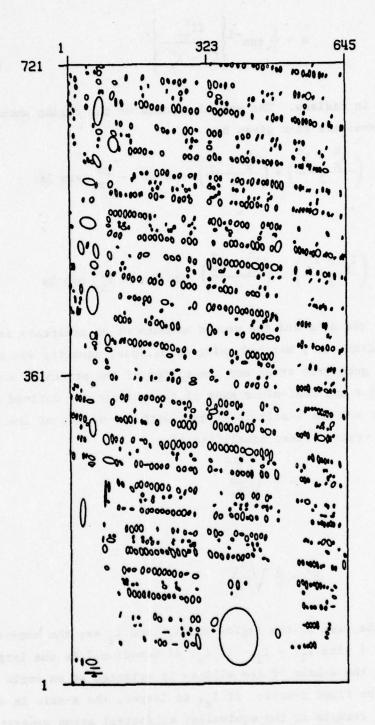


FIGURE 3-4 EQUIVALENT ELLIPTICAL AREAS FOR THE 9.3 - 11.7 µm CHANNEL OF FLINT-1 WITH A 1.5σ THRESHOLD

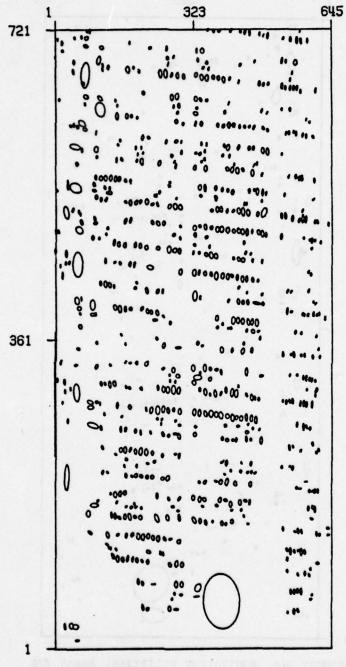


FIGURE 3-5 EQUIVALENT ELLIPTICAL AREAS FOR THE 9.3 - 11.7  $\mu m$  CHANNEL OF FLINT-1 WITH A 2.0 $\sigma$  THRESHOLD

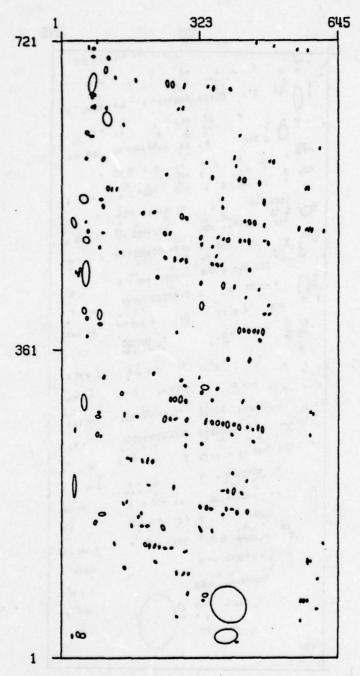


FIGURE 3-6 EQUIVALENT ELLIPTICAL AREAS FOR THE 9.3 - 11.7 µm CHANNEL OF FLINT-1 WITH A 2.50 THRESHOLD

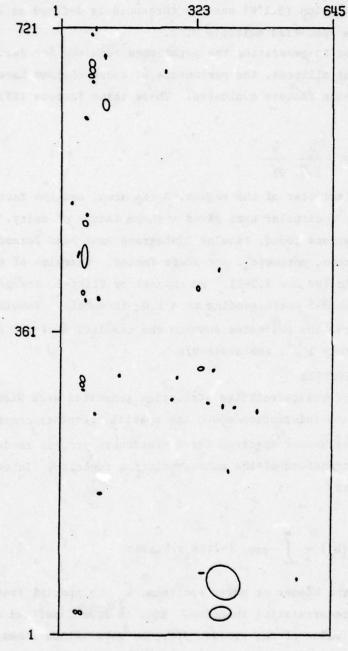


FIGURE 3-7 EQUIVALENT ELLIPTICAL AREAS FOR THE 9.3 - 11.7 µm CHANNEL OF FLINT-1 WITH A 3.00 THRESHOLD

exceeding the specified threshold (1.5 $\sigma$ , 2.0 $\sigma$ , 2.5 $\sigma$ , 3.0 $\sigma$ ) where  $\sigma$  is the standard deviation (3.1 $^{\circ}$ K) and the threshold is defined as the mean (294 $^{\circ}$ K) plus the specified multiple of  $\sigma$ .

In addition to generating the parameters required for definition of the equivalent ellipses, the perimeters of these regions have been tabulated and shape factors evaluated. These shape factors (SF) were defined as

$$SF = \frac{1}{2\sqrt{\pi}} \frac{P}{\sqrt{A}}$$
 (9)

where P is the perimeter of the region, A its area, and the factor  $1/2\sqrt{\pi}$  included so that a circular area gives a shape factor of unity.

For all regions found, tabular histograms have been formed sorting the regions by area, perimeter, and shape factor. Examples of these histograms, again for the 9.3-11.7  $\mu m$  channel of Flint-1, are given in Table 3-3 through 3-5 corresponding to a  $1.0_{\odot}$  threshold. Tabulations with increments in area and perimeter down to the resolution of the scanner data, approximately 1 m<sup>2</sup>, are available.

## WIENER (POWER) SPECTRA

The last of the correlative statistics generated were Wiener spectra which gave information about the spatial frequency content of the images. The Weiner spectrum for a stationary process is defined as the Fourier transform of the autocorrelation function. In one dimension this is

$$S(k_{x}) = \int_{-\infty}^{\infty} \exp(-2\pi i k_{x} x) R(x) dx$$
 (10)

where  $S(k_x)$  is the Wiener or power spectrum,  $k_x$  the spatial frequency and R(x) the autocorrelation function. R(x) is itself defined as the expectation value of the product of scene data values times the corresponding values for the scene when displaced by x:

$$R(x) = E \{f(X)f(X + x)\}$$
 (11)

SQUAR	E METERS	FREQUENCY
0.0 T	0 100.0	2047
100.0 T	0 200.0	78
200.0 T	0 500.0	26
500.0 T	0 1000.0	8
1000.0 T	0 1500.0	2
1500.0 T	0 2000.0	0
2000.0 T	0 2500.0	0
2500.0 T	3000.0	0
3000.0 T	0 4000.0	1
4000.0 T	5000.0	0
5000.0 T	6000.0	0
6000.0 T	0.0008	1
8000.0 T	0 10000.0	0
10000.0 T	0 15000.0	0
15000.0 T	20000.0	0
20000.0 T	40000.0	0
40000.0 T	0.00008	0
80000.0 T	0 160000.0	0
OVE	R 160000.0	0

ME	ETER	RS		FEI	T	FREQUENCY
0	то	50	0	то	164	1991
50	то	100	164	то	328	128
100	то	150	328	TO	492	16
150	то	200	492	то	656	15
200	то	250	656	TO	820	5
250	то	300	820	то	984	3
300	TO	350	984	то	1148	1
350	то	400	1148	то	1312	1
400	TO	500	1312	то	1640	1
500	TO	600	1640	TO	1968	0
600	то	700	1968	то	2296	0
700	то	800	2296	то	2624	0
800	то	900	2624	то	2952	1
900	то	1000	2952	то	3280	1
1000	TO	1200	3280	TO	3937	0
1200	то	1400	3937	TO	4593	0
1400	TO	1600	4593	TO	5249	0
1600	то	2000	5249	то	6561	0
ov	ER	2000	70	ER	6561	0

TABLE 3-5 SHAPE FACTOR DISTRIBUTIONS FOR RECOGNIZED REGIONS IN THE 9.3-11.7  $\mu m$  CHANNEL OF FLINT-1 WITH A 1  $\sigma$  THRESHOLD

SHAPE FACTOR	FREQUENCY
0.0 TO 1.0	11
1.0 TO 1.1	2
1.1 TO 1.2	447
1.2 TO 1.3	363
1.3 TO 1.4	513
1.4 TO 1.5	280
1.5 TO 1.6	227
1.6 TO 1.7	133
1.7 TO 1.8	59
1.8 TO 1.9	50
1.9 TO 2.0	34
2.0 TO 2.2	43
2.2 TO 2.4	21
2.4 TO 2.6	9
2.6 TO 2.8	7
2.8 TO 3.0	5
3.0 TO 3.5	15
3.5 TO 4.0	3
OVER 4.0	1

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where E represents the expectation value of the argument. The Wiener spectrum may be evaluated without first determining the autocorrelation function if the integral

$$\int_{-\infty}^{\infty} |xR(x)| dx$$
 (12)

is bounded, which is usually the case for non-periodic data with zero mean. In this case it may be shown that [Reference 4]

$$S(k_{x}) = \lim_{x \to \infty} \left| \int_{x_{1}}^{x_{2}} f(x) \exp(-2\pi i k_{x} x) dx \right|^{2}$$
(13)

so that the Wiener spectrum is, in the limit, the modulus squared of the Fourier transform of the scene. Written in terms of the discrete Fourier transform, this equation becomes

$$S(j) = \frac{\Delta x}{(N-1)} \left| \sum_{\ell=0}^{N-1} f(\ell) \exp(-2\pi i j \ell/N) \right|^2$$
 (14)

where N is the total number of points being transformed, i is the square root of  $\neg 1$ , and the spatial frequency  $k_{_{\mbox{X}}}$ , evaluated only at integer values of j, is given by

$$k_{x} = \frac{j}{N\Delta x} \tag{15}$$

where  $\Delta x$  is the displacement between successive data points.

It may be seen from Equation 14 that the Wiener spectrum S(j) is symmetric about j = N/2 since

$$\exp \left(-2\pi i(N-j)\ell/N\right) = \exp \left(+2\pi ij\ell/N\right) \tag{16}$$

<sup>[4]</sup> A. Papoulis, Probability, Random Variables, and Stochastic Processes, McGraw-Hill Book Company, New York, 1965.

Hence

$$S(N - j) = S(j)$$
 for  $j = 1, 2, ..., N/2$  (17)

and only the first half of the Wiener spectrum needs to be evaluated. The calculated frequency range is then

$$\frac{1}{N\Delta x} \le k_x \le \frac{1}{2\Delta x} \tag{18}$$

The two dimensional Wiener spectrum is defined in an analgous manner except that two transforms are required, one for each dimension:

$$S(j, \ell) = \left(\frac{\Delta x}{N-1}\right) \left(\frac{\Delta y}{M-1}\right) \left| \sum_{n=0}^{N-1} \exp(-2\pi i j n/N) * \right|$$

$$* \sum_{m=0}^{M-1} \exp(-2\pi i \ell m/M) f(n,m) \left| 2 \right|$$
(19)

where the spatial frequencies in the two dimensions are given in terms of the integers j and  $\ell$  by

$$k_x = \frac{1}{N\Delta x}$$
 and  $k_y = \frac{\ell}{M\Delta Y}$  (20)

One dimensional Wiener spectra were evaluated both cross-track (along scan line) and in-track (parallel to the aircraft flight paths). These are average spectra since Equation 14 was used to transform individual "lines" of data and the transforms have been averaged over a number of "lines". Since the Fourier transform algorithms were substantially less expensive if the number of points transformed was a power of 2, only 512 points were used for both the cross-track and in-track "lines" of data. The middle 512 scan lines were averaged to obtain the cross-track Wiener spectra; 25 along-track lines equally spaced across the image were averaged to obtain the in-track Wiener spectra. Examples of in-track and

cross-track Wiener spectra for the 9.3-11.7  $\mu$ m channel of Flint-1 are shown in Figures 3-8 and 3-9. The units of power density are (K)<sup>2</sup>/cycle per meter for the 9.3-11.7  $\mu$ m band and  $(\mu w/cm^2 \cdot sr \cdot \mu m)^2$ /cycle per meter for the 1.0-1.4, 1.5-1.8 and 2.0-2.6  $\mu$ m bands.

Representative two-dimensional Wiener spectra were evaluated only for the Flint-1 scene. Figure 3-10 shows a plot of the two-dimensional spectrum for the 9.3-11.7  $\mu$ m channel. The units of power density for the two-dimensional Wiener spectrum are (K) $^2$ /(cycle per meter) $^2$ . As for the one-dimensional spectra, the two-dimensional spectra were evaluated using 512 data points in each of the dimensions. The utility of the two-dimensional Wiener spectra to the system designer has not been firmly established so that only limited two-dimensional Wiener spectra processing has been performed to date.

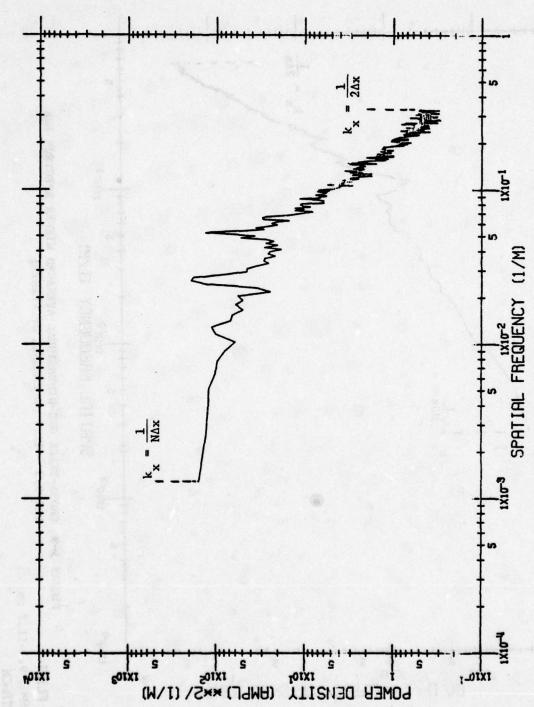
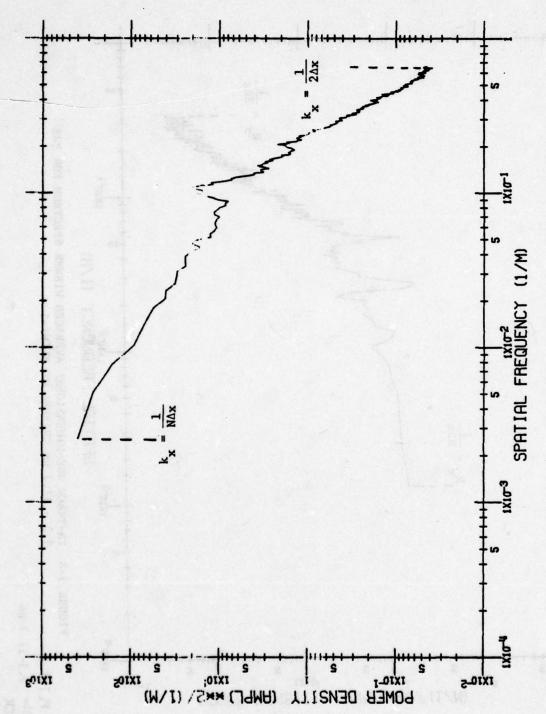


FIGURE 3-8 IN-TRACK ONE-DIMENSIONAL AVERAGED WIENER SPECTRUM FOR THE 9.3 - 11.7 µm CHANNEL OF FLINT-1 AREA: FLINT 1 LAMBOR= 9.3-11.7 µm. INTRACK

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CROSS-TRACK ONE-DIMENSIONAL AVERAGED WIENER SPECTRUM FOR THE 9.3 - 11.7 pm CHANNEL OF FLINT-1 FIGURE 3-9 AREA: FLINT 1

LAMBOR= 9.3-11.7 µm CROSSTRACK

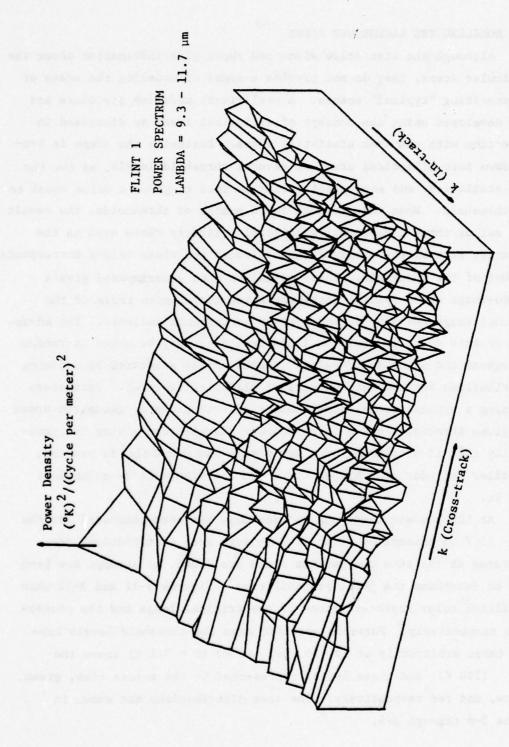


FIGURE 3-10 TWO-DIMENSIONAL WIENER SPECTRUM FOR THE 9.3 - 11.7 µm CHANNEL OF FLINT-1

## 3.3 MODELING THE BACKGROUND SCENE

Although the statistics discussed above give information about the particular scene, they do not provide a means of modeling the scene or of generating "typical" scenes. A preliminary modeling procedure has been developed using the concept of elliptical areas as discussed in connection with the area statistics above. Basically the scene is broken down into elliptical areas at several threshold levels, as for the area statistics, and each pixel within an area is given a value equal to the threshold. When this is done for a number of thresholds, the result is a set of three-dimensional elliptical cylinders whose area is the geometric area of the original scene element and whose height corresponds to that of the threshold. These cylinders when superimposed give a pseudo-image whose spatial characteristics approximate those of the original image for many sensor systems performance analyses. The advantage of this scene is that the individual areas may be moved at random throughout the scene and "typical" scenes may be generated by defining distributions for the various sets of elliptical volumes. Parameters defining a typical scene could then be distributions of geometric areas for given thresholds and a joint density distribution giving the probability that if a cylinder of a given size and threshold is present, a smaller cylinder of a higher threshold and size will be coincident with it.

At the present time, one pseudo-image has been generated for the 9.3 - 11.7  $\mu m$  channel of Flint-1. Although area distributions are generated at the time the various areas are found, no attempt has been made to determine the joint probabilities. Figures 3-11 and 3-12 show artificial color representations of the original image and the psuedo-image respectively. For this specific case the threshold levels have been taken arbitrarily at  $1\sigma$ ,  $2\sigma$ ,  $3\sigma$ , and  $4\sigma$  ( $\sigma$  = 3.1 K) above the mean (294 K) and these levels represented by the colors blue, green, yellow, and red respectively. The area distributions are shown in Tables 3-6 through 3-9.



Blue =  $29\frac{4}{9} - 304^{\circ}$ K Yellow =  $30\frac{4}{9} - 307^{\circ}$ K Green =  $301 - 304^{\circ}$ K Red =  $307 - 310^{\circ}$ K Brown =  $<296^{\circ}$ K

FIGURE 3-12. ARTIFICIAL COLOR REPRESENTATION OF THE PSEUDO-IMAGE GENERATED FROM THE 9.3 - 11.7 μm CHANNEL OF FLINT-1.

FIGURE 3-11. ARTIFICIAL COLOR IMAGE OF THE 9.3 - 11.7 μm CHANNEL OF FLINT-1.

TABLE 3-6

AREA DISTRIBUTIONS FOR RECOGNIZED REGIONS IN THE REAL AND PSEUDO-IMAGES OF THE 9.3-11.7  $_{\mu m}$  CHANNEL OF FLINT-1.

# THRESHOLD LEVEL = $1 \sigma$

SQUARE	METERS	FREQUENCY
0.0 TO	100.0	2047
100.0 TO	200.0	78
200.0 TO	500.0	26
500.0 TO	1000.0	8
1000.0 TO	1500.0	2
1500.0 TO	2000.0	0
2000.0 TO	2500.0	0
2500.0 TO	3000.0	0
3000.0 TO	4000.0	1
4000.0 TO	5000.0	0
5000.0 TO	6000.0	0
6000.0 TO	8000.0	1
8000.0 TO	10000.0	0
10000.0 TO	15000.0	0
15000.0 TO	20000.0	0
20000.0 TO	40000.0	0
40000.0 TO	80000.0	0
80000.0 TO	160000.0	0
OVER	160000.0	0

TOTAL NUMBER OF REGIONS = 2163

TABLE 3-7

AREA DISTRIBUTIONS FOR RECOGNIZED REGIONS IN THE REAL AND PSEUDO-IMAGES OF THE 9.3-11.7  $\mu m$  CHANNELS OF FLINT-1.

# THRESHOLD LEVEL = $2 \sigma$ .

SQUA	RE	METERS	F	REQUENCY
0.0	то	100.0		1110
100.0	то	200.0		10
200.0	то	500.0		4
500.0	то	1000.0		2
1000.0	то	1500.0		0
1500.0	то	2000.0		0
2000.0	то	2500.0		0
2500.0	то	3000.0		0
3000.0	то	4000.0		0
4000.0	TO	5000.0		0
5000.0	то	6000.0		1
6000.0	TO	8000.0		0
8000.0	то	10000.0		0
10000.0	TO	15000.0		0
15000.0	то	20000.0		0
20000.0	TO	40000.0		0
40000.0	то	80000.0		0
80000.0	TO	160000.0		0
ov	ER	160000.0		0
TOTAL NUMBE	R	F REGIONS	-	1127

TABLE 3-8

AREA DISTRIBUTIONS FOR RECOGNIZED REGIONS IN THE REAL AND PSEUDO-IMAGES OF THE 9.3-11.7  $\mu m$  CHANNEL OF FLINT-1. THRESHOLD LEVEL = 3  $\sigma_{\star}$ 

SQUARE	METERS	FRE	QUENCY
0.0 TO	100.0		97
100.0 TO	200.0		1
200.0 TO	500.0		2
500.0 TO	1000.0		1
1000.0 TO	1500.0		0
1500.0 TO	2000.0		0
2000.0 TO	2500.0		0
2500.0 TO	3000.0		0
3000.0 TO	4000.0		1
4000.0 TO	5000.0		0
5000.0 TO	6000.0		0
6000.0 TO	8000.0		0
8000.0 TO	10000.0		0
10000.0 TO	15000.0		0
15000.0 TO	20000.0		0
20000.0 TO	40000.0		0
40000.0 TO	80000.0		0
80000.0 TO	160000.0		0
OVER	160000.0		0
TOTAL NUMBER O	F REGIONS	-	102

SQUARE	METERS	FREQ	UENCY
0.0 TO	100.0		6
100.0 TO	200.0		1 000
200.0 TO	500.0		0
500.0 TO	1000.0		1
1000.0 TO	1500.0		0
1500.0 TO	2000.0		1
2000.0 TO	2500.0		0
2500.0 TO	3000.0		0
3000.0 TO	4000.0		0
4000.0 TO	5000.0		0
5000.0 TO	6000.0	10	0
6000.0 TO	8000.0		0
8000.0 TO	10000.0		0
10000.0 TO	15000.0	-	0
15000.0 TC	20000.0		0
20000.0 TO	40000.0		0
40000.0 TO	80000.0		0
80000.0 TO	160000.0		0
OVER	160000.0		0
TOTAL NUMBER (	OF REGIONS	-	9

### DISCUSSION OF RESULTS

The complete summary of statistical measures for the chosen background scenes are included as Appendix II of this report. Means, standard deviations, and spectral correlation coefficients are tabulated, and histograms for sub-areas of the scene as well as for the total scene are presented.

Some of the more obvious features follow expected patterns. For example, the mean values of radiances in the reflective near IR channels vary widely, due in part to the different background reflectivities in the different areas and in part to variation in solar elevation angles at the time the data were collected (giving some large shadowed areas). The Mill Creek data were collected early in the morning and the radiance levels are low and shadows clearly evident. The standard deviations are proportionately larger for this scene because of these shadows. In the thermal channel, 9.3-11.7 µm, the standard deviation about the mean temperature is smaller in the Mill Creek data than in other scenes as is expected early in the morning. The spectral correlation coefficients between pairs of near IR channel data are high in the Mill Creek data and low in the Baltimore data. This is indicative of a wide variety of materials in the Baltimore scene, some with reflectivities that increase and others that decrease with wavelength, and of the large shadowed areas and/or the predominance of materials in the Mill Creek scene that have the same relative spectral reflectance characteristics. The spectral correlations between the reflective and thermal IR channels are low as expected. A summary of these total area statistics is shown in Table 4-1.

The histogram data reveal the very non-Gaussian characteristics of most of the terrain backgrounds data. Especially notable is the wide distribution of the Mill Creek data with its large areas of shadow. Histograms derived from the multispectral scanner data of Mill Creek should vary dramatically during the diurnal cycle because of the topography

TABLE 4-1. TOTAL AREA DATA SUPPLARY

Mean istandard deviation for reflective IR channels in  $\mu\nu/cm^2 \cdot sr \cdot \mu m$  and in Kelvin for the thermal IR channel.

	μw/cm²·sr·μm and	μw/cm²·sr·μm and in Kelvin for the thermal IR channel.	thermal IR channel.	
	FLINT-1	FL INT-2	BALTIMORE	MILL CREEK
	1132 AM, Sept 18 Residential	1155, Sept 18 Industrial	1137, May 11 Residential	0733, June 30 Mountains
Spectral Band				
1.0- 1.4 иш	1273 ± 364	790 ± 305	2133 ± 778	· 112 ± 62
1.5- 1.8 µm	173 ± 83	240 ± 78		36 ± 20
2.0- 2.6 рт	36 ± 10	39 ± 14	78 ± 44	4.2 ± 2.9
9.3-11.7 им	294 ± 3.1	297 ± 3.2	299 ± 5.9	298 ± .97
Spectral Correlations	Control of the contro			
1.0-1.4, 1.5-1.8	0.392	0.718		0.835
1.0-1.4, 2.0-2.6	0.303	0.489	0.084	0.869
1.0-1.4, 9.3-11.7	7 -0.455	-0.437	nan Bar Sis	0.052
1.5-1.8, 2.0-2.6	0.603	0.634		0.880
1.5-1.8, 9.3-11.7	7 0.048	-0.180		0.256
2.0-2.6, 9.3-11.7	7 0.177	-0.036		0.245

TABLE 4-1. TOTAL AREA DATA SUMMARY (Continued)

PISGAH CKATER MONO LAKE

BLACK HILLS-2

BLACK HILLS-1

	1340, July 22 Forested Mountains	1340, July 22 Forested Mountains	0822, Oct 30 Mountains	0822, Oct 30 0952, Sept 23
Spectral Band	72.			10 20 21 21
1.0- 1.4 µm	1799 ± 618	1603 ± 464		2053 ± 334
1.5- 1.8 µm		447 ± 155	1	
2.0- 2.6 нт	106 ± 55	91 ± 39		95 ± 17
4.5- 5.5 µm	295 ± 2.3		1	286 ± 1.3
8.0-13.5 µm	294 ± 2.4	(5)	1	289 ± 1.6
11.3-13.5 µш			290 ± 2.9	
8.0-10.9 µш			289 ± 2.5*	
9.4-12.1 µm			289 ± 2.5*	
Spectral Correlations				
1.0-1.4, 1.5-1.8		0.743		
1.0-1.4, 2.0-2.6	0.505	0,518	i i	0.892
1.5-1.8, 2.0-2.6		0.908		
1.0-1.4, 4.5-5.5	-0.166		1	0.833
2.0-2.6, 4.5-5.5	0.498			0.814
8.0-10.9, 9.4-12.1	7 m 1 m 2 m 2 m 2 m 2 m 2 m 2 m 2 m 2 m 2		0.811*	

<sup>\*</sup>Sub-area 2 data only

and this factor must be accounted for when using these backgrounds data for sensor performance estimates under conditions other than those for which the data were collected. The histograms for the various sub-areas of the Baltimore and Mill Creek scenes show the largest inhomogeniety of the background scenes analyzed.

The one-dimensional power spectra for the 1.0-1.4 and 9.3-11.7 µm data of Flint-1 and Mill Creek do not show any particularly unique or distinguishing characteristics, nor do the two-dimensional power spectra for the Flint-1 data. However, there are very pronounced differences in the spatial characteristics of these background scenes which may be important to the performance of a sensor in detecting or tracking a target against these backgrounds. The area/intensity statistics, that is the occurrence of equivalent elliptical areas representing contiguous regions of the background above a threshold, for Flint-1 and Mill Creek are quite distinctive. Especially noticeable in the thermal infrared are the warm roofs of houses, many of which exceed two standard deviations above the mean.

The area/intensity statistics do preserve many of the characteristics of background scenes that may cause false alarms in many sensor systems. The equivalent elliptical areas above each threshold setting,  $1\sigma$ ,  $2\sigma$ ,  $3\sigma$ , and  $4\sigma$  above the mean, can in most instances be identified with the specific spatial features they represent in the original image. A simulation of the actual scene with these equivalent elliptical areas was shown in Section 3. The utility of the area/intensity statistics will depend on whether or not the simulated scene adequately represents the actual scene for sensor performance estimates, and whether or not sensor performances depends specifically on the placement of these equivalent ellipses within the scene. This subject will be the basis for future terrain background statistical analyses.

## SUMMARY AND RECOMMENDATIONS

Several terrain backgrounds were selected and statistics were derived for these backgrounds from calibrated multispectral scanner data. Conventional statistical parameters - means, standard deviations, histograms, spectral correlations, and power spectra - are reported. In addition a program has been initiated for developing statistical parameters of terrain backgrounds particularly relevant to the sensor designer's problem of detecting and tracking targets with low probability of false alarm or false track. These statistical parameters are the equivalent elliptical area/intensity statistics that have been reported.

It is intuitively obvious that these area/intensity statistics are approximations of what sensor system designers need to estimate systems performance characteristics. It is now necessary 1) to demonstrate that these statistics are adequate, i.e. that the performance of sensors against the actual background and against the simulated background is essentially the same and that the salient spatial features of the background have been preserved, and 2) to demonstrate that terrain backgrounds can be classified in some way, e.g. residential, industrial, mountainous, etc., so that the statistics can be inferred without recourse to actual measurement. Future backgrounds efforts should be directed to demonstrating the utility of the area/intensity statistics for terrain backgrounds and to expanding these efforts to include sky and cloud backgrounds.

# APPENDIX I

DETAILS OF CALIBRATION AND FIELD-OF-VIEW
AVERAGING PROCEDURES

#### APPENDIX I

# DETAILS OF CALIBRATION AND FIELD-OF-VIEW EQUALIZATION PROCEDURES

### CALIBRATION OF SCANNER DATA

As discussed in Section 3.1, output from the ERIM scanners is in the form of digital tapes in which the data values are represented by integers ranging in value from 0 to 255. At the end of each scan line a set of calibration sources is scanned and the integers observed for these sources are used to calibrate the data in apparent radiance or temperature. The resulting calibrated tape also represents the data as integers but these integers are adjusted so that they are linear in radiance or temperature and a set of multiplicative and additive factors are used to convert these integer values to the appropriate units.

The calibration sources scanned once per scan line are: controllable temperature "hot" and "cold" plates; an ambient temperature plate; a visible-near-IR lamp; an ultraviolet lamp; and a sun sensor. The visible-reflective IR channels (approximately 0.4  $\mu$ m to 3.0  $\mu$ m) are generally calibrated in radiance using the visible-near-IR lamp as a radiance standard and the "ambient" plate as a dark level reference. If a linear relationship is assumed between radiance and detector output, the apparent radiance of the target (the radiance observed at the scanner aperture) is given by

$$L_{T}^{a} = \left(\frac{V_{T} - V_{A}}{V_{\ell} - V_{A}}\right) (L_{\ell} - L_{A}) + L_{A}$$
 (I-1)

where

 $\mathbf{V}_{\mathbf{T}}$  = The integer value observed for the target

VA = The integer value observed for the ambient plate

 $V_{\ell}$  = The integer value observed for the lamp

 $L_{\ell}$  = The radiance of the lamp at the center of the bandpass of the channel to be calibrated

LA = The ambient radiance at the center of the bandpass of the channel to be calibrated

and  $\boldsymbol{L}_{T}^{a}$  is the apparent radiance of the target which is related to the actual target radiance  $\boldsymbol{L}_{T}$  as

$$L_{T}^{a} = L_{T}^{T}_{p} + L_{p}$$
 (I-2)

where  $\tau_p$  is transmission of the intervening path and  $L_p$  the radiance of this path.

The lamp radiance  $L_2$  in Equation I-1 is obtained from a calibration of the visible-near-IR lamp using an NBS standard lamp while the ambient radiance  $L_A$  is taken as the radiance of the ambient temperature plate with emissivity  $\epsilon_A$  given by

$$L_{A} = \varepsilon_{A} L_{A}^{BB} + (1 - \varepsilon_{A}) L_{A}^{BB}$$
 (I-3)

where the first term is the plate emittance and the second term the surrounding radiance reflected from this plate. Since the ambient temperature plate and its surroundings are at the same temperature, this equation simply gives  $L_{\stackrel{}{A}}$  equal to  $L_{\stackrel{}{A}}^{BB}$  or the radiance of a black-body at ambient temperature.

Equation I-1 is then written in terms of a "mult" and an "add" factor as

$$L_{T}^{a} = V_{T} \cdot MULT + ADD \qquad (I-4)$$

where

$$\begin{array}{ll} \text{MULT} = \text{W} \\ \text{ADD} & = \text{L}_{\text{A}}^{\text{BB}} - \text{WV}_{\text{A}} \end{array}$$

and

$$W = (L_{\ell} - L_{A}^{BB})/(V_{\ell} - V_{A})$$
 (I-5)

The computer program used for calibration initially averages the integer values (bin values) of the calibration sources for all scan lines in the image and outputs a mean and a standard deviation for them. If the standard deviations are small compared to the mean values the program allows for an "average" calibration in which the mean bin values of V and  $V_A$  are used in Equations I-4 and I-5. In this case the integer data values on the calibrated tape are the same as those in the original tape; only "mult" and "add" factors are evaluated by the calibration procedure. However, if the standard deviations are not small compared to the means, indicating a drift in the system, a "line-by-line" calibration is required. For this type of calibration values of  $V_{\rho}$  and  $V_{\Lambda}$ are taken from the calibration sources at the end of each scan line and these values used to determine "mult" and "add" factors from Equation I-5. These factors are then used to modify the integer data values of a given scan line so that only one "mult" and "add" factor is required for the total image. The single "mult" and "add" factors used are those determined from the mean  $V_{\ell}$ ,  $V_{\Lambda}$  values and the modified integer data value is taken as

$$V_{T} = \frac{V_{T} \cdot MULT + ADD - \overline{ADD}}{\overline{MULT}}$$
 (I-6)

where the average factors are  $\overline{\text{MULT}}$  and  $\overline{\text{ADD}}$ , those determined for each line are MULT and ADD, and  $V_{_{\rm T}}$  is the modified integer data value.

The long wavelength IR channels ( $\lambda > 3.0~\mu m$ ) are calibrated in temperature and require a somewhat more involved calibration procedure. Since the detector output is proportional to radiance and not temperature, the first step in the process is to relate bin value (integer data value) to radiance, as in the reflective IR channels, using the "cold" plate as a dark level reference, the "hot" plate as a radiance standard, and the "ambient" plate to correct for ambient radiation levels. If a linear relationship is again assumed between detector output and radiance the apparent target radiance is given by an equation identical to I-1 except that the ambient radiance ( $L_A$ ) and bin value ( $V_A$ ) are replaced

by those for the "cold" plate ( $L_C$ ,  $V_C$ ) and the lamp radiance ( $L_\ell$ ) and bin value ( $V_\ell$ ) are replaced by those for the "hot" plate ( $L_H$ ,  $V_H$ ):

$$L_{T}^{a} = L_{C} + \left(\frac{v_{T} - v_{C}}{v_{H} - v_{C}}\right) (L_{H} - L_{C})$$
 (1-7)

In this case however the "hot" plate radiance is given by

$$L_{H} = \epsilon_{H} L_{H}^{BB} + (1 - \epsilon_{H}) L_{A}^{BB}$$
 (I-8)

where  $\epsilon_{H}$  is the emissivity of the "hot" plate,  $L_{H}^{BB}$  the radiance of a blackbody at the same temperature as the "hot" plate, and  $L_{A}^{BB}$  the ambient blackbody radiance. Similarly, the "cold" plate radiance is given by

$$L_{C} = \varepsilon_{C} L_{C}^{BB} + (1 - \varepsilon_{C}) L_{A}^{BB}$$
 (I-9)

In both of these expressions the first term is the radiance emitted by the plate while the second term is the ambient radiance reflected by the plate.

Substitution of Equations I-8 and I-9 into I-7 and taking the plate emissivities equal gives

$$L_{T}^{a} = \left[ \varepsilon L_{C}^{BB} + (1 - \varepsilon) L_{A}^{BB} \right] + \left( \frac{V_{S} - V_{C}}{V_{H} - V_{C}} \right) \left[ \varepsilon (L_{H}^{BB} - L_{C}^{BB}) \right]$$
 (I-10)

This equation could be used for calibration but the ambient radiance  $\mathsf{L}_{A}^{BB}$  would have to be calculated from ambient temperature measurements. This may be avoided by again assuming linearity of the detectors and taking

$$L_A^{BB} = L_C + \left(\frac{v_A - v_C}{v_H - v_C}\right) (L_H - L_C)$$
 (I-11)

as for  $L_{\rm T}^{\rm a}$  in Equation I-7. Substituting Equations I-8 and I-9 into this expression it is found that many of the terms cancel and the ambient

radiance is given by

$$L_A^{BB} = L_C^{BB} + \left(\frac{V_A - V_C}{V_H - V_C}\right) (L_H^{BB} - L_C^{BB})$$
 (I-12)

where all radiances are now blackbody radiances evaluated at the plate temperatures. Making a final substitution of Equation I-12 into Equation I-10 and rearranging terms gives

$$L_{T}^{a} = L_{C}^{BB} + W [(1 - \varepsilon)V_{A} - V_{C}] + \varepsilon WV_{T}$$
 (I-13)

where

$$W = \left(\frac{L_{H}^{BB} - L_{C}^{BB}}{V_{H} - V_{C}}\right) \tag{I-14}$$

Equation I-13 then relates the data bin values  $(V_T)$  to radiance and a second transformation is required to convert these values to temperature.

The computations required to convert radiance to temperature have been minimized by noting that the radiance values are bounded; the minimum value being given by  $V_T=0$  and the maximum by  $V_T=255$ . Using this fact a table of temperature versus radiance is constructed, as shown in Table I-1, by integrating the Planck function over the bandpass of the channel to be calibrated choosing a range of temperatures sufficient to cover the entire radiance range. The temperature increments in this table are taken small enough ( $\sim 1^{\circ}$ C) so that interpolation may be used to form an array of temperature versus data bin value  $T(V_T)$  for all possible bin values. It is this array which is then used to directly convert the uncalibrated data values to temperature.

Unlike the radiance data, the integer values appearing in the calibrated images for the thermal channels are never the same as those of the original image since the calibrated values are now proportional to temperature not radiance. This new set of integer data values is scaled from 0 to 255 using

TABLE I-la. TABLE OF BLACKBODY RADIANCE VS TEMPERATURE IN THE 4.5 - 5.5 µm BAND

TEMPEDA LUNE	PARTANCE	TEMPEDATURE	SANTANCE	TEMPFRATURE	RADIANCE
(NE K)	(MY) CH / (STR)	(DEG K)	(AW/CH2/51R)	(DEG K)	(MW/CM2/STR)
245.	3,15526101	272.	9.9325[10]	299.	2.5496F+02
246.	3.306.75+41	273.	1.03105102	300.	2.631AF+02
247.	3.46A1F101	274	1.67141 102	301.	2.7160F+02
248	3.5277F+01	275	1.11206 102	302.	2.80235.102
240.	3.79768+01	276.	1,15531,02	303.	2.890RF+02
250	3.97418+01	277.	1.1989[+02	304.	2.9A15E+02
251.	4.15726+01	27A.	1.7430F+02	305	3.0744F+92
252	4.3473F+01	279.	1.2903L+02	306.	3.1696F+02
253	4.5.485F + 0.1	- nac	1.5380[ +62	307.	3.26715402
1/20	101 10071 1	) lac	1.38721 +02	308.	5.367nF+02
24.5	0.9610F101	202.	1.43751.402	509.	3.46925+62
26.6.	5.1P03F101	243.	1,449HF.102	310.	3.5739F + 112
257.	5.00055+01	284.	1.54341.402	311.	3.68165+02
26.8.	S.c.anneini	285	1.5985E102	312.	3.790KE +17
580	5. RAMGF +01	246.	1.85521.02	313.	5.94.2HF112
266.	6.1414F tn1	247.	1.71356+02	314.	4.0175F+02
201.		2 k R .	1.77341.462	315.	4.1390E102
20%	6.673AF 101	203	1.83491.402	316.	4.25456 102
265.		2011.	1.609.21.102	317.	4.37775+12
264	7.24335+01	201.	1.06321.402	319.	4.50328+02
20.5.	7.44261.401	202	2.03001 102	219.	1.63197102
266.	7.95205+01	293.	2,6985[+62	320.	4.76255+02
207.	R.1716F101	2011	2.16891+02	321.	4.89665102
268.	3/10'.º	295.	2.24126402	322.	5.13355+112
200.	9. 44,26F + 01	206.	2.315AE+02	323.	5.17345+02
270.	9.10455 +41	707.	2,39156+02	324.	5.3162F+02
271.	9 6,6,775 +01	20.8	2.46967 +02	125	5 46215405

TABLE I-1b. TABLE OF BLACKBODY RADIANCE VS TEMPERATURE IN THE 9.3 - 11.7 µm BAND

TEMPERATURE	RADIANCE	TEMPFRATURE	PADIAMEF	1FPPERATURE	PADTANCE
(DEG K)	(MW/C" 2/STR)	(DFG K)	(MW/CM2/STR)	(DEG K)	(pu/CH2/3TP)
245.	8.2466F+02	272.	1.4466E+03	.005	2.29375+03
246.	A. 45,78F+02	273.	1.47386+03	300.	2.329AF+03
247.	8.6518F+02	274.	1.50135+03	301.	2.3658F+03
248.	R. RURTE+02	275.	1.5292E+03	505	2.4023F+05
549.	9.04A4F+02	276.	1.557/16+03	303.	2.4392F+63
250.	150	.777.	1.5A59E+03	304.	2.4764F+05
251.	9.4567F+n2	278.	1.6147E+03	305.	2.5130F+03
252.	9.66525+02	279.	.643AE+03	306.	2,55175+03
253.	9.8766F+02	280.	1.67335.+03	307.	2.58995103
254.	1.0091F+03	281.	1.7030E+03	308.	2.6284F+03
255.	1.0308F+03	2A2.	1.73316+03	309.	2.6472F+03
256.	1.0529F+03	283.	1.76356+03	310.	2.7064F+03
257.	1. "752F+n3	284.	1.7942E+03	311.	2,7459F+03
258.	1.0978F+03	285.	1.82530+03	\$12.	2.1857F+43
259.	1.12075+03	286.	1.85665+03	313.	2.825KE+03
260.	1.1440F+03	287.	1.3883[+03	314.	2. R66 5F+03
261.	1.1675F+03	28A.	1.9203E+03	315.	2.9070F+03
262.	1.1913F+03	289.	1.95266+03	316.	2.94825+03
263.	1.2155F+03	290.	1.9853E+03	31.7.	2.9846F+03
564.	1.2399E+03	291.	2.01825+03	318.	3.0314F+03
265.	1.2647F+03	292.	2.05151+03	319.	3.0734E+05
266.	1.2897E+03	293.	2.0852E+03	320.	3.11505+04
267.	1.3151F+n3	2941.	2,1191[+03	\$71.	3.15A6F+03
268.	1.3408F+03	295.	2.1534L+03	322.	3.2017F+05
269.	1.36675+0.3	296.	2.18795+03	323.	3.2450E+03
270	1.3930F+03	297.	2.2729E+03	3.74.	S. PRARE+03
271.	1.41965+03	298.	2.25815+03	325.	3.332AF+13

TABLE I-1c. TABLE OF BLACKBODY RADIANCE VS TEMPERATURE IN THE 8.0-13.5 µm BAND

TEMPEPATURE	PANTANCF	TEMPFRA TURE	RADIAUCE	TEMPERATURE	RADIANCE
(DFG K)	(M4/CH2/STP)	(DFG K)	(AN/CM1/STR)	(DEG K)	(JW/CMZ/STR
245.	1.9275F+03	272.	3,1775[+03	200.	5.0315E+03
246.	1.96915103	273.		300.	5.1103F+03
247.	1.91135+03	2711.		301.	5.1A99E+03
248.	1,05416+03	275	_	302.	5.27025.103
249.		276.	3.41946+03	303.	5.3512F+03
25.0	2.0416F+03	277.		304.	5.4330E+03
251.		. 27A.	3.54456+03	305.	5.5155F+03
262	2.1317F+03	279		306.	5.5987F+03
253.	2.17775 1113	ZAU.		307.	5.68275+03
254.	2.2244F+03	281.		308.	5.7675€+03
255	2.2717F+113	282.		309.	5. A524E+03
25.6.	2.3196F+03	243		310.	5.93916103
257	2.36A7F+03	284.	7.934.91.103	311.	6.02615+03
25k.	2.41755+63	247.	4.004FL+03	312.	6.113RF+03
250	2.46746746	296.		313.	6.20238+03
260.	2.5179F+03	287.		314.	6.29155103
Zul.	2.1402F+03	2AR.	4,21285,103	315.	6.38141.03
20.2.	2.67115103	249.		316.	6.47215+03
203.	2.6757F+n3	200.		317.	6.56368+03
264.	2.7269F+03	291.		-	
265.	2. /HOUF +03	292.		319.	6.74875103
206.		203.	4.5740[+03	320.	6.8424E+03
207.	2. A90 HF + 0.3	2911.	4.6HRAE+03	321.	6.936RE+03
20, R.	2.9467F+03	295.		322.	7.0320F+03
200.	3.00345103	962	.7995E	373.	7.1279F+03
270.	3.0607F+03	297.	4.8761E+03	324.	7.2246E+03
271.	3-11885+03	294.	4.9534(+03	325.	7.32205+03

$$N = \frac{T(V_T) - T(0)}{T(255) - T(0)} 255$$
 (I-15)

where T is the temperature versus bin value array with  $T(V_T)$  equal to the temperature corresponding to bin value  $V_T$ . The "mult" and "add" factors for the thermal channels are then taken as

$$MULT = \frac{T(255) - T(0)}{255}$$

$$ADD = T(0)$$
(I-16)

The calibration program allows for "average" or "line-by-line" calibration of the thermal channels as it did for the reflective IR channels. Because of the amount of computation required to set up the temperature versus bin value array, only one such array is generated using the scene average values of  $V_C$ ,  $V_A$ , and  $V_H$  in Equation I-13. If an "average" calibration is used this array directly relates data bin values ( $V_T$ ) to temperature and Equation I-15 is used directly. However, if a "line-by-line" calibration is required the data bin values must be modified so that I-13, using scene average values of  $V_C$ ,  $V_A$ , and  $V_H$ , gives the correct radiance. The modification of the data bin values is done in the same way as for the reflective IR channels using Equation I-6. In this case the "mult" factors are given by  $\varepsilon W$  or  $\varepsilon \overline{W}$  and the "add" factors by the first two terms of Equation I-13 or

ADD = 
$$L_C^{BB} + W [(1 - \varepsilon) V_A - V_C]$$

$$\overline{ADD} = L_C^{BB} + \overline{W} [(1 - \varepsilon) \overline{V_A} - \overline{V_C}]$$

To avoid round-off errors the values determined from I-6 are not rounded to the nearest integer but taken as floating point numbers and interpolation in the  $T(V_T)$  array is used to determine the temperature. This temperature is then used in place of  $T(V_T)$  in Equation I-15 to evaluate the calibrated integer value.

In a typical data set both thermal and reflective IR channels are present so that both of the above procedures are used in generating a calibrated image tape.

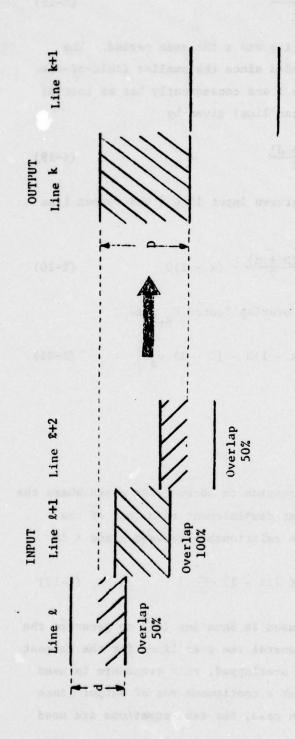
CORRECTIONS FOR OVERLAP AND UNEQUAL FIELDS-OF-VIEW

Since the detectors used in the various channels (wavelength regions) vary in size and consequently in instantaneous field-of-view, direct comparisons of the channels is not possible unless the fields-of-view are normalized in some fashion. A second, although less critical, problem is that depending on the aircraft altitude, scan lines and/or pixels may be highly overlapped resulting in oversampling of the scene. Both of these problems were corrected at the time the data was calibrated by averaging the scan lines (and/or pixels) of the smaller field-of-view channels and generating an equivalent scan line (and/or pixel) with a field-of-view equal to the largest field-of-view. This procedure must be carried out separately for scan lines and pixels within a scan line since the fields-of-view and the data taking rates are different in these two dimensions. In the following discussion only scan line averaging will be discussed since pixel averaging is completely analogous.

As outlined in Section 3.1, the averaging procedure consists of setting up a set of contiguous output lines with a field-of-view equal to the largest field-of-view (D) and then combining the smaller field-of-view (d) scan lines to generate equivalent lines with fields-of-view D. As shown in Figure I-1, the combining of scan lines is accomplished using a weighted average given by

$$V_{k} = \frac{\sum_{\ell} F_{k,\ell} V_{\ell}}{\sum_{\ell} F_{k,\ell}}$$
(I-17)

where  $V_k$  is the  $k^{th}$  output line data value for a given pixel,  $V_\ell$  the  $\ell^{th}$  input line data value for the same pixel, and  $F_{k,\ell}$  the overlap between input line  $\ell$  and output line k. Since the overlap will be non-zero only for a small number of lines about the output line,  $F_{k,\ell}$  need only be calculated for a few values of  $\ell$ . A general expression for the overlap was determined by considering the displacements of the scan lines from the beginning of the scene. The displacement to the bottom of input scan line  $\ell$  is given by



Output Line k = {0.5 (Input Line k) + 1.0 (Input Line k+1) + 0.5 (Input Line k+2)}/2.0

FIGURE 1-1 SCHEMATIC REPRESENTATION OF THE PROCEDURES USED FOR SCAN LINE AVERAGING

$$(\ell - 1) v_a \tau + \frac{(D + d)}{2}$$
 (I-18)

where  $\mathbf{v}_{\mathbf{a}}$  is the aircraft ground velocity and  $\tau$  the scan period. The second term in this equation is included since the smaller field-of-view (d) is concentric with D in scan line 1 and consequently has an initial displacement (to the bottom of the scan line) given by

$$D - \frac{(D - d)}{2} = \frac{(D + d)}{2} \tag{I-19}$$

As shown in Figure I-2 the overlap between input line  $\ell$  and output line k is then given by

$$\gamma = (\ell - 1)v_a \tau + \frac{(D+d)}{2} - (k-1)D$$
 (I-20)

so that the percent overlap ( $\gamma/d$ ) or overlap factor  $F_{k,\ell}$  is

$$F_{k,\ell} = \frac{1}{2} [1 + \frac{D}{d}] - \frac{1}{d} \left| (k-1)D - (\ell-1) v_a^{\tau} \right|$$
 (I-21)

with the constraints

$$F_{k,\ell} \rightarrow 1 \text{ if } F_{k,\ell} \geq 1$$

$$F_{k,\ell} \rightarrow 0 \text{ if } F_{k,\ell} \leq 0$$

The absolute value appears in this equation to account for cases where the bottom of the input line has a greater displacement than that of the outrate line. It may be seen that the relationship between k and & is

$$(k-1)$$
 = Integer value of  $[(l-1)\frac{v_a\tau}{D}]$  (I-22)

These overlap factors are then used in Equation I-17 to generate the equivalent output lines. Since in general the scan lines for the largest field-of-view channel are themselves overlapped, this procedure is used to average these lines as well so that a contiguous set of output lines is obtained in all channels. In this case, the same equations are used but d is equal to D.

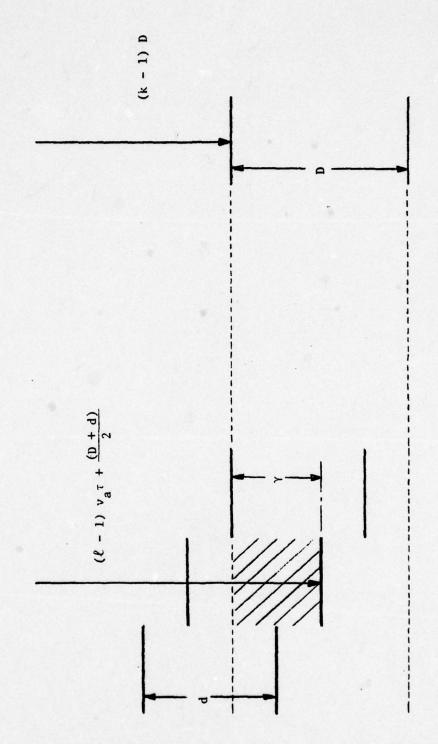


FIGURE 1-2 SCHEMATIC OF DISPLACEMENTS USED TO DERIVE THE OVERLAP FACTORS Fk, L

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APPENDIX II

COMPLETE COMPILATION OF STATISTICAL DATA

## APPENDIX II

## COMPLETE COMPILATION OF STATISTICAL DATA

DISCUSSION OF FORMATS, SPECIFIC PROCEDURES, ANOMALIES AND LIMITATIONS

This appendix presents the statistics generated for all of the

This appendix presents the statistics generated for all of the chosen scenes. It is broken down into two major sections, the first of which presents the mean values, standard deviations, spectral correlations, and histograms for each of the scenes, while the second section presents the area/intensity statistics and Wiener spectra computed for Flint-l and Mill Creek. It is important to emphasize that the data presented here are only descriptive of the specific scenes for the specific conditions under which the imagery was collected and that generalizations to other background scenes, other background types or other conditions cannot be made without further data analysis and modeling. The primary purpose of this presentation is to familiarize the potential user of the data with what is and what can be made available to assist in systems analysis.

In the first section of this appendix, the statistics for each scene are preceded by (1) maps showing the regions covered, (2) linescan images for each of the wavelength bands generated from the scanner data, and (3) a visual image showing the subareas defined for statistics generation. The histograms for the subareas, total area, and calibration sources of each scene are presented in graphical form but tabulations of the data used to generate these plots are available at ERIM for quantitative analysis. Histograms of the calibration sources have been included for two reasons:

- (1) To indicate the range of possible data values so saturation problems may be identified, and
- (2) To indicate the distribution of calibration source values and hence the possible uncertainty associated with the radiance or temperature calibrations.

Histograms of the calibration sources are not presented for the 9.3-  $11.7 \mu m$  Baltimore data, the 1.0-1.4 and 2.0-2.6  $\mu m$  Black Hills-1 data,

and the 1.0-1.4 and 2.0-2.6 µm Mono Lake data. Only the position of the calibration signal used is shown. The Baltimore data were processed before the calibration histogram capability was developed, and the Black Hills-1 and Mono Lake calibration histograms are not shown because the calibration was inferred from other data as discussed later.

Each of the calibration source histograms is presented with dual abscissa units: the recorded integer data value (bin number) and the calibrated radiance or temperature. Since the data is collected as positive 8-bit integers, this data is constrained to the range 0 to 255 with negative data points being given the value zero and points with values greater than 255 being given the value 255. Consequently, if the wings of a given data distribution show the presence of scene elements with calibrated data values corresponding to a bin value of zero or 255, it must be assumed that these points are saturated and that the actual scene contained values outside the 0 - 255 range.

Cases where 255 saturation are in evidence are in the Flint-2 2.0-2.6 µm channel, the Mill Creek 1.5-1.8 and 2.0-2.6 µm channels, the Black Hills-1 2.0-2.6 µm channel, and the Black Hills-2 1.5-1.8 µm channel. Zero saturations were found in the Baltimore 9.3-11.7 µm channel.

The histograms of the calibration sources cannot be used to directly infer the influence of system noise on the distribution of scene data values. This is the case since in many instances the spread of calibration source values is due to a cyclical variation or a drift of the source throughout the scene which is corrected for using the line-by-line calibration procedures discussed in Section 3. No attempt has been made at the present time to determine the degree to which these line-by-line procedures completely removed these cyclical or drift variations during calibration.

A few comments regarding the data appearing in the first section of this appendix are in order:

(1) Each of the histograms for the subareas and total area are independently normalized by assigning a relative frequency of unity to the data value appearing most frequently in the scene. As a result, if 255 saturations occur and a large enough number of points have this value, the histogram may never reach unity except for the spike appearing at 255. This is in evidence in the histogram of the 2.0-2.6  $\mu$ m channel of Flint-2 data.

- (2) In addition to the digital saturations discussed earlier, some of the data histograms show an anomalously large number of data points at the high end of the distribution which are not digitally saturated. In the cases where this has been identified, it was found to be due to analog saturation in the aircraft recording system, and hence is not indicative of the true scene distribution. Cases where this has been observed are the Flint-1 9.3-11.7 μm channel around data value 308K, the Black Hills-1 4.5-5.5 μm channel near data value 307K, and the Black Hills-2 2.0-2.6 μm channel near data value 280 μw/cm<sup>2</sup>·sr·μm).
- (3) In the 9.3-11.7 μm channels of Flint-1, Flint-2, and Mill Creek, as well as the 11.3-13.5, 8.0-10.9, and 9.4-12.1 μm channels of Pisgah Crater, some spikes appear in the data histograms. These are the results of the analog-to-digital conversion process in which certain data values are digitized as the next higher or lower integer value. This digitization error is not important as it is an error in magnitude of only a few tenths degree Kelvin. These are not seen in the imagery since these data values appear randomly throughout the scene but they do appear in the histograms.

As discussed elsewhere in this report\*, the computer code developed for data calibration was equipped to do three different types of calibration:

<sup>\*</sup>See Section 3 and Appendix I.

- An average calibration in which the average bin values
  of the calibration sources for the whole scene are used;
- (2) A line-by-line dark level correction in which the dark level value of each scan line is used in conjunction with average values for the other calibration sources; and
- (3) A line-by-line calibration in which the bin values of all calibration sources taken from the individual scan lines are used.

In general, an average calibration was used when the calibration sources were reasonably constant throughout the scene so that their average bin values had small standard deviations, while a line-by-line procedure was used when the calibration sources showed cyclical variations or drifts. Of the two possible line-by-line procedures, a dark level correction (2) was used if only the dark level varied, while a complete line-by-line calibration (3) was used if any or all of the other calibration sources showed variation. However, in its present form, the computer code is constrained to use the same type of calibration on all channels calibrated in radiance and a separate type for all channels calibrated in temperature. Consequently, if any of the radiance (or temperature) channels required a line-by-line calibration, the remainder of the radiance (or temperature) channels had to be similarly calibrated.

To assist in determining the calibration procedure required for each scene, three types of data displays have been used:

- (1) Histograms of the calibration sources for the total scene to determine mean values and standard deviations (Figure II-1);
- (2) "A"-scope traces of several full scan lines to determine line-to-line variations and to see if variations in the video portion of the scan followed those in the calibration sources (Figure II-2); and,
- (3) Time history traces of the calibration sources to observe source drifts or cyclical variations (Figure II-3).

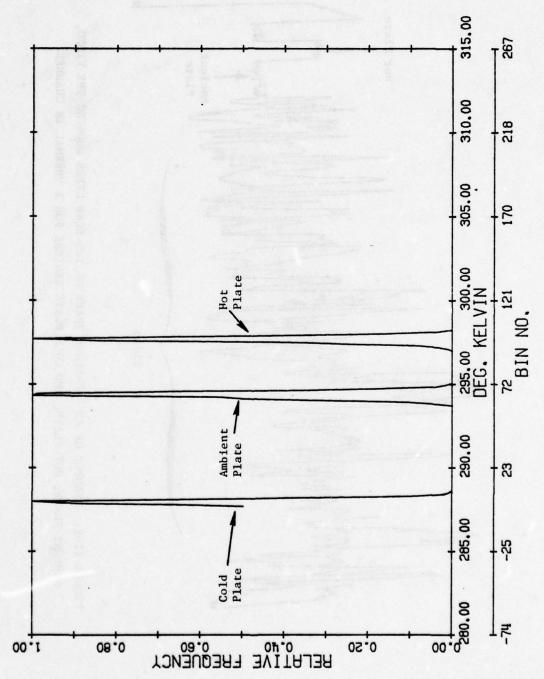


FIGURE II-1. EXAMPLE OF CALIBRATION SOURCE HISTOGRAMS FOR A THERMAL IR CHANNEL SHOWING THE COLD, AMBIENT, AND HOT PLATE DISTRIBUTIONS

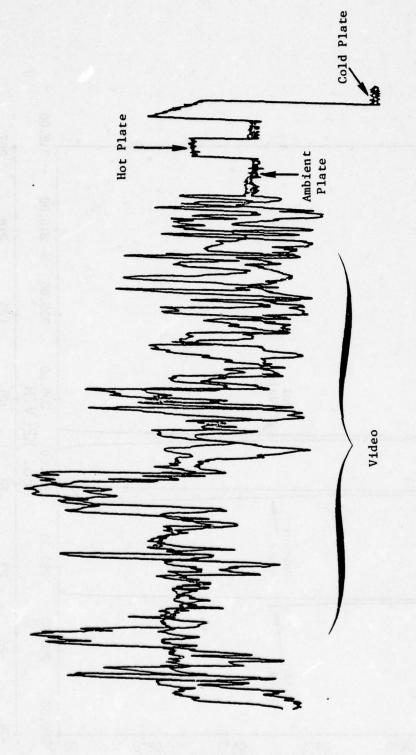


FIGURE 11-2. EXAMPLE OF AN "A"-SCOPE TRACE OF TWO SCAN LINES SHOWING THE VIDEO, AMBIENT PLATE, HOT PLATE, AND COLD PLATE REGIONS FOR A THERMAL IR CHANNEL.

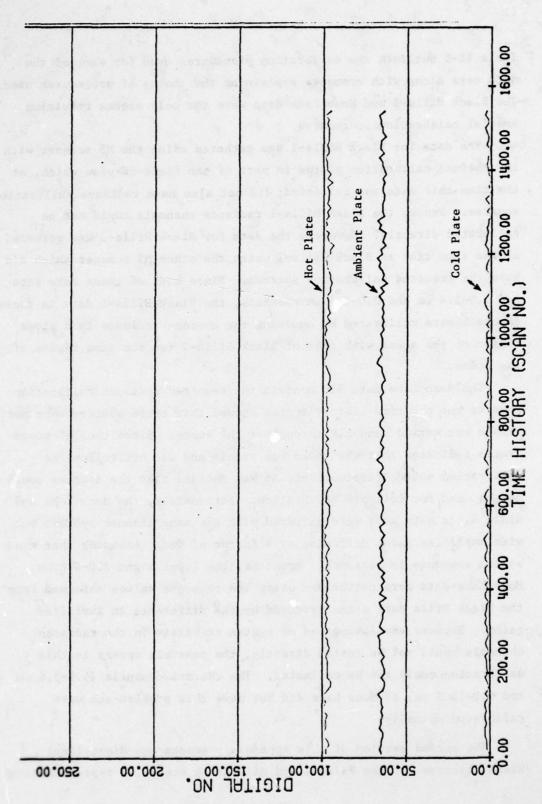


FIGURE 11-3. EXAMPLES OF TIME HISTORY TRACES OF THE COLD, AMBIENT, AND HOT PLATE DATA VALUES FOR A THERMAL IR CHANNEL

Table II-1 outlines the calibration procedures used for each of the data sets along with comments explaining the choice of procedures used. The Black Hills-1 and Mono Lake data were the only scenes requiring special calibration procedures.

The data for Black Hills-1 was gathered using the M5 scanner with the thermal calibration plates in part of the field-of-view which, at the time this data was collected, did not also have radiance calibration sources. Hence, the Black Hills-1 radiance channels could not be calibrated directly. However, the data for Black Hills-2 was gathered at the same time as Black Hills-1 using the other M5 scanner which did have the required calibration sources. Since both of these data sets had 1.0-1.4  $\mu m$  and 2.0-2.6  $\mu m$  channels, the Black Hills-1 data in these channels were calibrated by equating the average radiance in a given region of the scene with that of Black Hills-2 for the same region of the scene.

The Mono Lake data did contain the required radiance calibration sources but the time history traces showed that these sources were not stable but varied randomly throughout the scene. Since the "A"-scope traces indicated that the video was stable and did not follow the calibration source fluctuations, it was decided that the sources could not be used for reliable calibration. Fortunately, the Mono Lake and Black Hills data sets were gathered with the same scanner systems but with amplifier gains differing by a factor of two. Assuming that the system response is reasonably constant, the 1.0-1.4 and 2.0-2.6 µm Mono Lake data were calibrated using the response values obtained from the Black Hills data sets corrected by the difference in amplifier gains. Because the assumption of system stability in the radiance channels could not be tested directly, the possible errors in this calibration could not be estimated. The thermal channels (4.5-5.6 µm and 8.0-13.5 µm) of Mono Lake did not have this problem and were calibrated normally.

The second section of this appendix presents one-dimensional Wiener spectra for the Flint-1 and Mill Creek scenes, a representative

TABLE II-1. CALIBRATION PROCEDURES USED FOR THE VARIOUS BACKGROUND SCENES

Scene (Scanner)	Calibration Used Radiance Temper Channels Chan	ion Used Temperature Channels	Comments
Flint-1 (M7)	Line-by-line	Average	Line-by-line required because of cyclical variations in the 2.0-2.6 µm channel calibration sources.
Flint-2 (M7)	Line-by-line	Average	Line-by-line required because of cyclical variations in the 1.5-1.8 µm and 2.0-2.6 µm channel calibration sources.
Baltimore (M7)	Average	Average	Thermal 9.3 - 11.7 µm channel run separately, consequently not in registration with radiance channels.
Mill Creek (M7)	Average	Average	
Black Hills-2 (M5)	(See Text)	Line-by-line	No lamp present for calibration of radiance channels. These were calibrated using corresponding channels in Black Hills-2. Thermal channel calibration sources had cyclical variation requiring line-by-line calibration. The 8-13.5 µm channel is not spatially registered with the 1-1.4, 2-2.6, and 4.5-5.5 µm channels.
Black Hills-2 (M5)	Average		annow pu spilon
Pisgah Crater (M5)	ļ .	Average	No field-of-view averaging was used. The 11.3-13.5 µm channel is not spatially registered with the 8-10.9 and 9.4-12.1 µm.
Mono Lake (M5)	(See Text)	Average	Radiance channel calibration sources very noisy. Calibration done using Black Hills-2 data since both sets collected with same scanner and equipment. The 8-13.5 µm channel is not spatially registered with the 1-1.4, 2-2.6, and 4.5-5.5 µm channels.

two-dimensional Wiener spectrum for the 9.3-11.7  $\mu m$  band of Flint-1, and area/intensity statistics for the 1.0-1.4  $\mu m$  and 9.3-11.7  $\mu m$  bands of Flint-1 and Mill Creek.

Included with the one-dimensional Wiener spectra for Flint-1 are spectra of the dark level (ambient or cold calibration source) since these plots indicate that the feature at 0.5 cycles/meter is not a scene feature but a spatial frequency generated by the scanner itself. The area/intensity statistics are presented in two forms: plots of the equivalent elliptical areas for each threshold and tabulations of these areas as sorted by geometric area, perimeter, and shape factor. These latter tabulations are broken down into coarse increments, only to cover a large enough range to be generally applicable; these increments are not indicative of the resolution of the system and tabulations with much finer increments may be generated as required.

Calibrated data tapes for each of the scenes presented have been prepared and are available for additional processing as the need for additional statistics becomes apparent.

MEAN VALUES, STANDARD DEVIATIONS, SPECTRAL CORRELATIONS, AND HISTOGRAMS FOR THE SUB-AREAS AND TOTAL AREAS OF THE CHOSEN BACK-GROUND SCENES

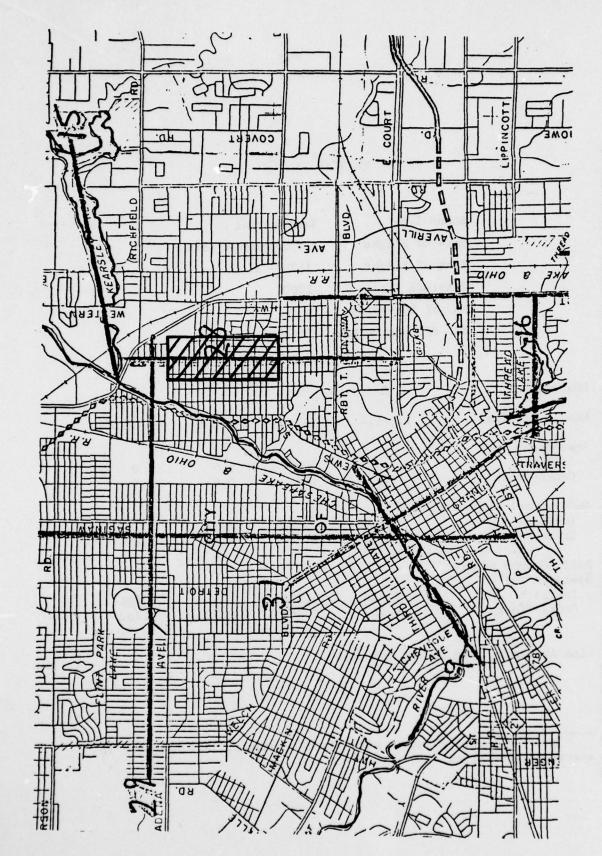
FLINT-1\*

Scene Type	Residential
Date of Flight	18 September 1971
Time of Flight	1132 - 1133
Altitude (Ft)	1000
No. of Sub-Areas	6
No. of Data Points	514,065

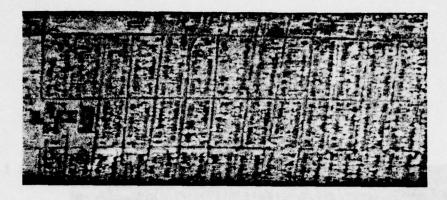
Channels	2	3	4	5
Wavelength (µm)	1.0-1.4	1.5-1.8	2.0-2.6	9.3-11.7
Resolution (mr)				
In-Track	5.0	5.0	5.0	5.0
Cross-Track	2.5	2.5	2.5	2.9
Nadir Pixel Dimension	s (m)			
In-Track	1.524	1.524	1.524	1.524
Cross-Track	0.762	0.762	0.762	0.884
Nadir Ground Sample				
Distance (m)				
In-Track	1.524	1.524	1.524	1.524
Cross-Track	0.762	0.762	0.762	0.762

Line Averaging used on ALL channels.

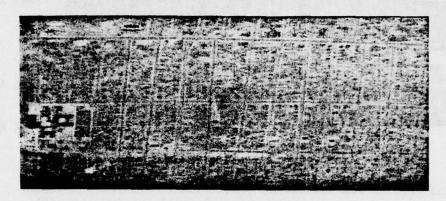
<sup>\*</sup>These data were obtained with the M-7 scanner. All data are in spatial registration.



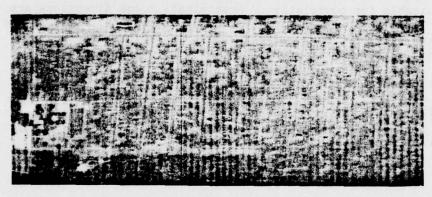
MAP OF THE FLINT AREA SHOWING THE REGION COVERED IN THE FLINT-1 RUN ABOUT FLIGHT LINE 28



 $1.0 - 1.4 \mu m$ 



1.5 - 1.8 µm

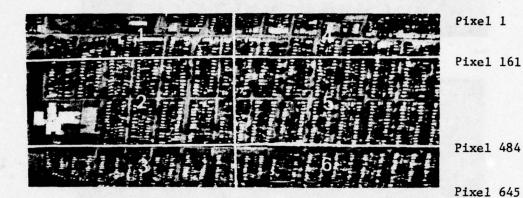


 $2.0 - 2.6 \mu m$ 



9.3 - 11.7 µm

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNEL OF FLINT-1
II-17



Line 403

Line 806

SUB-AREAS DEFINED FOR STATISTICS GENERATION IN THE FLINT-1 IMAGE. Uneven areas were chosen so that Areas 2 and 5 covered the  $\pm 20^{\circ}$  range suitable for correlation. Approximate scene dimensions are 3985 ft (1215 m) by 1612 ft (491 m). Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area 1 + Sub-area 4

Line 10

O Sub-area 2 × Sub-area 5

▲ Sub-area 3 ♦ Sub-area 6

FLINT-1 SUB-AREA 1

					4	4.1237F±01 - 2.9495E±02	1.0691E±01 2.6918L±00	63040. 63040.
£			1.900	0.132 1.000		2.3001E+02	7,7473E±01	63040
	1.000	- 0.493 . 1.000	0.316 0.614	-0.468 0.020 0.132 1.000		1.28045+03	- 3.47020 +02	63040.
CURRELATION	2	3	•	\$	CHANNEL S -	MF AN	SI DEV	TUTAL PTS.

FLINT-1 SUB-AREA 2

					 ιć	2.9495E+02	3.5245E+00	127262.
2	;				 7	3.7621E+01	1_0746E±01	127262.
5 4	00,175		1,000	0.167 1.000	 3	1.7978E+02	7,4411E+n1	127262
2 3	1.000	0.521 1.000	0.313 0.715 1,000	-0.482 -0.004 0.167	~	1.2757F+03	3.5471F±02	127262.
CHRREL AT JON	~	3	7	5	CHANNEL S	HFAN	SI. DEV.	THITAL PIS.

FLINT-1 SUB-AREA 3

8

						2.9379E+02	2.64761+00	63828.
					<b>a</b>	3.4348E+01	1.12445+01	6382B.
٦ م		6) (B. C.	1.000	0.112 1.000	<b>K</b>	1.6356E+02	8.1826E±01	63828.
2 3	1.000	0.724 1.000-	0.557 0.75R 1.000	-0.288 0.011 0.112	2	1.30566 + 03	4.2441E±02	63828.
CURREL AT ION		3	7	ç	CHANNEL S	MEAN	S1. DEV.	TOTAL PIS.

FLINT-1 SUB-AREA 4

4 5			• • • • • • • • • • • • • • • • • • • •	.116 1.000	3 4 5	1.9209f +n2 3.6268E+01 2.9499E+02	7.9889E±01 9.6634E+00 3.2649E+00	64480. 64480. 64480.	
	1,000	0.266 1.000	0.236 0.440 1.000	-0.520 0.012 0.116 1.000	2	1.1905F+03	3.4/1315.402	64483.	
	2	7	. 7	S	CHANNELS	MEAN	31. DEV.	THITAL PTS.	

FLINT-1 SUB-AREA 5

						5	2.9422E+02	3.0812E+00	130169.
						7	3.5162F+01	8.9344E+00	150169.
4 5			1.000	0.1.49 1.000	1	3	1.5A84E+02	7.9948E+01	130169.
2	1.000	0.2281.000	0.191 0.406	-0.525 -0.017 0.149		٦	1.3120F+03	3,5515F+02	130167.
CURREI ATION	2	3	TI TI	\$		CHANNFI S	MFAN	SI. DEV.	THIN PIS.

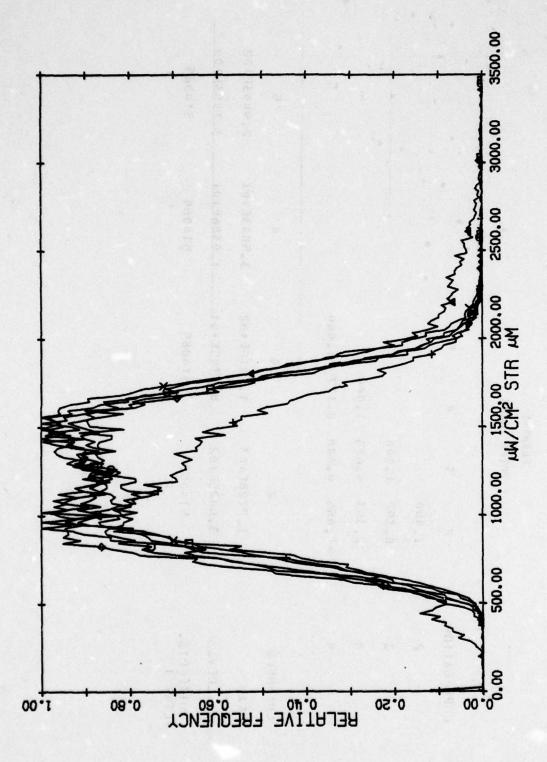
ENVIRONMENTAL RESEARCH INST OF MICHIGAN ANN ARBOR IN-ETC F/G 17/5 STATISTICAL ANALYSIS OF TERRAIN BACKGROUND MEASUREMENTS DATA. (U) AD-AU77 584 MAR 77 R SPELLICY , J BEARD , J R MAXWELL ERIM-120500-12-F N00123-76-C-0708 UNCLASSIFIED NL 2 OF 4 ADA 077 584 0

FLINT-1 SUB-AREA 6

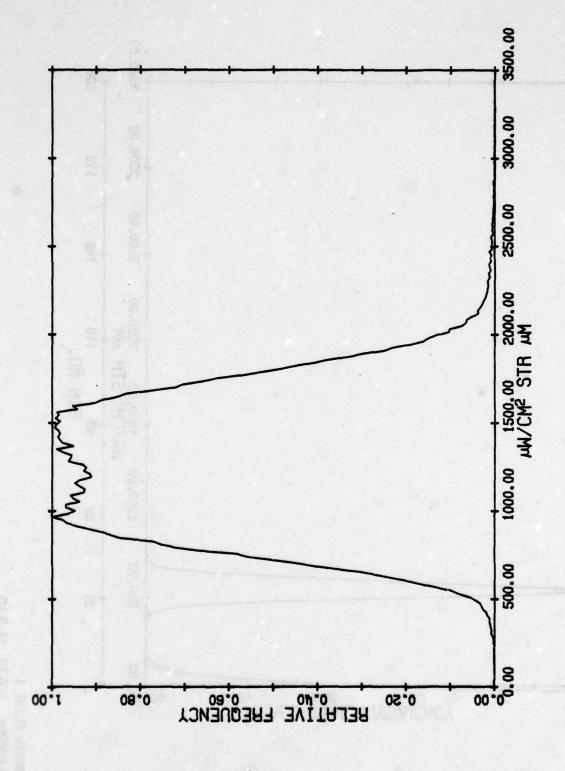
CHRPELATION	2	2		
~	1.000			
M	0.353 (.000	( 1 !		
7 .	0.2995 0.373 1.000	1.000		
\$	-0.440 -0.043	-0.440 -0.043 0.084 1.000		
CHANNEL S	٨	3	9 9	\$
MF AN	1.2313F+03	1,2457E+02	2.95716+01	2.9338E+0
31. DEV.	3.5484F+02	7.2868F+01	7.8701E+00	2,7294E+0
10TAL P13.	65286.	h5286.	65286.	65.286.

FLINT-1 TOTAL IMAGE

	. 1				. 5	3.5843E+01 2.9443E+02	1.0386F+01 3.1403E+00	514065 514065
			1.000	0.177 1.000	3	1.7316E+02	B.2745E+01	514065
. 5	1.000	0.392 1.000.	0.303 0.603	-0.455 0.048 0.177 1.000	 2	1.2728F103	3.6425E +02.	514065
CHRRELATION	2	<b>x</b>		S	CHANNEL S	MEAN	SI DEV	TUTAL PTS. FLINT 1



AREA: FLINT 1 LANBOR= 1.0 TO 1.4 M SUBAREAS

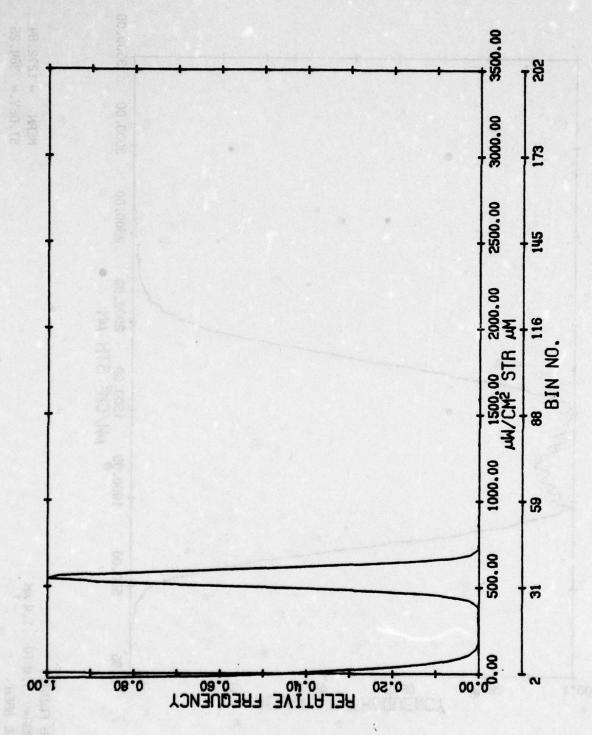


MERN = 1272.84 ST.DEV.= 364.25

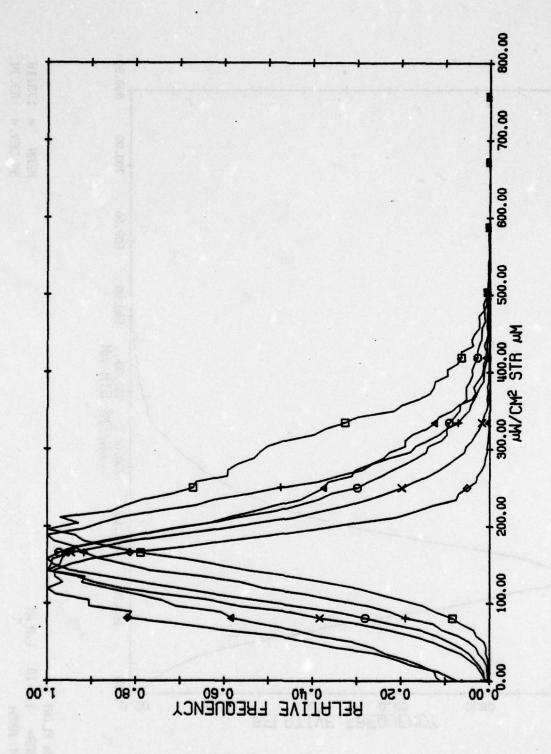
AREA: FLINT 1 LAMBOR- 1.0 TO 1.4 AM TOTAL PREA

0

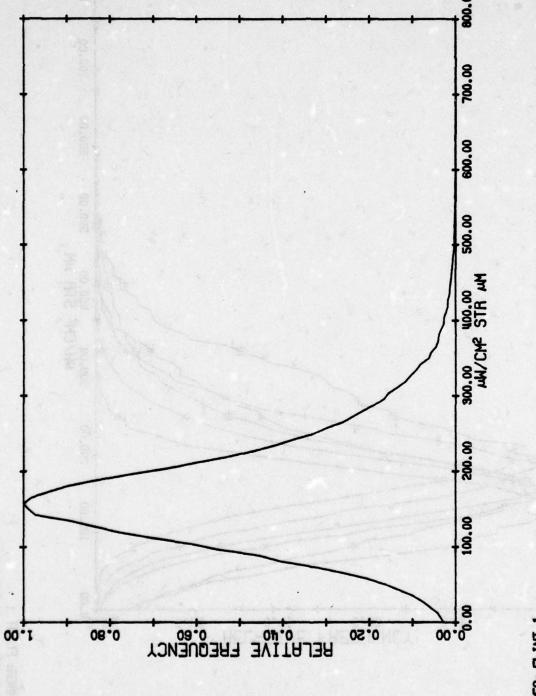
II-27



ANER: FLINT 1
LAMBOR- 1.0 TO 1.4 M
CALIB.PLATES



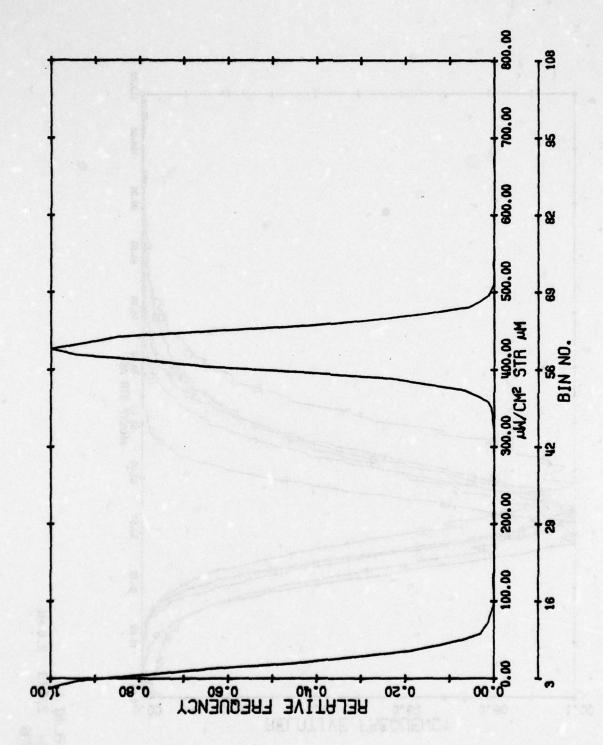
AREA: FLINT 1 LAMBOR= 1.5 TO 1.8 AM SUBAREAS



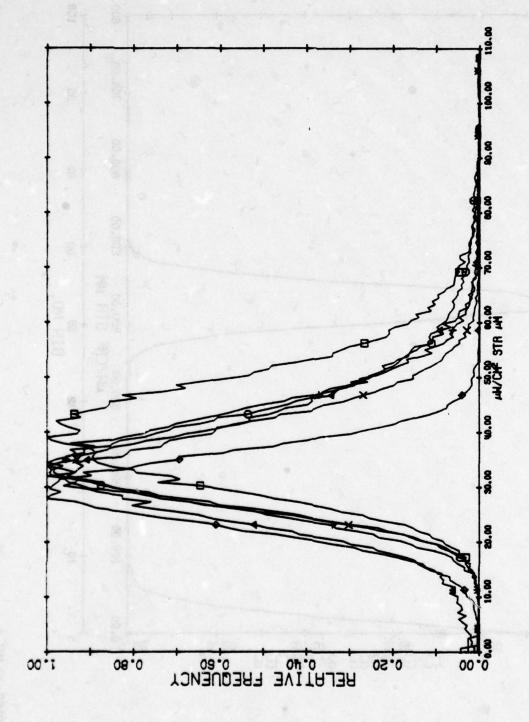
AREA: FLINT 1
LANDDA- 1.5 TO 1.8 AM
TOTAL AREA

= 173.16 .= 82.74

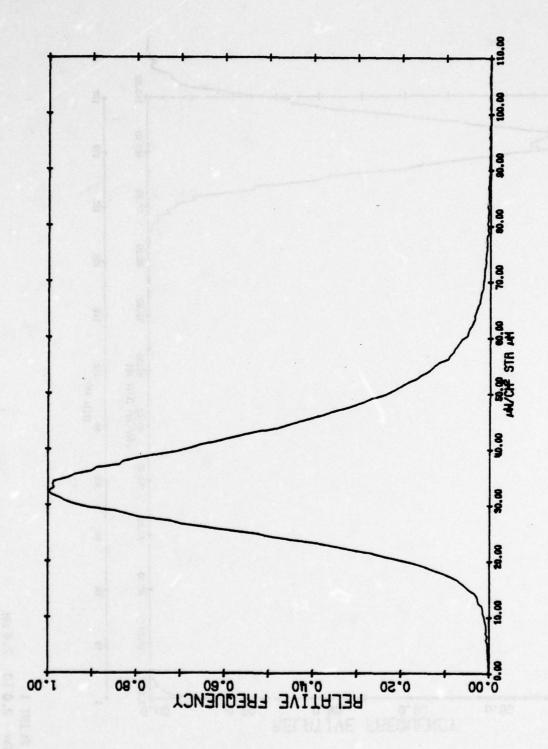
MERN = 1 ST. DEV.=



AREA: FLINT 1 LAMBOR- 1.5 TO 1.8 AM CALIB. PLATES

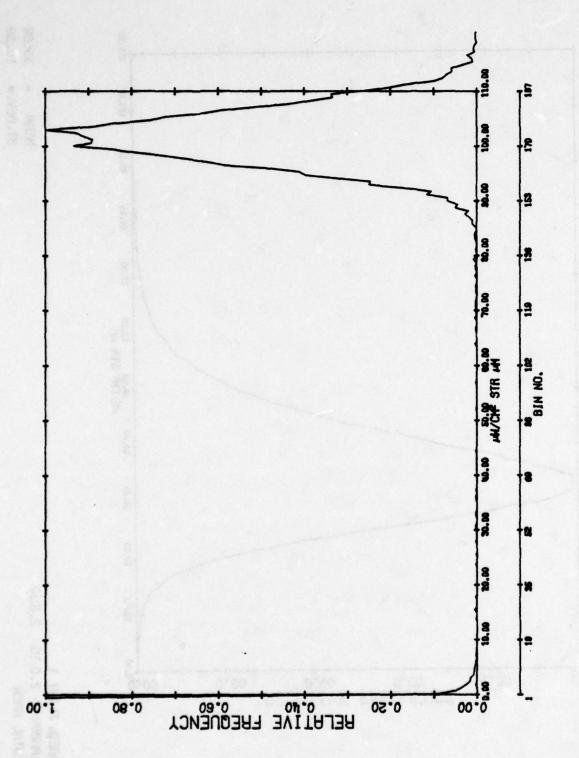


AREA: FLINT 1 LAMBOR= 2.0 TO 2.6 AM SUBAREAS



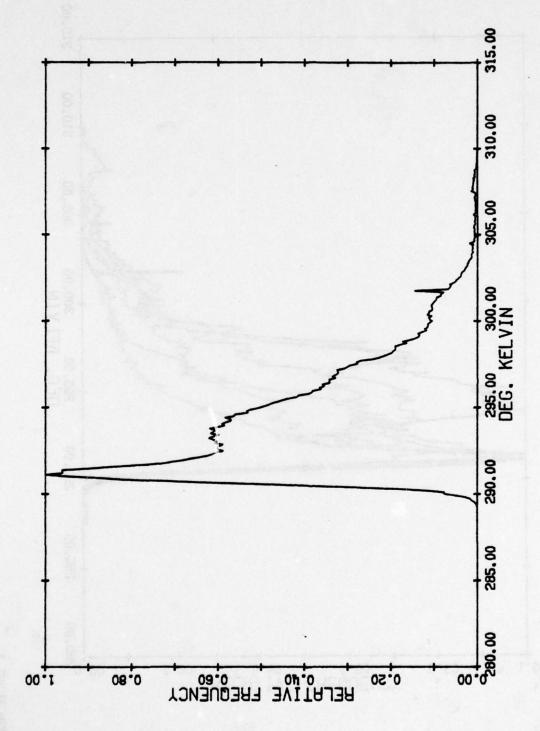
AREA: FLINT 1
LAMBOR 2.0 TO 2.6 MM
TOTAL AREA

MEAN = ST. DEV.=



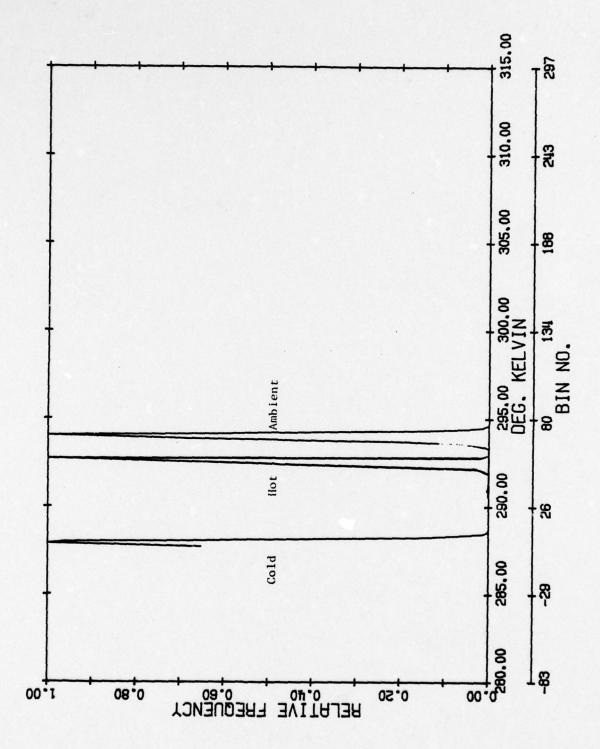
RREAL FLINT 1 LAMBOR 2.0 TO 2.6 M CALIB. PLATES

RREA: FLINT 1 LAMBOR= 9.3 TO 11.7 AM



ARER FLINT 1 LAMBOR 9.3 TO 11.7 AM TOTAL AREA

MERN = 294.43 ST.DEV.= 3.14



AREA: FLINT 1 LAMBOR= 9.3 TO 11.7 AM CALIB.PLATES

#### FLINT-2\*

Scene Type	Industrial
Date of Flight	18 Sep 1971
Time of Flight	1155 - 1157
Altitude (Ft.)	1000
No. of Sub-Areas	6
No. of Data Points	572,115

Channels	. 2	3	4	5
Wavelength (µm)	1.0-1.4	1.5-1.8	2.0-2.6	9.3-11.7
Resolution (mr)				
In-Track	5.0	5.0	5.0	5.0
Cross-Track	2.5	2.5	2.5	2.9
Nadir Pixel Dimen	sions (m)			
In-Track	1.524	1.524	1.524	1.524
Cross-Track	0.762	0.762	0.762	0.884
Nadir Ground Samp	le Distanc	e (m)		
In-Track	1.524	1.524	1.524	1.524
Cross-Track	0.762	0.762	0.762	0.762

Line averaging used on all channels of data

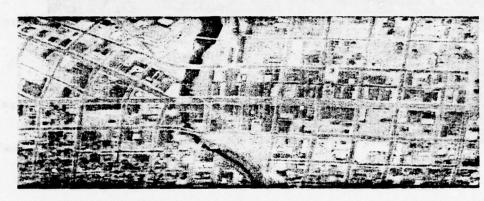
<sup>\*</sup> These data were obtained with the M-7 scanner. All data are on spatial registration.



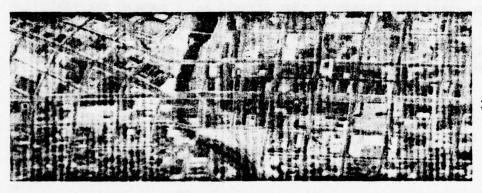
MAP OF THE FLINT AREA SHOWING THE REGION COVERED IN THE FLINT-2 RUN ABOUT FLIGHT LINE 31



1.0 - 1.4 µm



1.5 - 1.8 µm



 $2.0 - 2.6 \mu m$ 



9.3 - 11.7 µm

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF FLINT-2



SUB-AREAS DEFINED FOR STATISTICS GENERATION IN THE FLINT-2 IMAGE. Uneven areas were chosen so that Areas 2 and 5 covered the ±20° range suitable for correlation. Approximate scene dimensions are 4435 ft (1352 m) by 1612 ft (491 m). Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area 1 + Sub-area 4

○ Sub-area 2 × Sub-area 5

△ Sub-area 3 ♦ Sub-area 6

FLINT-2 SUB-AREA 1

CHANNELS 7.655	-0.244 -0.041 7.6551F+02 2.9745F+02	0.620 0.682 1.000 0.244 -0.041 0.057 7.6551F+02 2.40 <sup>6</sup> 2.9745F+02 8.24	000 057 1.000 3 2.4053E+02 8.2458F+01	4 3.8190E+n1 1.4956F+01	5 2.973RE+02 3.0840E+00
TUTAL PIS. 702	70240.	707	70240	70240	70240

FLINT-2 SUB-AREA 2

CURRELATION	2		•	r	CHANNELS	HEAN .	S1. 0EV.	TUTAL PTS.
2 3	1.000	0.797 1.800	0,562 0.654 1.000	-0-429 -0-2	2	7.4670F+02		141797.
7		00	54 1.000	-0.429 -0.254 -0.104 1.000	3	2.39316+02	- 8.0797F+0+	141797.
= 1				:		3.8759E+01		141797.
					<b>.</b>	2.9747E+02	-3-17486+60	141797.

FLINT-2 SUB-AREA 3

2 3 4 5	1.000	0.602 1.000	0.249 4.554 1.000	-0.507 -0.129 0.092 1.000	2 3	A.8222F+02 2.2722E+02 3.5325F+01	3.0389F+02 6.3982E+01 1.1400F+01	71118. 71118. 71118.
CURRELATION	2	3	V	r	CHANNEL S	MF. AN	31. DEV.	TIITAL PTS.

FLINT-2 SUB-AREA 4

				000		102 4.1351F+01 2.9545F+02	101	71680.
3 4 5		1.000	0.549 1.000	-0.550 -0.219 -0.039 1.000	•	7E+02 2,5540E+02	F+82 - 7-1678E+01-	10. T16A0.
2	1.000	0.618 1:000	0.378 0.549	- 0.550 -	O PARTIES A	8.9297E+02	2.87316+02	71680.
CURRELATION	Committee 5		•	\$	CHANNEL 8	HEAN	81. OEV.	TUTAL PTS.

FLINT-2 SUB-AREA 5

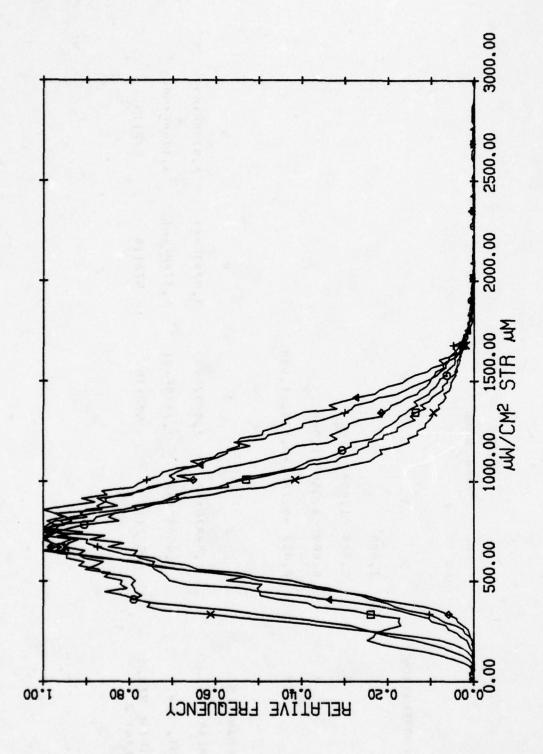
CUPRELATION 2 3	1.600	3 0.784 1.000	4 0.586 n.648 1.000	5 -0.391 -0.286 -0.163	CHANNEL S	7.1104E+02	SI. DEV. 2.93R2F+02	1UTAL PTS. 144704.	
4 5			1.000	-0.163 1.000	. <b>3</b> %	2,31306+02	7.88176+01	144704.	
(8)			9		4	3.9399F+01	1.4050F+01	144704.	
					٠.	2,97731+02	3.11465+00	144704.	

FLINT-2 SUB-AREA 6

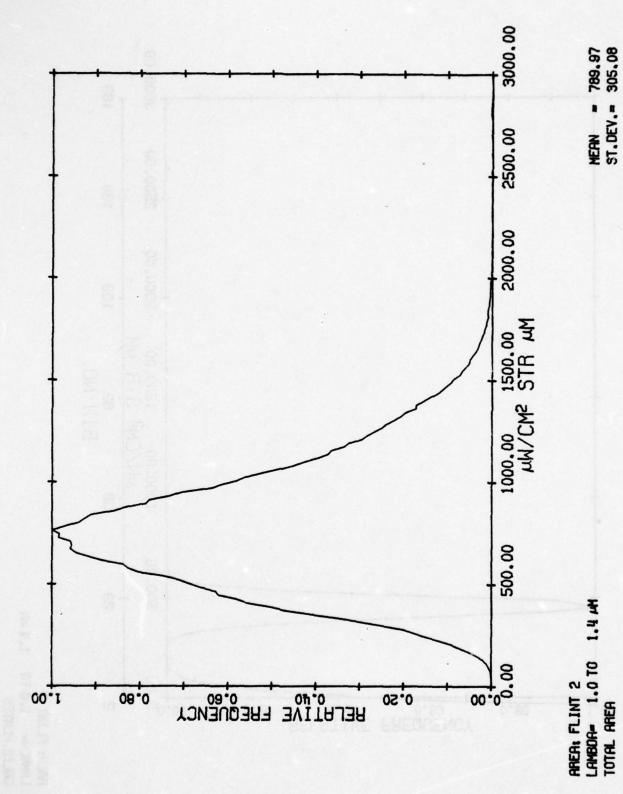
2 3 4 5	1.000	0.652 1.088	0.434 0.617 1.000	-0.311 0.071 0.146 1.000	2	8.6346F+02 2.5525E+02 4.2684E+01 2.9611E+02		72576- 72576- 72576-
CHRREL ATION			•	ur .	CHANNEL S.	MEAN	St. DEV.	TUTAL PTS.

FLINT-2 TOTAL IMAGE

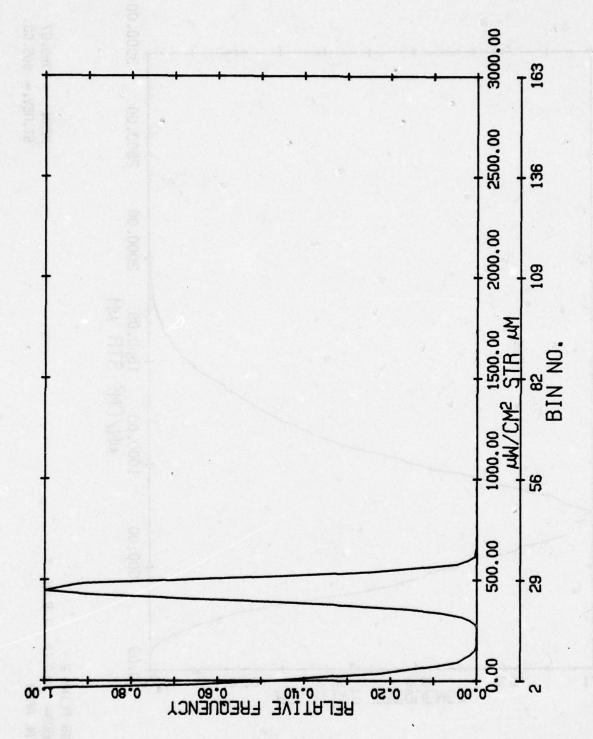
CORPELATION	~	۲	7	5					
2	1.000								
3	0.718 1.000	1.000	1		•	ŧ			
•	0.489	0.634	1.900						
\$	-0.437 -0.180 -0.036	0.180	.0.036	1.000					
						,			
CHANNELS	~		3	•	n			5	
MEAN	7.8997F+02	F+02	2,3097E+02	7E+02	3,92475+111	7F+01	ď	7.9700F+02	60
SI. DEV.	3.0508F+02	F+02	7.7870E+01	10+30	-1-3748F+01	8F+01	3.	3.1.7681.+04	4
TUTAL PTS.	572115	15	511575	511	51122	511		572115	



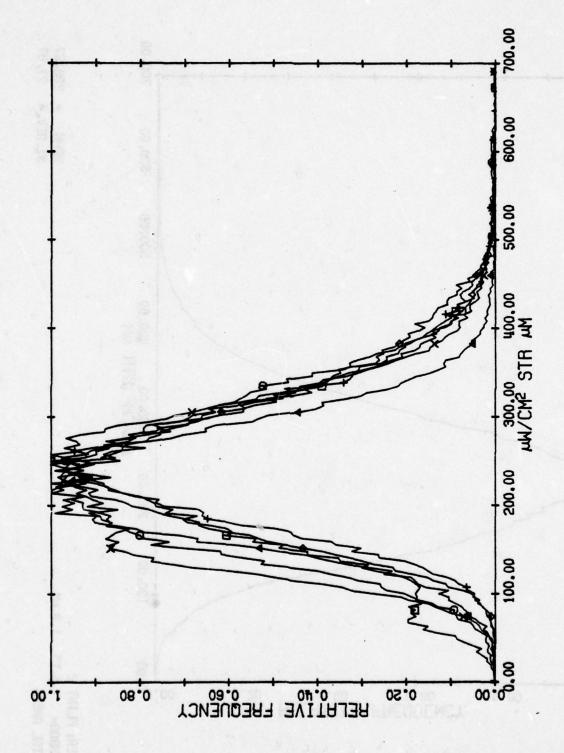
AREA: FLINT 2 LAMBOR= 1.0 TO 1.4 JM SUBAREAS



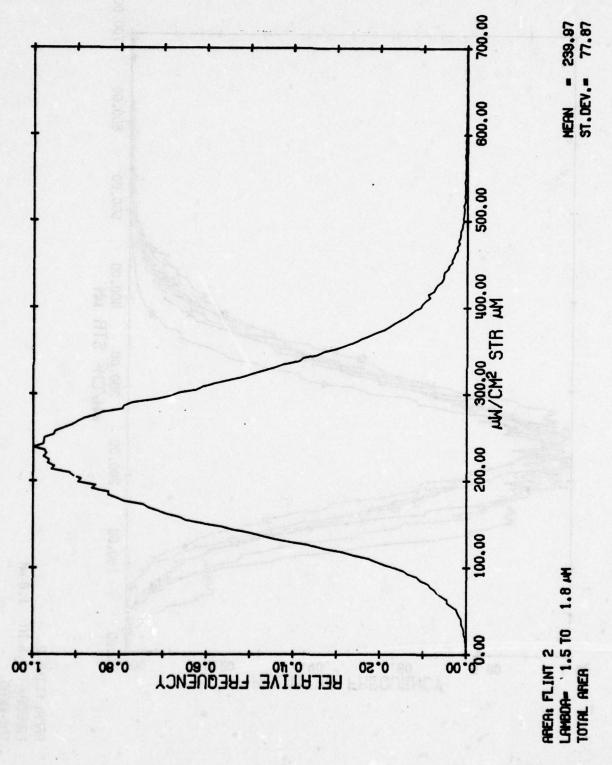
.

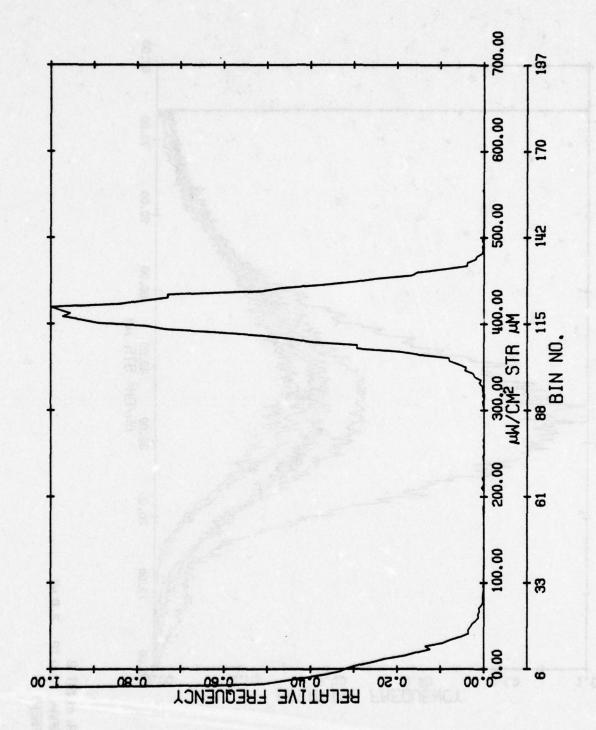


AREA: FLINT 2 LAMBOR- 1.0 TO 1.4 AM CALIB.PLATES

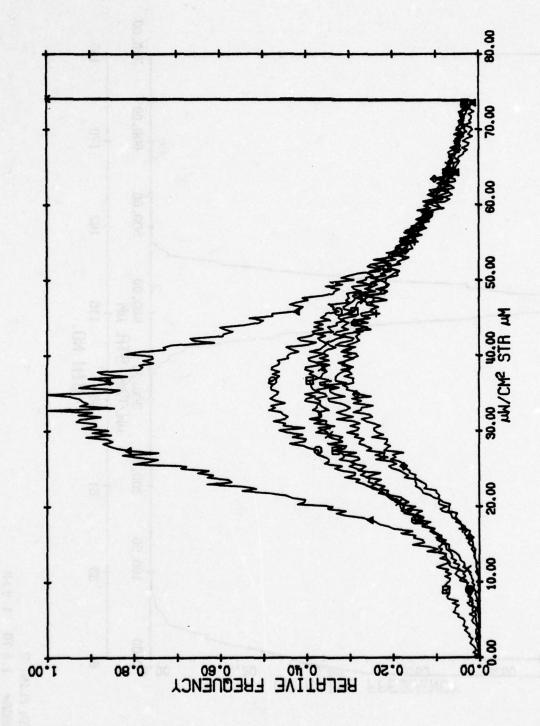


AREA: FLINT 2 LAWBOR- 1.5 TO 1.8 AM SUBAREAS

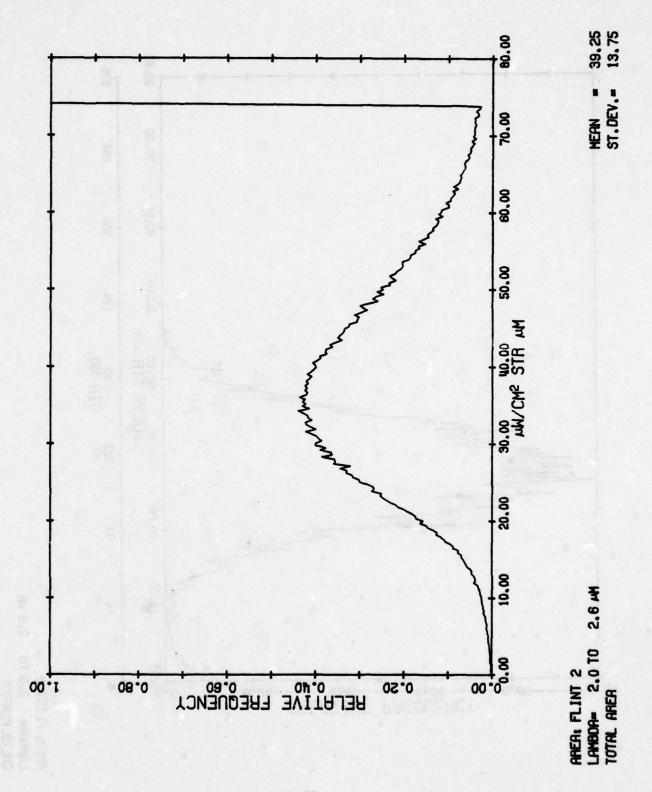


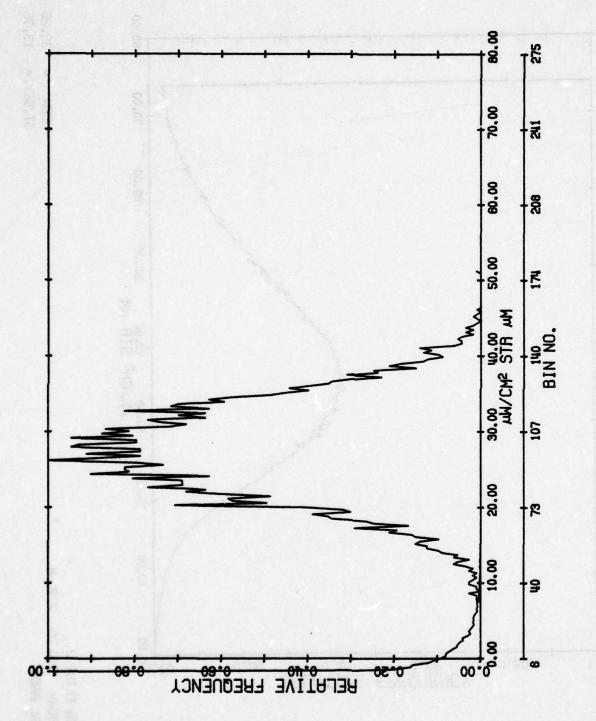


RREA: FLINT 2 LAMBOR= 1.5 TO 1.8 WH CALIB. PLATES

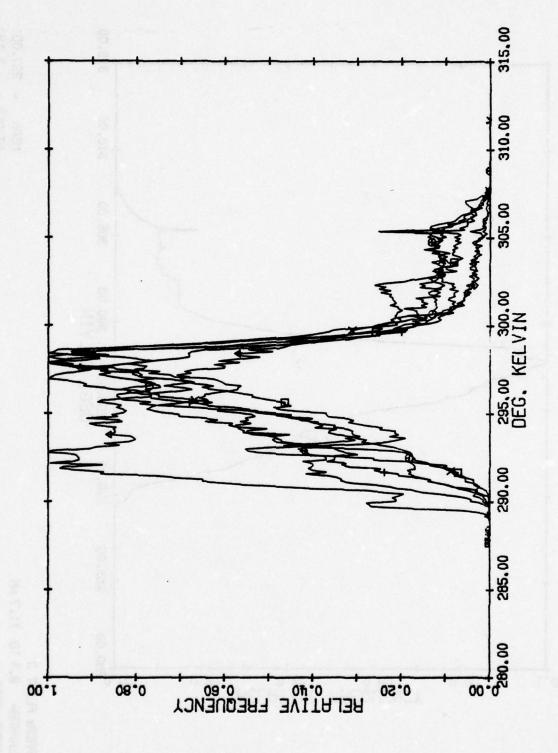


AREA: FLINT 2 LAMBOR 2.0 TO 2.6 SUBAREAS

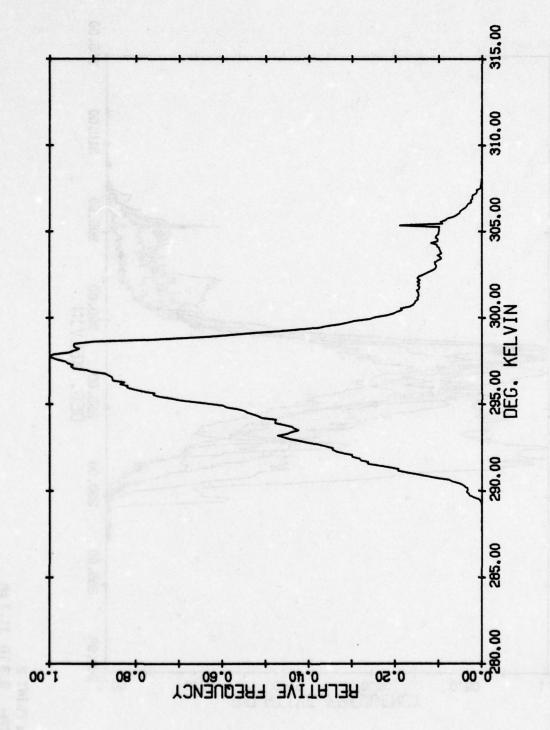




AREA: FLINT 2 LAWBOR- 2.0 TO 2.6 CALIB.PLATES



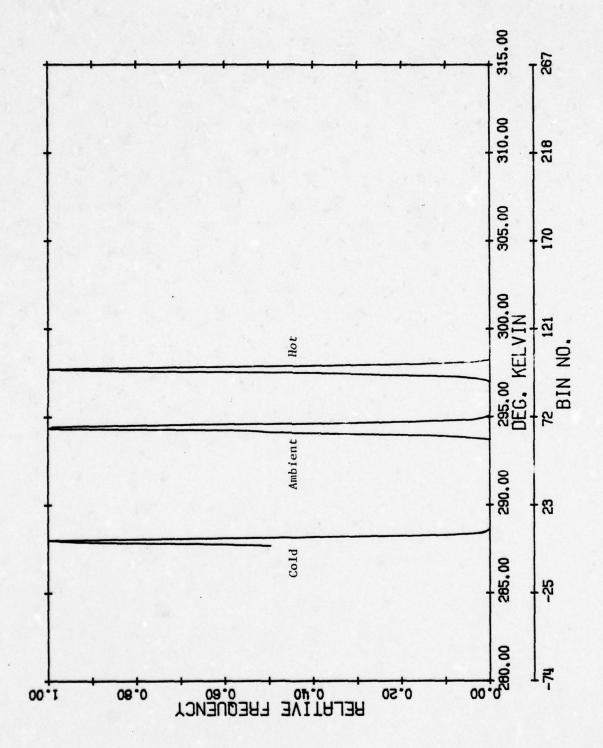
PREA: FLINT 2 LAMBOR- 9.3 TO 11.7 JM SUBAREAS



AREA: FLINT 2 LAWBOR= 9.3 TO 11.7 AM TOTAL AREA

MERN = ST.DEV.=

11-60



0

AREA: FLINT 2 LAMBDA= 9.3 TO 11.7 JM CALIB.PLATES

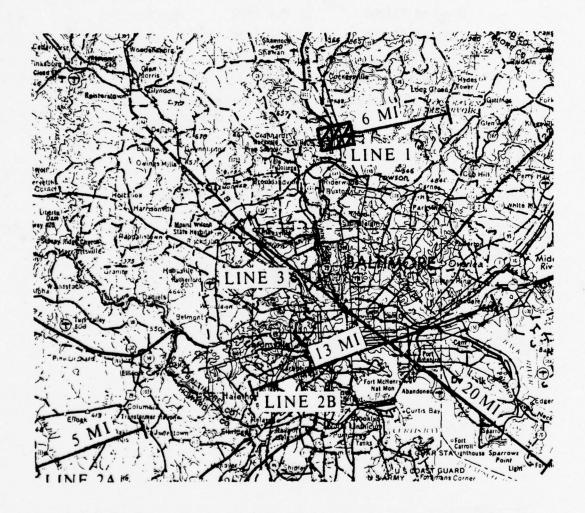
#### BALT IMORE\*

Scene Type	Residential
Date of Flight	11 May 1972
Time of Flight	1137 - 1139
Altitude (Ft)	2500
No. of Sub-Areas	6
No. of Data Points	269,610 for channels 2,4 322,500 for channel 5

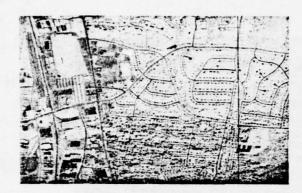
Channels	2	4	5
Wavelength (µm)	1.0-1.4	2.0-2.6	9.3-11.7
Resolution (mr)			
In-Track	5.0	5.0	5.0
Cross-Track	2.5	2.5	2.9
Nadir Pixel Dimensions	s (m)		
In-Track	3.810	3.810	3.810
Cross-Track	1.905	1.905	2.210
Nadir Ground Sample			
Distance (m)			
In-Track	3.810	3.810	3.810
Cross-Track	1.905	1.905	1.905

Line Averaging used for ALL channels.

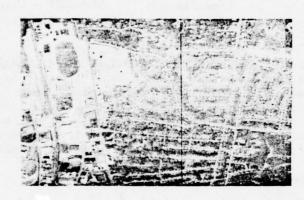
<sup>\*</sup>These data were obtained with the M-7 scanner. The 1.0-1.4 and 2.0-2.6  $\mu$ m data are in spatial registration, but the 9.3-11.7  $\mu$ m data were processed separately and are not in spatial registration with the 1.0-1.4 and 2.0-2.6  $\mu$ m data. Hence, spectral correlation coefficients have not been determined between the 9.3-11.7  $\mu$ m data and either the 1.0-1.4  $\mu$ m or 2.0-2.6  $\mu$ m data.



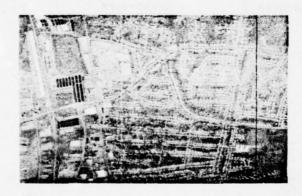
MAP OF THE BALTIMORE AREA SHOWING THE REGION COVERED IN THE BALTIMORE RUN ABOUT FLIGHT LINE 1



1.0 - 1.4 µm

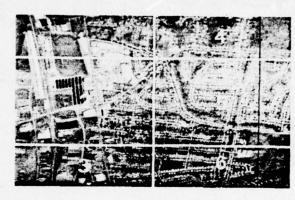


 $2.0 - 2.6 \mu m$ 



 $9.3 - 11.7 \mu m$ 

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF BALTIMORE



Pixel 1

Pixel 161

Pixel 484

Pixel 645

Line 10 Line 1 Line 213 Line 250 Line 427 - Channels 2, 4 Line 500 - Channel 5

SUB-AREAS DEFINED FOR STATISTICS GENERATION IN THE BALTIMORE IMAGE. Uneven areas were chosen so that Areas 2 and 5 covered the  $\pm 20^\circ$  range suitable for correlation. Approximate scene dimensions are 6250 ft (1905 m) by 4031 ft (1229 m) for channel 5 and 5225 ft (1592 m) by 4031 ft (1229 m) for channels 2 and 4. Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area 1

+ Sub-area 4

O Sub-area 2

× Sub-area 5

△ Sub-area 3

♦ Sub-area 6

1.000	
-0.157 1.000	
CHANNELS	
MEAN 2.4955F103 9.3149E+01 2.9940F+0	2_
ST. DEV. 8.0187F102 4.8381E+01 6.2943E+0	· 0
TOTAL- PTS. 32640. 32640. 40000.	

-CURRELATION -	2		
	1.000	· · · · · · · · · · · · · · · · · · ·	
4		4	
CHANNEL S	22		
HEAN	1.9511F+03	.0001E+02 2.9934	E+02
-STDEV.	7.1298F+02	-5234E+01 6.3927	E++0
TOTAL PTS	65897	658928075	0

CURPELATION -	2 4	
2	1.000	
	0.263 1.000	
CHANNELS	54	
MEAN-	1.5689F103 7.3852E+01	2,9896F±02
ST. DEV.	5.9838F+02 4.3159E+n+	-5,2225F+00
TUTAL PTS	330483048.	40500

CURRELATION	2 4	8	FOLLWISE BLUDS
	1.000	500,1	
	-0.119- 1.000	305.0	
			<u>.</u>
CHANNEL S	2	4	2.840.443
- MEAN	2.71115103	-7.5269E+01-	2-0001E+02
ST. DEV.	0.27931 +02	2.8969E+01	4.9329E+00
TUTAL PTS.	34240.	34240.	aanan.

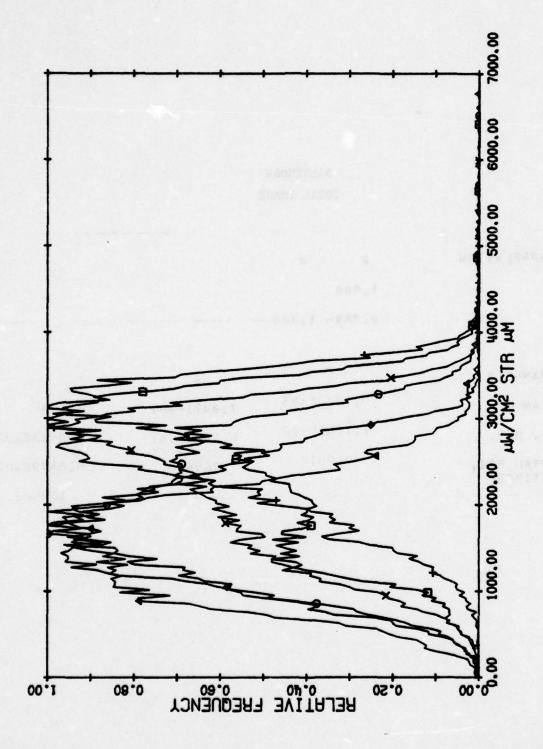
CHRRELATION	24		465 TAN 343 TO
-5	1.000	400.1	44.2
4	0.075-1.000		
200 m o o o o o o o o o o o o o o o o o o			
- CHANNELS	2	-4	
MEAN	2.2956E+03	6.7554E+#1	3.0025E+02
SI. DEV.	7.1763F+02	2.8608E+n1	- 5.7796E+00.
-TUTAL PTS.	69122.	69122.	80 750

## BALTIMORE SUB-AREA 6

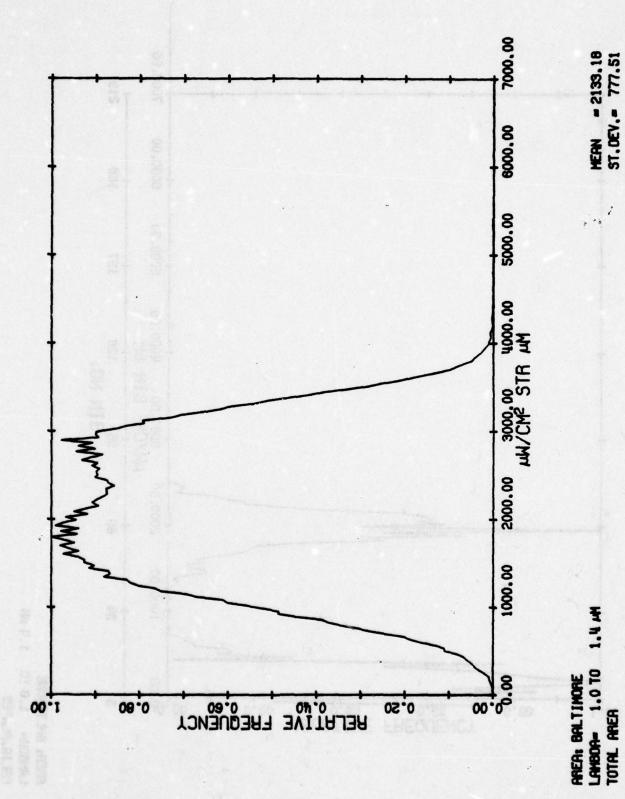
CURRELATION	54
· 2-	1:000
_	<del>-</del>
CHANNEL S-	2 4 - 11
- HEAN	1.7814E+03 5.3057E+0+ 2.9648F+4
ST. DEV.	6.1299F+02 2.7117E+01 5.2716E+
-TOTAL PTS	34668. 40500.

## BALTIMORE TOTAL IMAGE

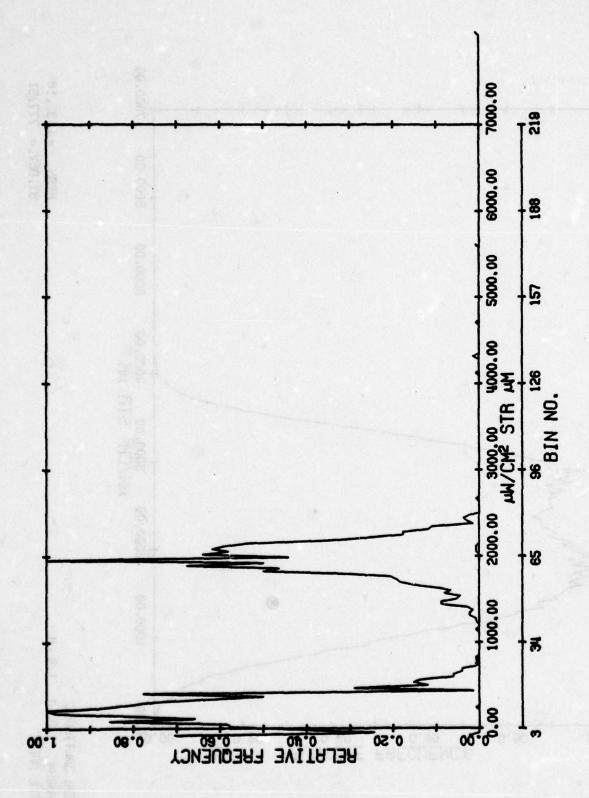
CURRELATION '	2 4 .		
	1.000 -		
. 4	0.084-1.000-	- :	
CHANNELS	7	4	. <b></b>
MFAN _	2.13325103	7:8471E+01	11
SI. DEV.	7.7751F+02	4.3876E+01	- 2-9913E+02_
TOTAL PTS. BALTIMORE	500010	269610	5.8879F+00
	· ····· - · · · · · · · · · · · · · · ·		322500



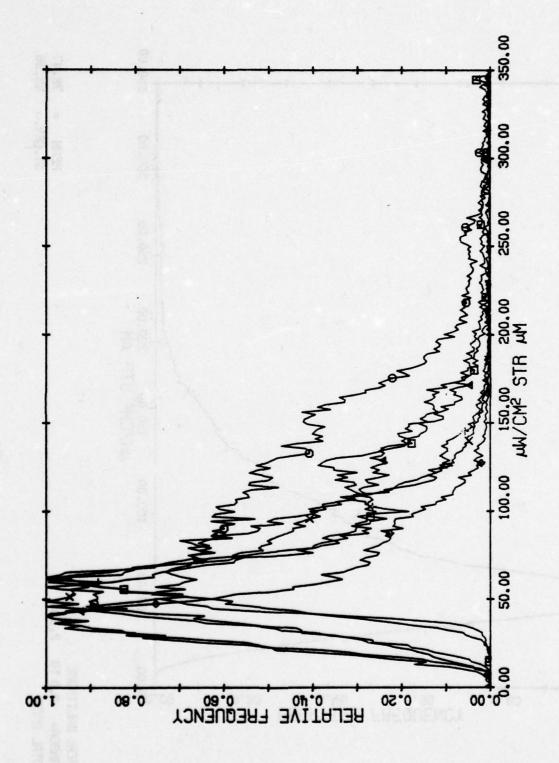
AREA: BALTIMORE
LAMBOR- 1.0 TO 1.4 JM
SUBAREAS



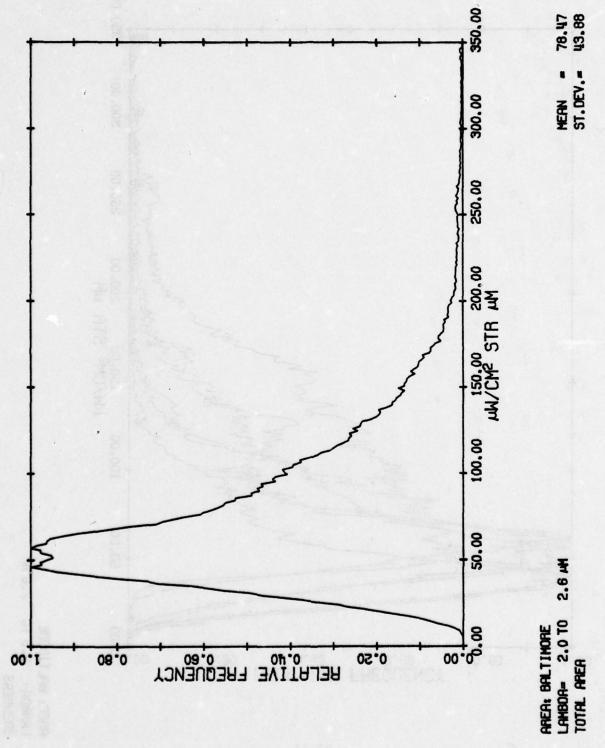
11-75

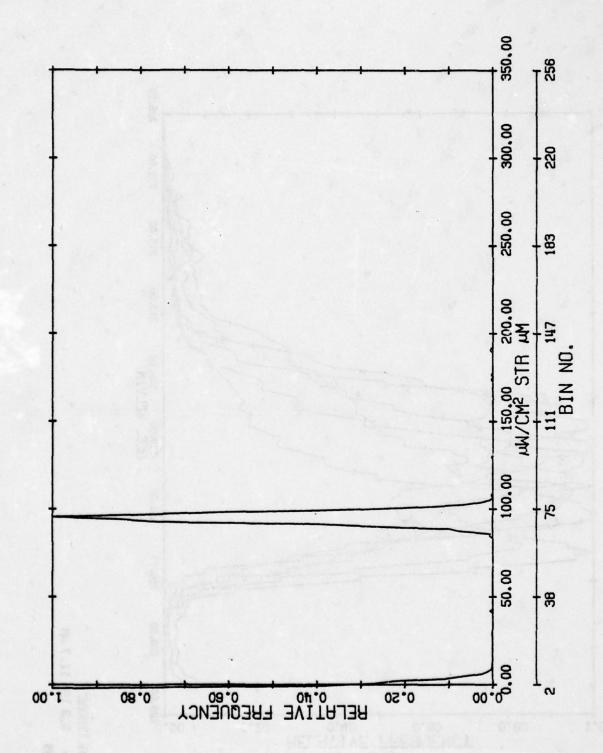


AREA: BRLTINGRE
LANGOR- 1.0 TO 1.4 AM
CALIB.PLATES

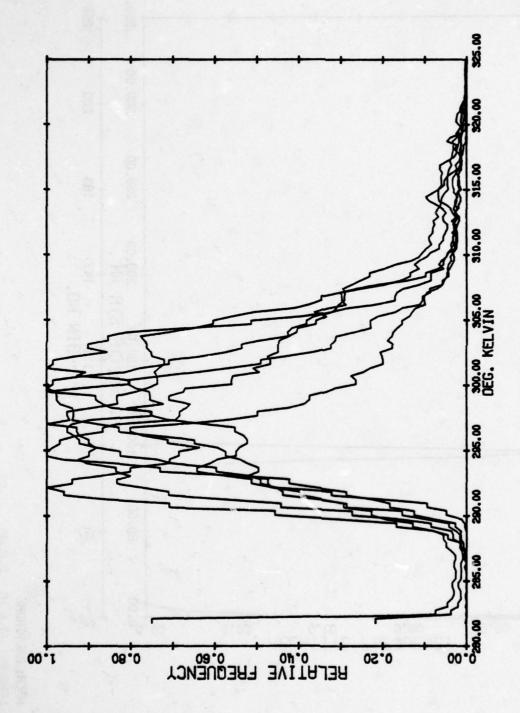


AREA: BALTIMORE
LAMBOR 2.0 TO 2.6 JM
SUBAREAS

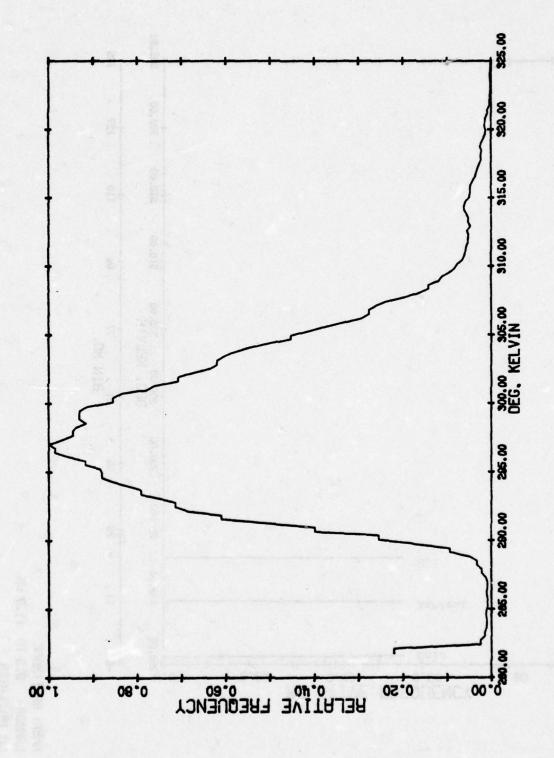




AREA: BALTIMORE
LAMBOR= 2.0 TO 2.6 WM
CALIB.PLATES

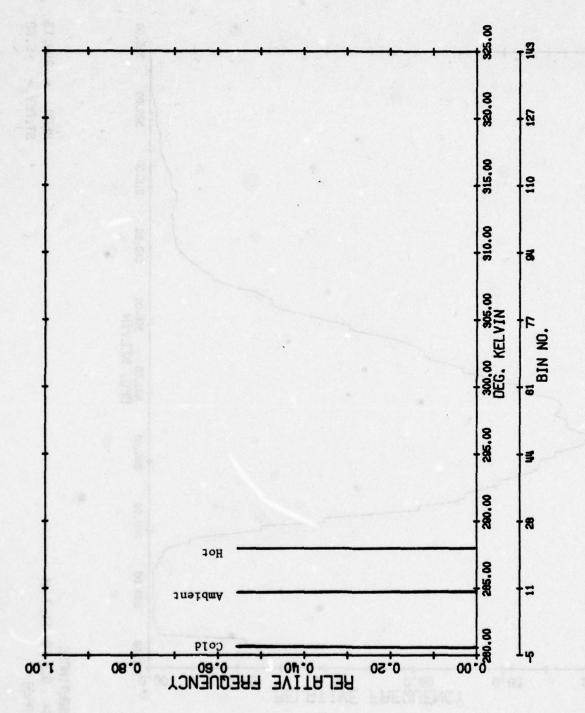


PREAL BALTINORE
LAWBOR- 9.3 TO 11.7 AM
SUBAREAS



AREA: BALTINORE
LAMBOR- 9.3 TO 11.7 M
TOTAL AREA

NEAN = 289.13 ST.DEV.= 5.89



AREA: BALTINORE
LAMBOR- 9.3 TO 11.7 AM
CALIB.PLATES

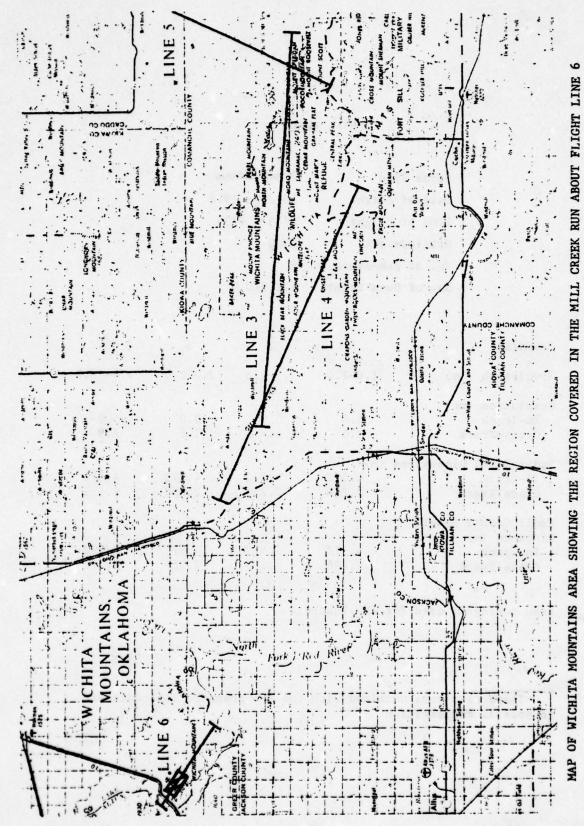
MILL CREEK\*

Scene Type	Mountainous			
Date of Flight	30 June 1972			
Time of Flight	0733 - 0736			
Altitude (Ft)	3000			
No. of Sub-Areas	6			
No. of Data Points	171,570			

Channels	2	3	4	5
Wavelength ( m)	1.0-1.4	1.5-1.8	2.0-2.6	9.3-11.7
Resolution (mr)				
In-Track	5.0	5.0	5.0	5.0
Cross-Track	2.5	2.5	2.5	2.9
Nadir Pixel Dimension	ıs (m)			
In-Track	4.572	4.572	4,572	4.572
Cross Track	2.286	2.286	2.286	2.652
Nadir Ground Sample				
Distance (m)				
In-Track	4.572	4.572	4.572	4.572
Cross-Track	2.286	2.286	2,286	2.286

Line Averaging used for ALL channels.

<sup>\*</sup>These data were obtained with the M-7 scanner. All data are in spatial registration



11-84



 $1.0 - 1.4 \mu m$ 



1.5 - 1.8 µm

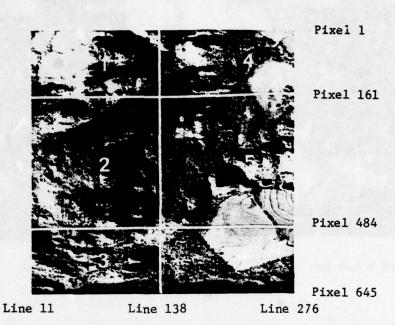


2.0 - 2.6 µm



9.3 - 11.7 μm

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF MILL CREEK



SUB-AREAS DEFINED FOR STATISTICS GENERATION IN THE MILL CREEK IMAGE. Uneven areas were chosen so that Areas 2 and 5 covered the  $\pm 20^{\circ}$  range suitable for correlation. Approximate scene dimensions are 3990 ft (1216 m) in-track by 4837 ft (1474 m) cross-track. Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area 1 + Sub-area 4

○ Sub-area 2 × Sub-area 5

△ Sub-area 3 ◇ Sub-area 6

MILL CREEK SUB-AREA 1

0

.

CURMFLATION	2	2 3		
Section 2				
,	1.000			
3	0.925 1.000	e Xika a Piribaa		
•	6,959 0,919	1.000		
r	0.589 4.653 0.634	0.634 1.000		
		٠		
CHAMNFL S	٨	~	Ð	ír
MEAN	1.1053F+02	3.9088F+01	5.2601E+00	2.9907E+02
31. DEV.	A.2802F101	2.8063F+n1	4.4031E+00	1.09116+00
TUTAL PTS.	20480.	Jodko.	20480.	20480

MILL CREEK SUB-AREA 2

		nnn	000°T 1°000	0.169 0.361 0.305 1.000	3	01 2.1860F+01 2.2662F+06 2.9840F+02	01 1.4143E+01 1.8589E+00 9.9308F-01	
2 3	1.0"0	0.812 1.000	0.895 0.434	0.169 n.	~ ~	6.3868F+01	4.3890F101	
CHRREI ATTON	2	•	=	5	CHAMNEL S	Mf A <sup>1</sup> !	ST. DEV.	

		MON.	\	000	٦.	+n1 4.1033F+n0 2.9787E+02	+01 1.6939F+00 8.5154E-01	. 20736. 20736.
3 4 5		1.000	000-1 /17.0	0.138 0.500 0.345 1.000	•	F+n2 3.7579F+n1	F+01 1.4356F+01	6. 20736.
ر NO	1.000	0.648 1.000	417.0 454.0	0.138	~	1.3055F+42	5.0883F+01	. 20736.
CHRRELATION	2	N	8		CHANNEL S	MEAN	31. DFV.	CUTAL P15.

						v	2.9781E+02	7.8850E-01	22080.
						n	5.0519F+00	3.2356E+00	,208n.
a 5			1.000	0.346 1.000		3	4.2616E+01	2.0884E+01	.220A0.
2 3	1.000	0.749 1.000	0.767 0.463	0.217 0.405 0.346 1.000	11111	٨	1.3146F102	5.7894E+n1	22080.
CHPPEL AT JON	~	3	<b>u</b>	L*		CHANNEL S	MEAU	SI. DEV.	TUTAL PTS.

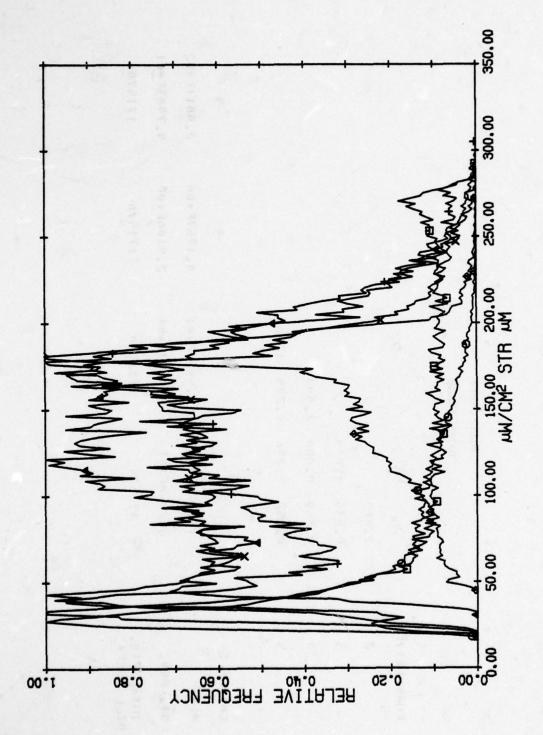
3

CHPMFLATION 2 3 4 5 5 1.000 2 1.000 3 0.779 1.000 4 0.845 1.000 5 0.094 0.342 0.260 1.000 6HANNELS 2 3.7550E+01 81.0FV. 5.4105E+01 1.7685E+01	1.000 3.9794E+02 50E+01 4.2318F+00 2.9794E+02 85F+01 2.4486E+00 7.6937E-01
---	---

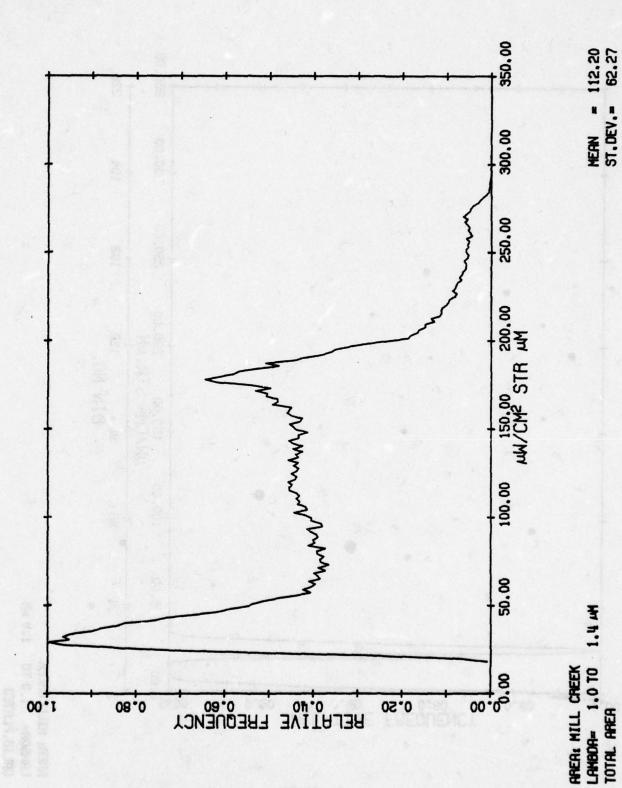
CHPREL AT ION	٨	~	<b>U</b>	r		
2	1,000					
r	0.702 1.000	1.000				
•	0.732 0.859 1.000	0.859	1.000			
\$	0.125 0.424 0.368 1.000	11511.11	0.368	1.000		
	Table Land					
CHANNEL S	~			3	7	5
MEAN	1.54795+02	2013	1.76	10+31147.	5.8111F+00	2.9752E+02
SI. DEV.	3.8400F+01	101	1,49	1,49658+01	2.1549E+00	6.5507E-01
TUTAL PTS.	22356.	.,	22	. 95222	22356.	22356.

MILL CREEK TOTAL IMAGE

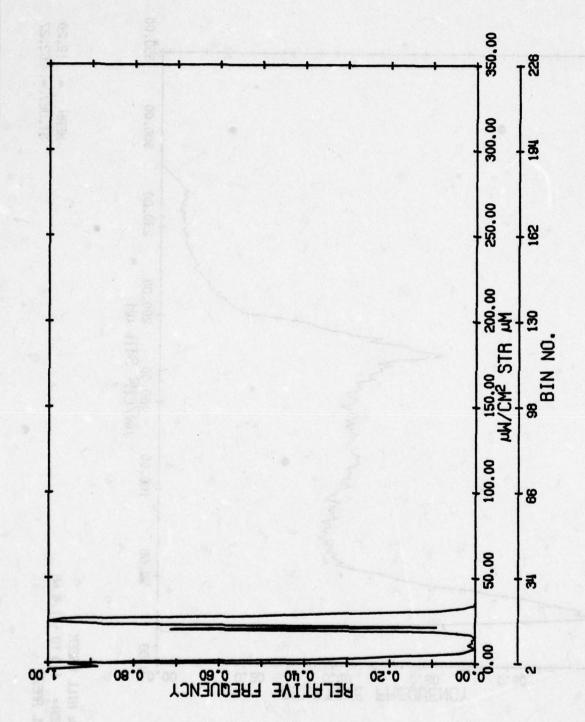
2 1.000 3 0.835 1.000 4 0.869 0.880 1.000 5 0.052 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.256 0.256 0.256 0.245 1.000 6 0.052 0.256 0.245 1.000 6 0.052 0.256 0.	CHPRELATION	2	~	-	5		
0.835 1.000 0.869 0.880 1.000 0.052 0.256 0.245 1.000 2 3 3 4 1.1220F+02 3.5919F+01 4.1767F+00 0.2268F101 2.0177F+01 2.9106F+00 171570 171570 171570	C.	1.000					
0.869 0.840 1.000 0.052 0.245 1.000 2 3 4 1.1220F+02 3.5919F+01 4.1767F+00 0.2268F101 2.0177F+01 2.9106E+00 171570 171570 171570	<b>8</b>	0.835	1.000				
0.052 0.256 0.245 1.000  2	= 0	0.869	0.880	6 v 0 • 1			
2 3 4 1.1220F + 02 3.5919F + 01 4.1767F + 00 0.2268F + 01 77E + 01 2.9106E + 00 171570 17157n 171570	\$	0.052	1.256	0.245	1.900		
3 4 1.1220F+02 3.5919F+01 4.1767F+00 0.2268F101 2.0177E+01 2.9106E+00 171570 171570 171570							
1.1220F+02 3.5919F+01 4.1767F+00 0.2268F101 2.0177E+01 2.9106E+00 171570 171570 171570	CHANNEL S	~			3	7	5
0.2268Fin1 2.0177E+01 2.9106E+00 171570 17157n 171570	MFAM	1.1220	F+02	3.59	198+01	4.1767F+00	2.9811E+02
072171 072171 072171	SI. DEV.	0.2268	1011	7.01	77E+01	2.9106E+00	9.7983E-01
	HILL CREEK	1715	02	1.1	1570	171570	171570



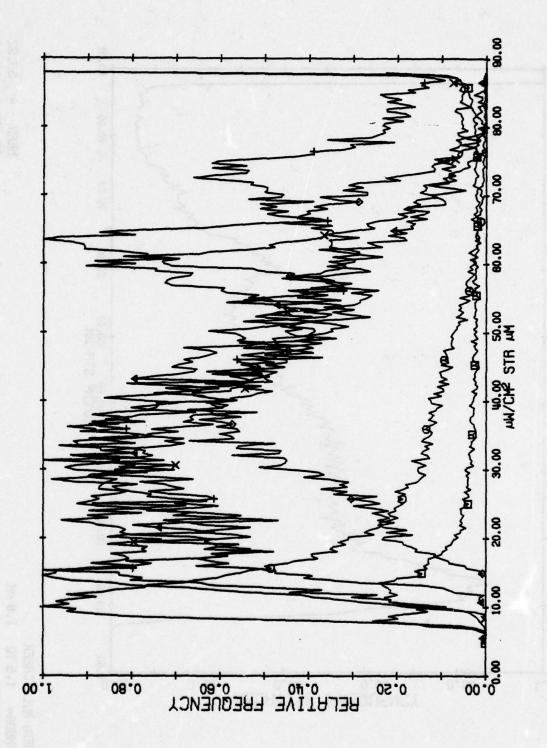
AREA: MILL CREEK
LAMBOR= 1.0 TO 1.4 M
SUBARERS



11-95

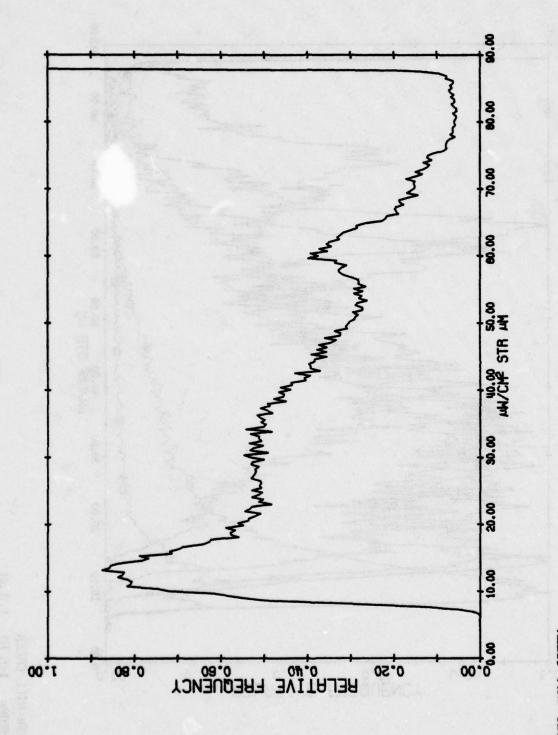


AREA: MILL CREEK LAHBOR- 1.0 TO 1.4 JH CALIB, PLATES



AREA: MILL CREEK LAMBOR= 1.5 TO 1.8 AM SUBAREAS

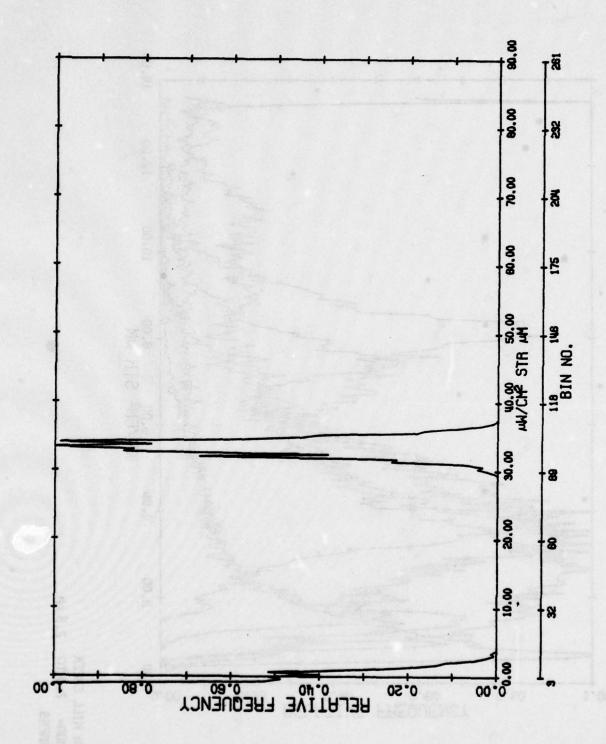
0



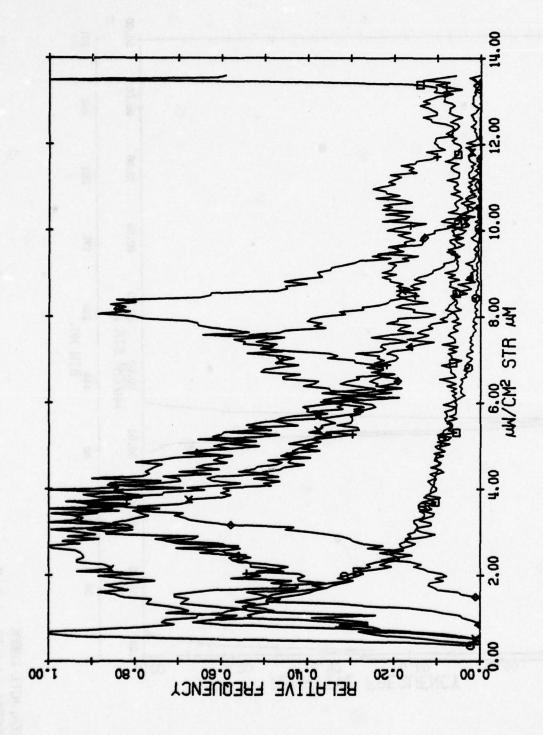
APER MILL CREEK LANBOR 1.5 TO 1.8 AM TOTAL AREA

35.92

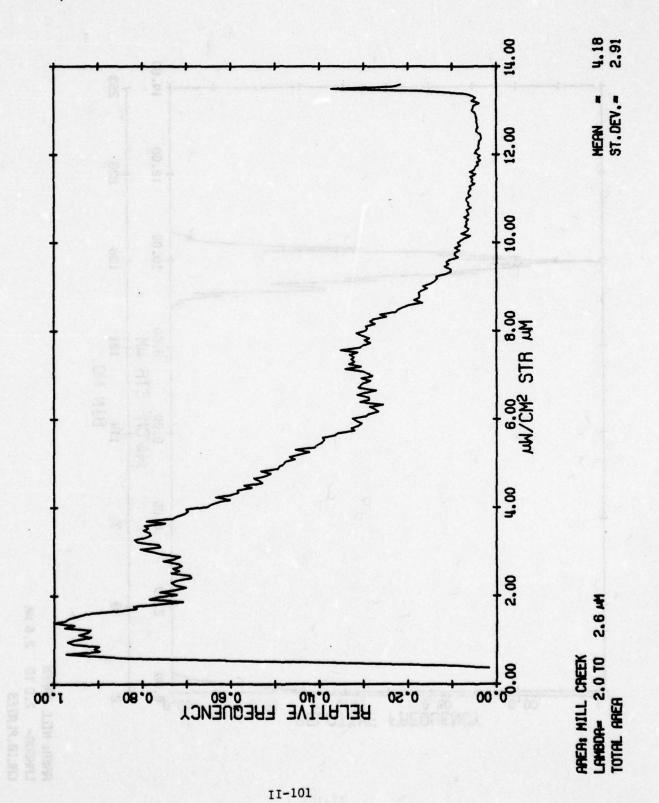
HERN -

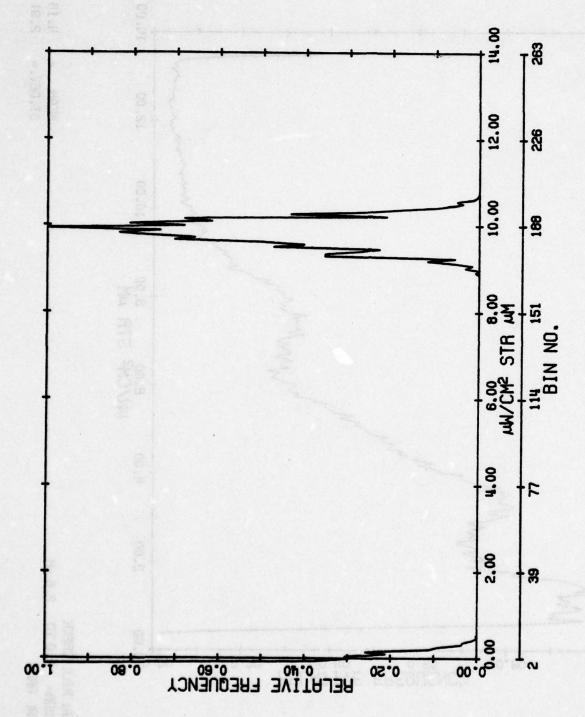


AREA: MILL CREEK LAMBOR= 1.5 TO 1.8 MM CALIB.PLATES

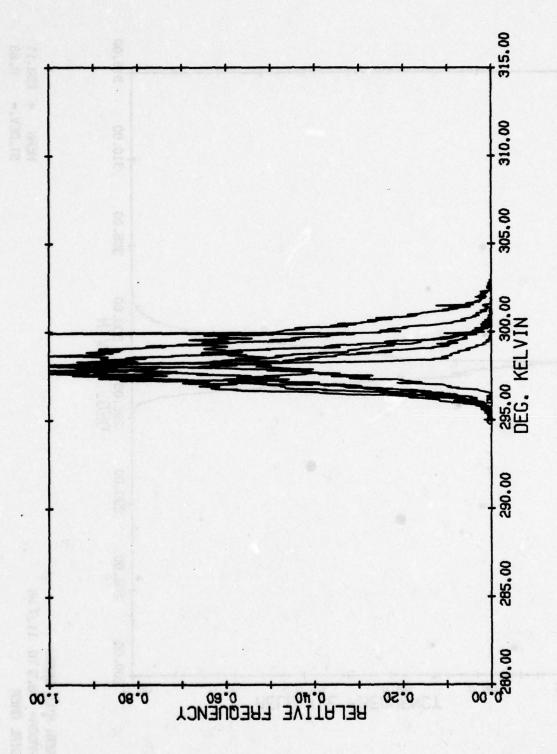


ANER: MILL CREEK LAWBOR- 2.0 TO 2.6 SUBGRERS

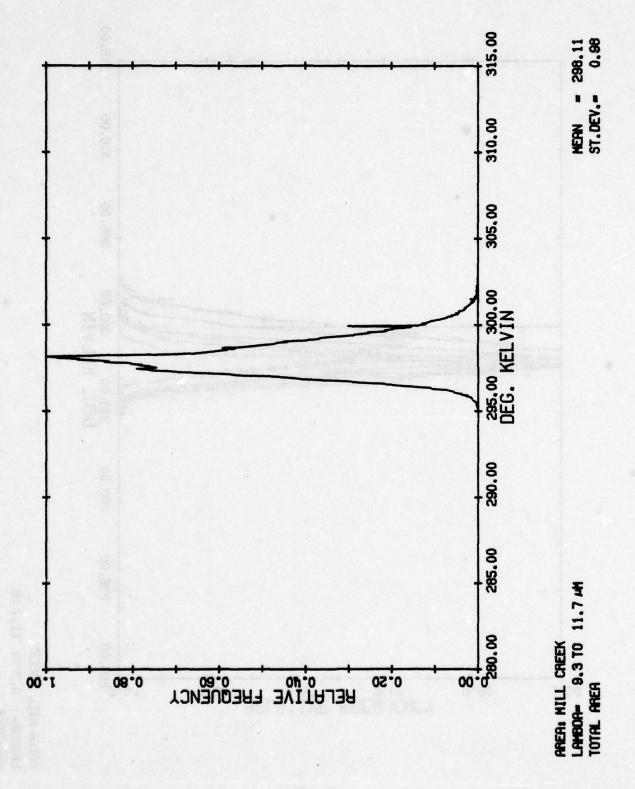


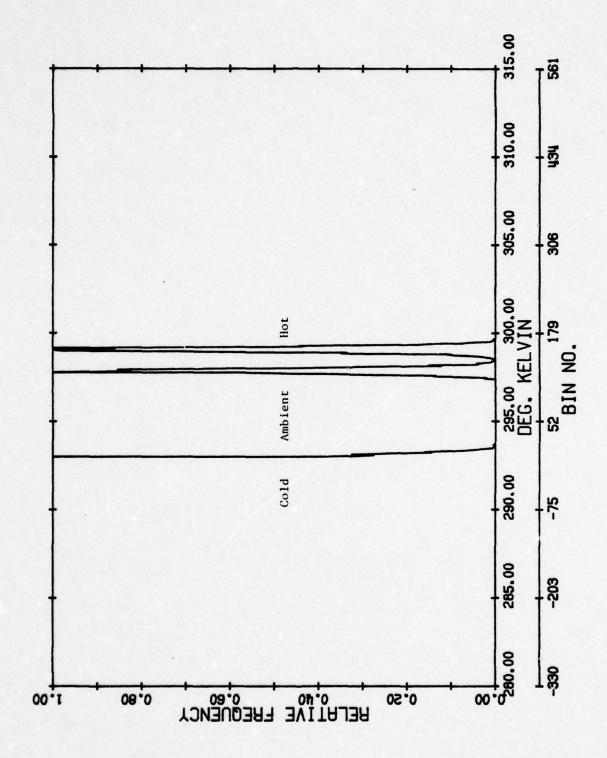


AREA: MILL CREEK LANBOR- 2.0 TO 2.6 JH CALIB. PLATES



AREA: MILL CREEK LAMBOR= 9.3 TO 11.7 M SUBAREAS





AREA: MILL CREEK LAMBOR- 9.3 TO 11.7 M CALIB. PLATES

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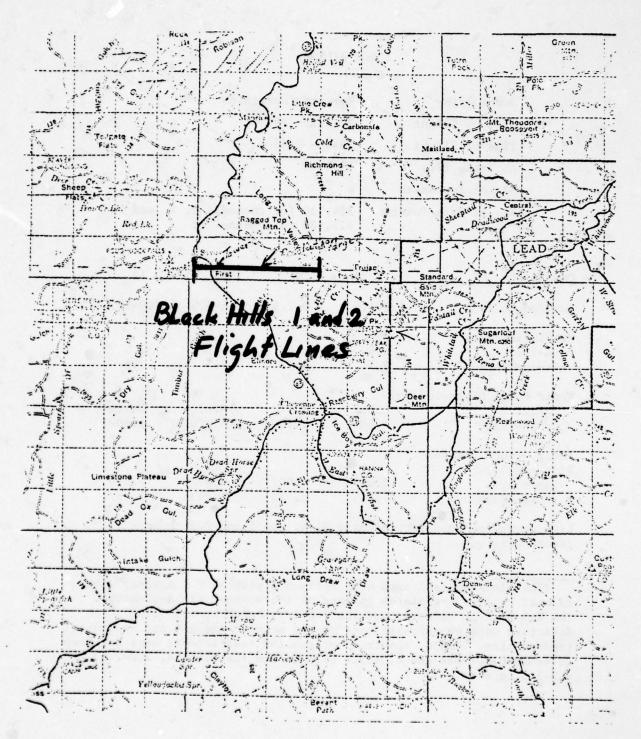
## BLACK HILLS-1\*

Scene Type	Forested Mountains					
Data of Flight	22 July 1969					
Time of Flight	1340 - 1342					
Altitude (Ft)	1500					
No. of Sub-Areas	4					
No. of Data Points	224,130 for channels 2, 4, and 5 425,630 for channel 12					

Channels	2	4	5	12
Wavelength (µm)	1.0-1.4	2.0-2.6	4.5-5.5	8.0-13.5
Resolution (mr)				
In-Track	6.6	6.6	6.6	3.5
Cross-Track	3.5	3.5	3.5	3.5
Nadir Pixel Dimension	on (m)			
In-Track	3.017	3.017	3.017	1.600
Cross-Track	1.600	1.600	1.600	1.600
Nadir Ground Sample				
Distance (m)				
In-Track	3.017	3.017	3.017	1.600
Cross-Track	1.143	1.143	1.143	1.143

Line Averaging used for channels 2, 4, and 5 and for channel 12 independently.

<sup>\*</sup>The Black Hills-1 data were collected with an M-5 scanner with thermal calibration plates in part of the scanner field-of-view. The 8.0-13.5  $\mu$ m detector and the 1.0-1.4, 2.0-2.6, 4.5-5.5 $\mu$ m detectors were on opposite ends of the scanner and are not in spatial registration. Hence, spectral correlation coefficients have not been determined between the 8.5-13.5  $\mu$ m data and the 1.0-1.4, 2.0-2.6, or 4.5-5.5  $\mu$ m data.



MAP OF BLACK HILLS 1



1.0 - 1.4 µm



 $2.0 - 2.6 \mu m$ 

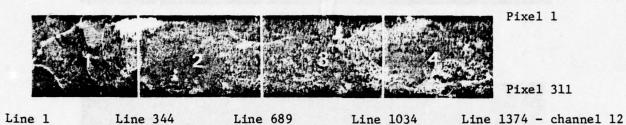


4.5 - 5.5 µm



8.0 - 13.5 µm

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF BLACK HILLS-1



Line 552

Line 732 - channels 2,4,5

Line 369

Line 10

Line 183

SUB-AREAS DEFINED FOR STATISTICS GENERATION IN BLACK HILLS-1. Approximate scene dimensions are 1166 ft (355 m) by 7212 ft (2198 m) for channel 12 and 1166 ft (355 m) by 7146 ft (2178 m) for channels 2, 4, 5. Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area 1 + Sub-area 4

○ Sub-area 2 × Sub-area 5

△ Sub-area 3 ◇ Sub-area 6

BLACK HILLS-1

V
REA
AB
1
ė
SU
O3

	\$1.400 Sept. 18			- 15	2.9443F+n2	2.7077F+00	106649.
					2.94RSE+02	2.63486+00	53940.
3	:		1.000	Ą	1.2177E+02	6.805AE+01	53940.
2. 4	1,000	0.328 1.000	-0.202 0.647 1.000	2	1.9804F+03	6.65715102	53940.
CURPELATION	<b>~</b>	В	5	CHANNEL S	MFAN	SI. DFV.	TUTAL PTS.

BLACK HILLS-1 SUB-AREA 2

The state of the s	2			46.000
2	1.000			
4	0.490 1,000			2
<b>S</b>	-0.291 0.370 1.000	1.000	• •	
CHANNEL S	2	q		1.2
MF AN	1.73735:03	9.7070F+01	2.9417F+02	2.9360F+02
SI. DFV.	5-4031E+02	4.3322F+01	2.0097E+00	2.06795+00
THE DIE	57663	57660	57650	106050.

BLACK HILLS-1 SUB-AREA 3

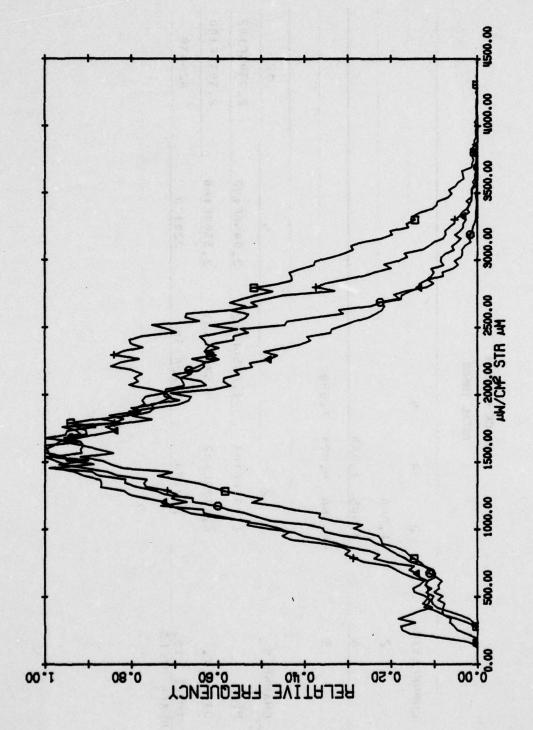
,		1.000	0.29R 1.000	4 5	F+03 9.8521E+01 2.9468F+02 2.9388F+02	1F+02 5.0679E+01 2.2654F+00 2.2431F+00	10. 56730. 56730.
2 4	1.000	0.671 1.000	-0.168 0.298 1.000	2	1.6546F+03	5.95045+02	56730.
CURPELATION.	Castage 1 & 2	N	s	CHANNEL S	MF.AN	S1. DFV.	TUTAL PTS.

BLACK HILLS-1 SUB-AREA 4

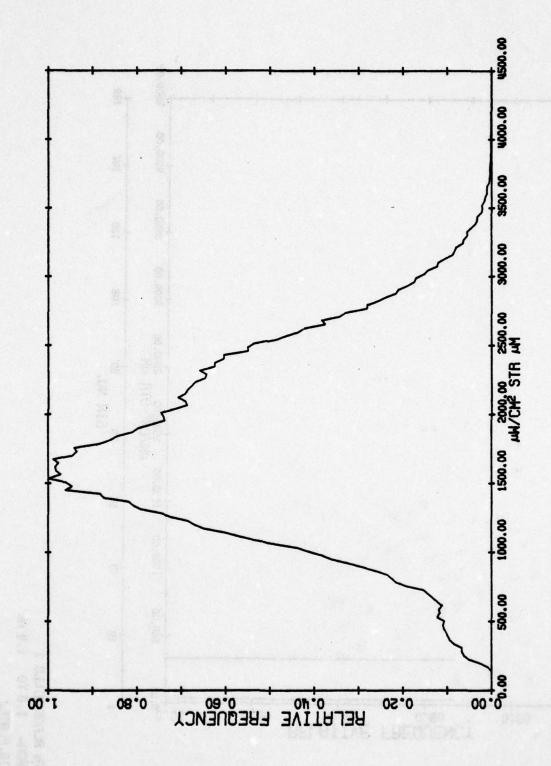
				12	2.93A7F+02	2,3905F+00	105710.
				٦	2.9457F+02	2.3698F+00	55800.
5	, p		1,000	7	1.0581E+02	5.3A26E+01	55800.
2	1,000	0.543 1.00n	-0.084 0.559 1.000	2	1.83041	6.1996E+02	55A60.
CURPELATION		8		CHANNFLS	MEAN	SI. DEV.	TUTAL PIS.

BLACK HILLS-1 TOTAL IMAGE

CHPRELATION	2 4			
2	1,000			
N	0.505 1.000			
٠. د	-0.166 0.49A 1.000	1.000		
CHANNEL S		<b>"</b>		12
MEAN	1.79905+03	1.0556F+02	2,9456E+02	2.9395F+02
SI. DEV.	6.1770F102	5.5347F+01	2.3389E+00	2.38315+00
TUTAL PIS.	051762	224130	224130	425630



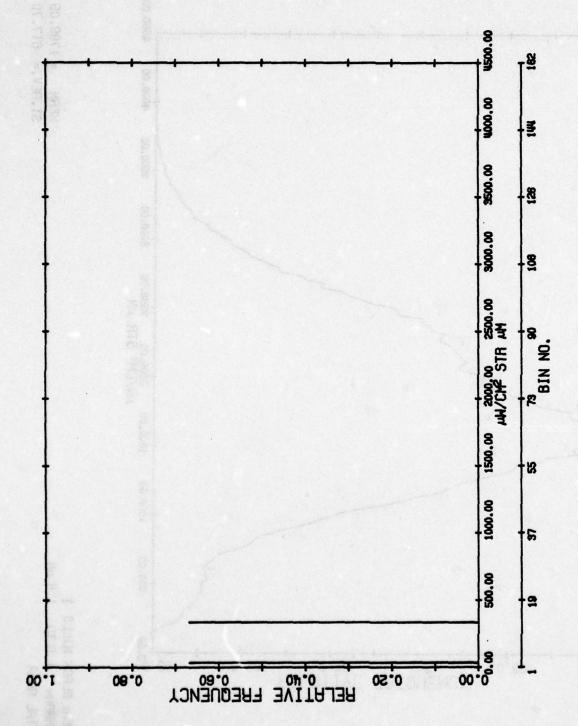
RREA: BLACK HILLS 1 LAMBOR 1.0 TO 1.4 AM SUBPRERS



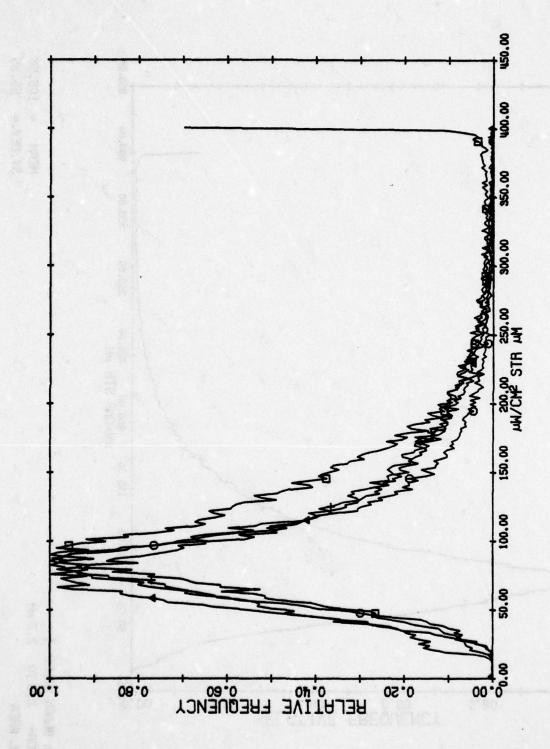
MERN = 1799.05 ST.DEV.= 617.70

APER: BLACK HILLS 1
LANBOR 1.0 TO 1.4 AH
TOTAL AREA

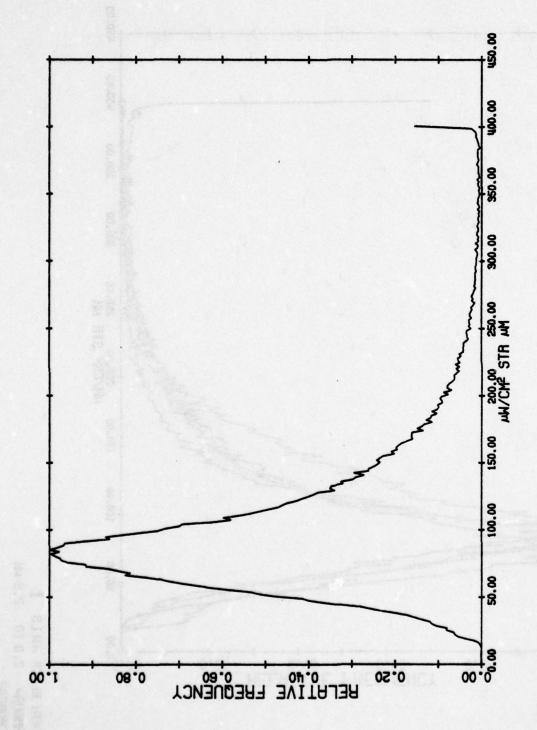
11-117



AREA: BLACK HILLS I LAWBOR 1.0 TO 1.4 AM CALIB.PLATES

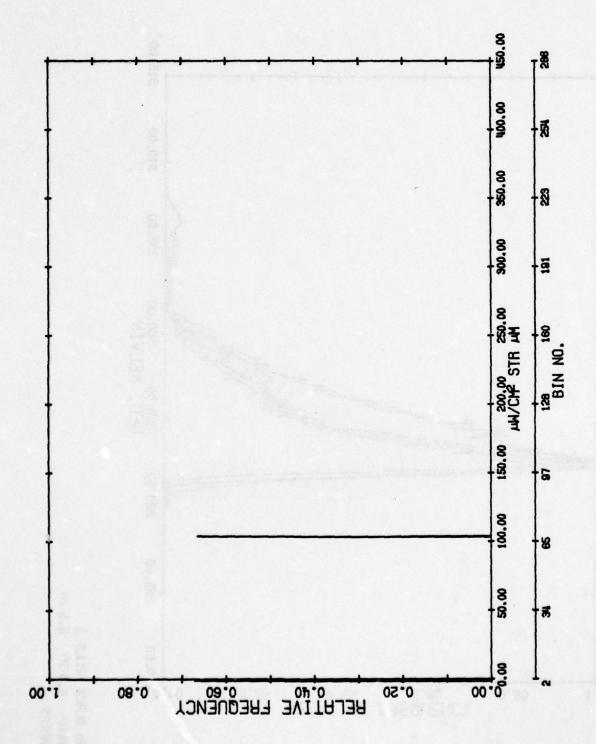


AREA: BLACK HILLS 1 LANBOR 2.0 TO 2.6 AM SUBARERS

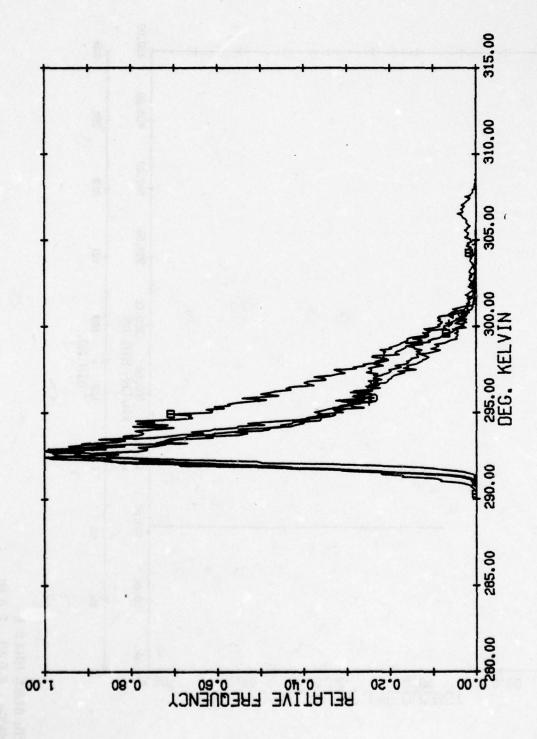


AREA: BLACK HILLS 1 LAMBOR= 2.0 TO 2.6 MM TOTAL AREA

MEAN = 105

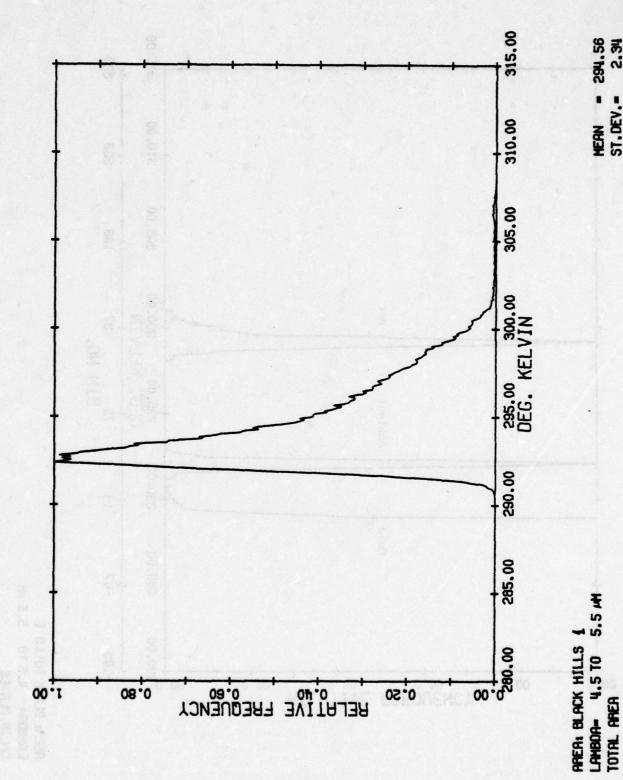


RREA: BLACK HILLS 1 LAMBOR 2.0 TO 2.6 APCRLIB.PLATES



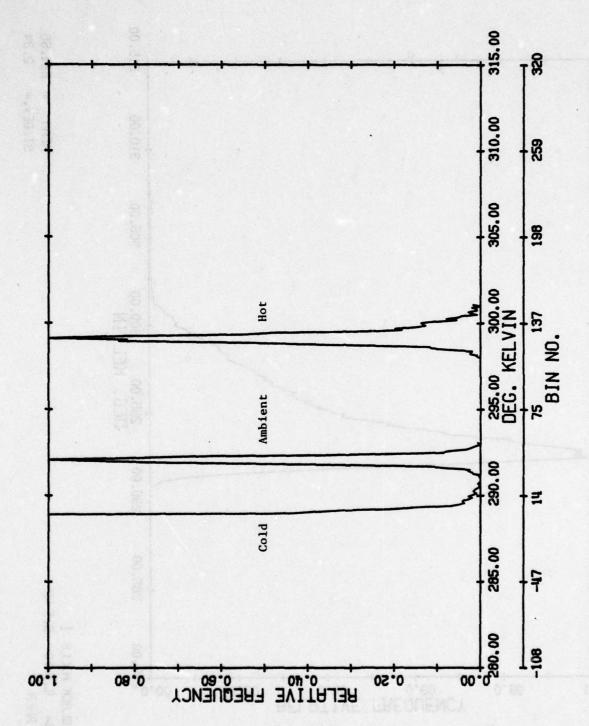
AREA: BLACK HILLS 1 LAMBOR- 4.5 TO 5.5 AM SUBAREAS

ENVIRONMENTAL RESEARCH INST OF MICHIGAN ANN ARBOR IN-ETC F/G 17/5 STATISTICAL ANALYSIS OF TERRAIN BACKGROUND MEASUREMENTS DATA.(U) MAR 77 R SPELLICY , J BEARD , J R MAXWELL N00123-76-C-0708 ERIM-120500-12-F AD-A077 584 UNCLASSIFIED 3 OF 4 ADA 077 584

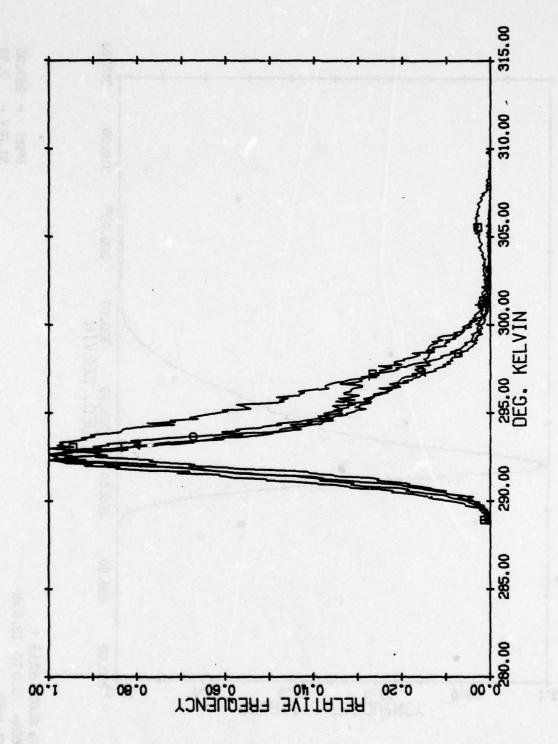


MEAN = 294.56 ST.DEV.= 2.34

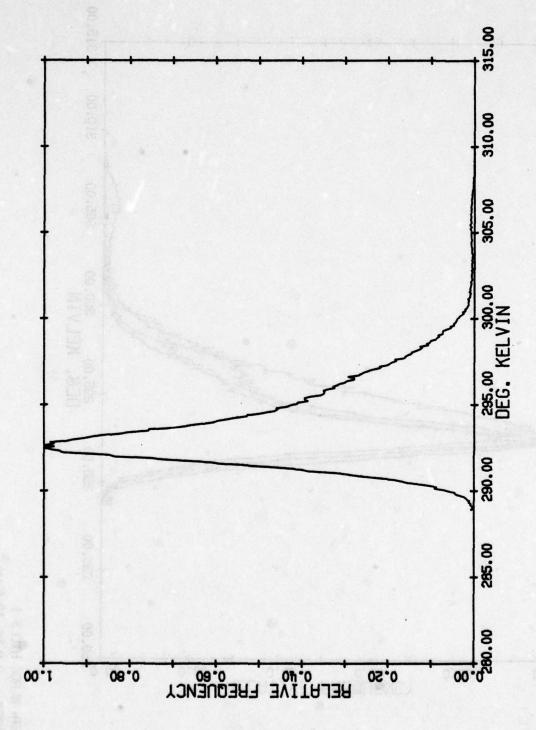
II-123



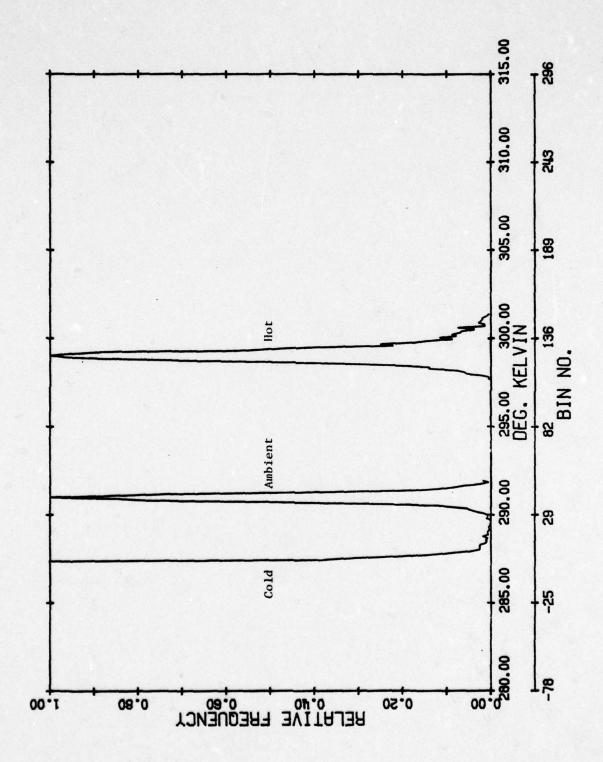
ANEA: BLACK HILLS 1 LANBOR- 4.5 TO 5.5 µ CALIB.PLATES



AREA: BLACK HILLS 1 LAMBOR= 8.0 TO 13.5 AM SUBRRERS



FRER BLACK HILLS 1 LANBOR 8.0 TO 13.5 AM TOTAL FRER



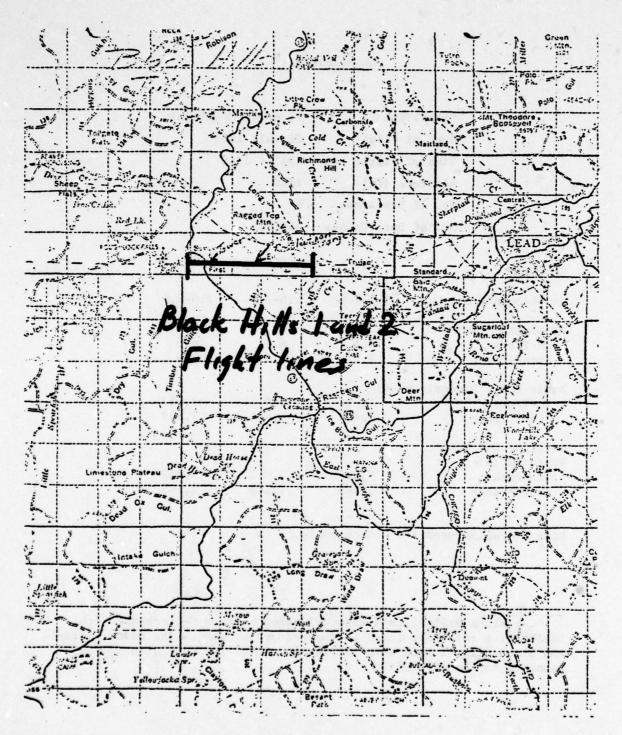
RREA: BLACK HILLS 1 LANBOR= 8.0 TO 13.5 AM CALTR. PLATES

#### BLACK HILLS-2\*

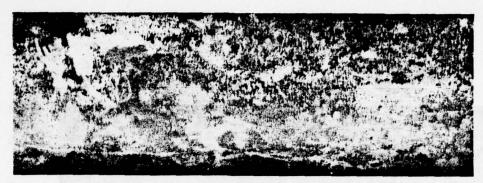
	Scene Type		Forested M	lountains
	Date of Fli	ght	22 July 19	69
	Time of Fli	ight	1340 - 134	2
	Altitude (F	t)	1500	
	No. of Sub-	-Areas	6	
	No. of Data	Points	468,915	
Channels		5	3	7
Wavelength (µm	1.	.0-1.4	1.5-1.8	2.0-2.6
Resolution (mr	•)			
In-Track		6.6	6.6	6.6
Cross-Track		3.5	3.5	3.5
Nadir Pixel Di	mensions (m)			
In-Track		3.017	3.017	3.017
Cross-Track		1.600	1.600	1.600
Nadir Ground S	Sample			
Distance (m)				
In-Track		3.017	3.017	3.017
Cross-Track		1.143	1.143	1.143

Line Averaging used for ALL channels.

<sup>\*</sup>The Black Hills-2 data were collected with an M-5 scanner with calibration reference lamps in the scanner housing. The Black Hills-1 and Black Hills-2 data were collected at the same time with two M-5 scanners in the aircraft.



MAP OF BLACK HILLS-2



 $1.0 - 1.4 \mu m$ 

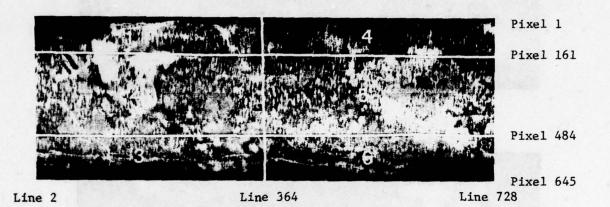


1.5 - 1.8 µm



 $2.0 - 2.6 \mu m$ 

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF BLACK HILLS-2



SUB-AREAS DEFINED FOR STATISTICS GENERATION IN BLACK HILLS-2 IMAGE. Uneven areas were chosen so that Areas 2 and 5 covered the ±20° range suitable for correlation. Approximate scene dimensions are 2418 ft (737 m) by 7206 ft (2195 m). Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area 1 + Sub-area 4

○ Sub-area 2 × Sub-area 5

△ Sub-area 3 ◇ Sub-area 6

# BLACK HILLS-2

## SUB-AREA 1

CHRRELATION	3 5	7	
3	1.000		
5	0.632 1.000		
7	0.925 0.390	1.000	
CHANNEL 2	3	··· 5· ··	
MFAN	11.29576+02	1.6740E+03	8.5542F+01
ST. DEV.	1.7416F+02	1.7239E+02	5.0259E+01
TITAL PTS.	5874n.		58240.

CUPRELATION	3	5	7	
3	1.000			2 ( r v ) ( 3 ( 0 0 ) )
· · · · · · · · · · · · · · · · · · ·	0.562	1.000	10 1	
7	0.871	0.205	1.000	
CHAMNEL'S	. 3		5	<del>-</del>
MEAN	4.9552	F+02	1.7377E+03	1.0016E+02
ST. DEV.	1.2367	FIOS	1.0619F+02	3.3910F+01
THTAL PTS.	11757	2	-117572.	-117572. ···

CURRELATION	3 5	7	
3	1.000		4(3) A. Jawana
5	0.861 1.000		
7	0.864 0.695	1.000	
	minus seeks		
- CHANNELS	3	5	<del>, , , , , , , , , , , , , , , , , , , </del>
MEAN	3.9/143F+02	1.4353E+03	8.1228F+01
ST. DEV.	1.30906+02	1.9175E+02	2.6563F+01
THIAL PIS.	SAGNA.	- 58968	58968.

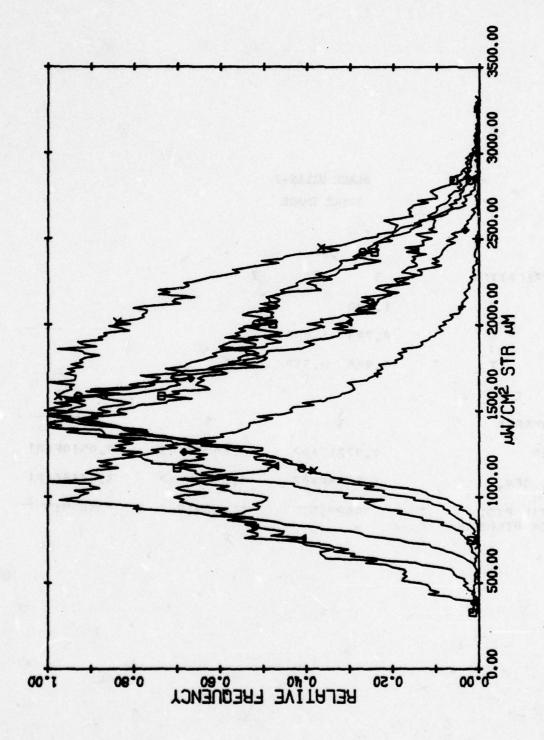
CHRRELAT	LIUN		3	5	7.0.1		-
	3		1.000				
	5	-	718-	1.000	0.8.7.0	-	
	7		0.907	0.557	1.000		
							3 (14/1247)
CHANNEL S	5-	alary)	3		tage of the		<b>7</b>
MEAN			3.3717	7F+02	1.2432E+03		6.7338E+01
ST. DEV	•		1.1846	VL+05	3.1479E+02		2.9141E+01
TUTAL P	rs		- 5808	80.	58080		- 58080. ···

CURRELATION	3		
3	1.000		
5	0.688 1.000	•	** *** **
7	0.921 0.473	1.000	
CHANNEL S	3	5	7
MEAN	5.2011F+02	1.7878F+03	1.0507F+02
SI. DEV.	1.51695+02	4.0922F+02	4.0479F+01
TOTAL PTS.	117240.	117249.	117249.

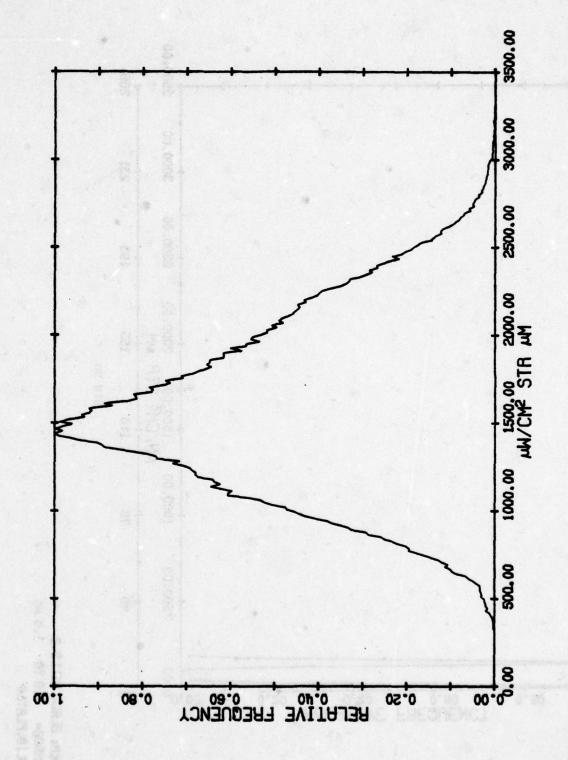
CUPRELATION	3 5	7	
3	1.000		
	0.857 "1.000	Elek 1	-
7	0.892 0.741	1.000	
CHANNELS	.3	5.	7
MEAN	3.8441F+02	1.4170E+03	7.9316F+01
S1. DEV.	1.39215+02	4.3637E+02	3.1003F+01
TUTAL PTS:	58806.	58806	58806.

# BLACK HILLS-2 TOTAL IMAGE

CURREI ATION	3 5	7	
3	1.000		
- 5	0.743 1.000		
7	0.908 0.518	1.000	
CHAMNELS	3	-5	· · · · · · · · · · · · · · · · · · ·
MEAN	4.4721E+02	1.6027F+03	9.0510F+01
ST. DFV.	1.54856+02	1.6380E+02	3.8712E+01
BLACK HILLS 2	46A915	468915	

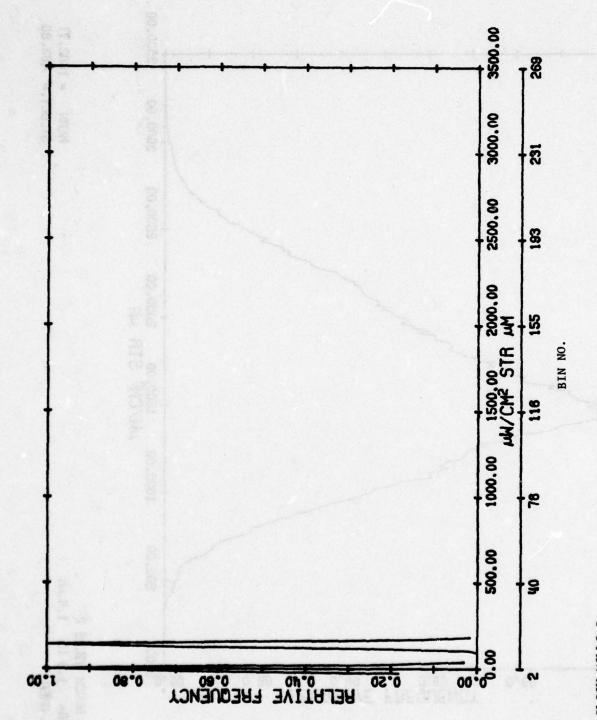


AREA: BLACK HILLS 2
LAMBOR- L.O TO L'LLA
SUBARERS

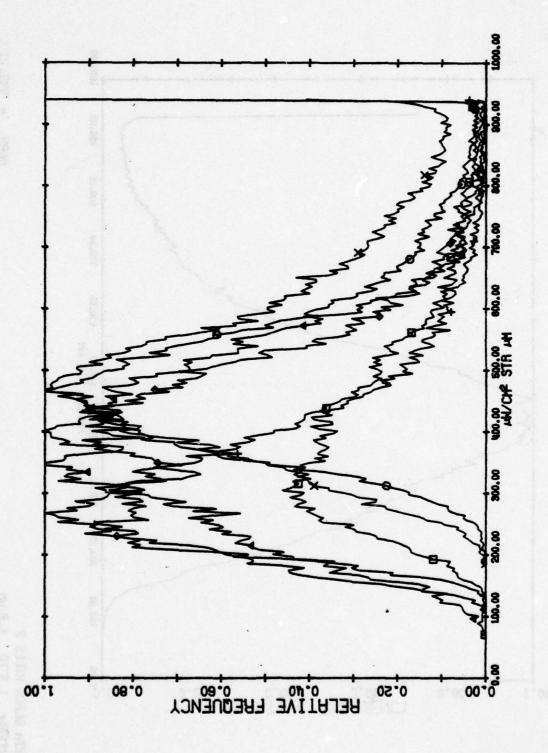


PREAL BLACK HILLS 2 LANBOR- 1.0 TO 1.4.JH TOTAL AREA

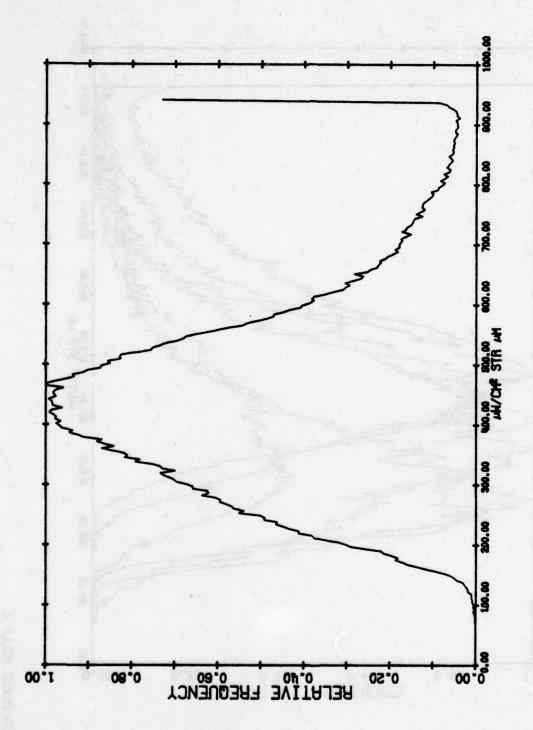
HEAN = 1602,71 ST.DEV.= 463,80



FAMERI BLACK HILLS 2
LANGOR- 1.0 TO 1.4 AN
CALIB.PLATES

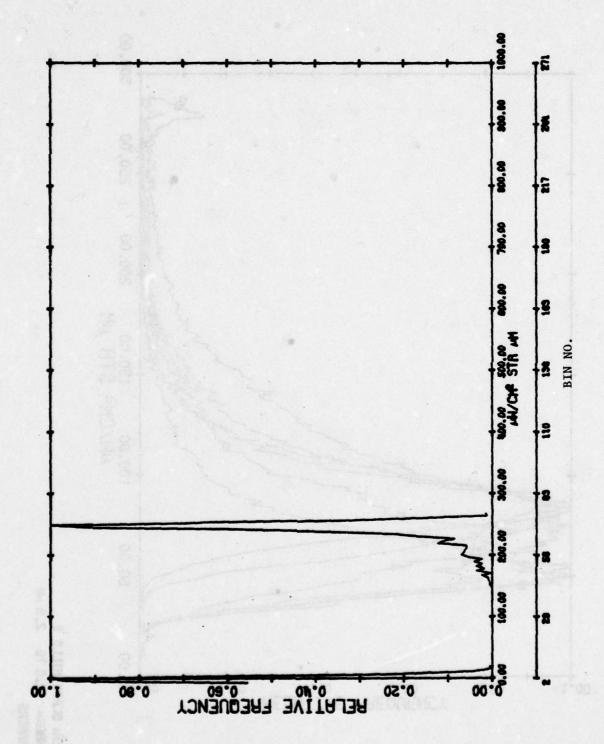


AREA: BLACK HILLS 2 LANBOR 1.5TO 1.8 AH SUBAREAS

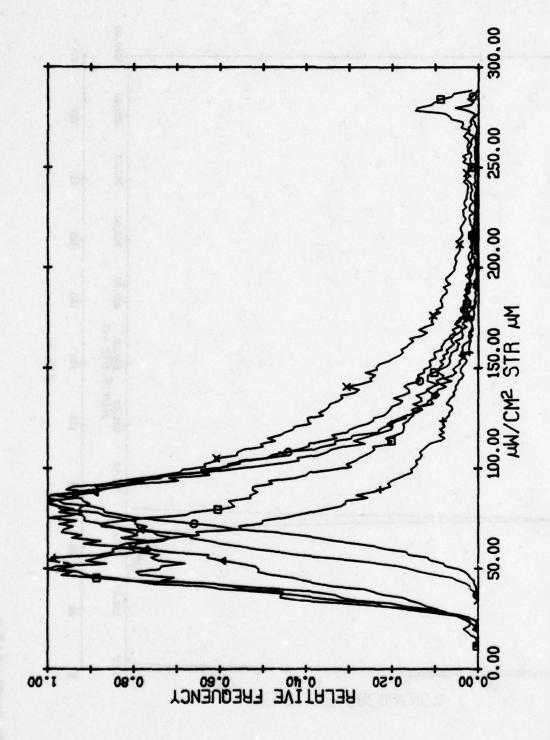


ST. DEV. = 154.85

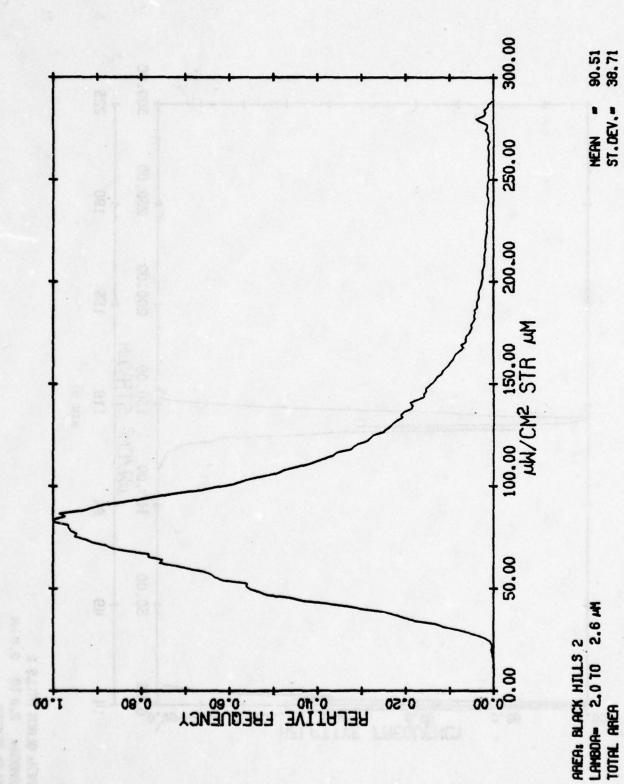
RREA: BLACK HILLS 2 LAMBOR= 1.570 1.8 JM TOTAL AREA



AREA: BLACK HILLS 2
LANDOR- 1.5 TO 1.8 AM
CALIB.PLATES

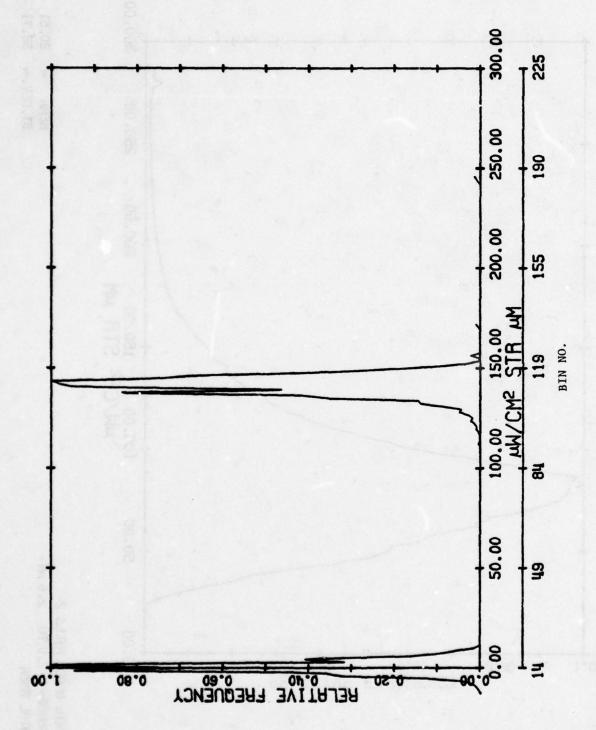


APPER BLACK HILLS 2
LAMBOR= 2.0 TO 2.6 AM
SUBAREAS



NERN ... ST. DEV. ..

II-147



AREA: BLACK HILLS 2 LAHBOA= 2.0 TO 2.6 AM CALIB.PLATES

### PISGAH CRATER\*

Date of Flight	20 Octo	ber 1970		
Date of Flight	30 0000	Der 1970		
Time of Flight	0822 -	0827		
Altitude (Ft)	1000			
No. of Sub-Areas	4			
No. of Data Point		for channe for channe		
nnels	4	1	2	
elength (µm)	11.3-13.5	8.0-10.9	9.4-12.1	
plution (mr) n-Track coss-Track	3.5 3.5	28 21	28 21	

Mountains

Cross-Track 1.067 6.401 6.401

Nadir Ground Sample
Distance (m)

1.067

8.534

8.534

In-Track 1.067 1.067 1.067 Cross-Track 0.762 0.762 0.762

No Line Averaging was used.

Nadir Pixel Dimension (m)

Scene Type

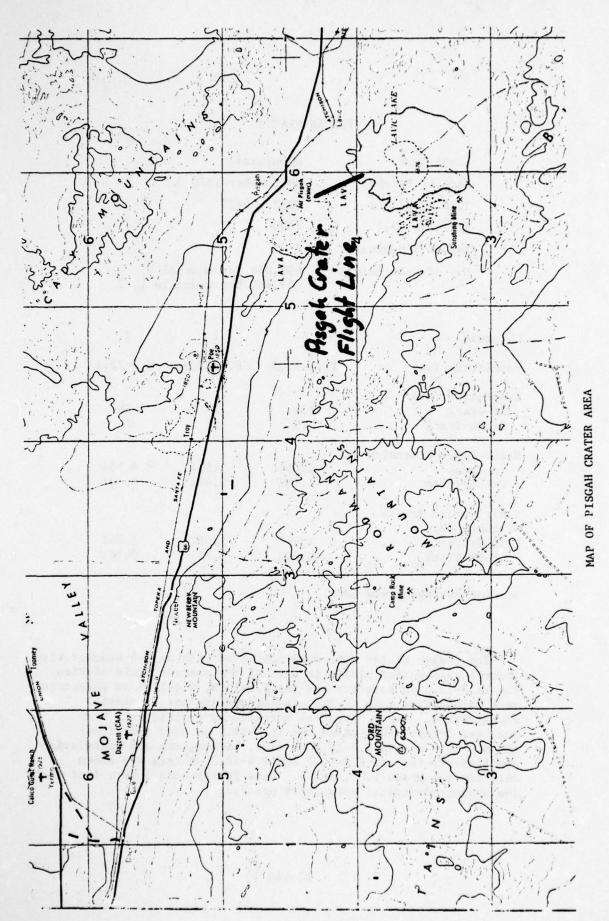
Chan

Wave

Reso

In-Track

<sup>\*</sup>The Pisgah Crater data were collected with an M-5 scanner with thermal calibration plates in part of the scanner field-of-view. The 11.3-13.5  $\mu m$  detector and the 8.0-10.9, 9.4-12.1  $\mu m$  detectors were on opposite ends of the scanner and are not in spatial registration. Hence, spectral correlation coefficients have not been determined between the 11.3-13.5  $\mu m$  data and either the 8.0-10.9 or the 9.4-12.1  $\mu m$  data. Histograms and correlation coefficients for the 8.0-10.9 and 9.4-12.1  $\mu m$  data are shown only for sub-areas 2, 3, and 4. Data in sub-area 1 were lost in the analog-to-digital conversion process.



II-150



11.3 - 13.5 µm



8.0 - 10.9 нт



.4 - 12.1 µm

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF PISCAH CRATER .



Line 1944 - channels 1,2 Line 1988 - channel 4

Line 1450

Line 1491

Line 994 Line 972

Line 486 Line 497

Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key. for channels 1, 2 and 6959 ft (2121 m) by 820 ft (249 m) for channel 4. SUB-AREAS DEFINED FOR STATISTIC GENERATION IN THE PISCAH CRATER IMAGE. Approximate scene dimensions are 6805 ft (2074 m) by 820 ft (249 m)

+ Sub-area 4 □ Sub-area 1

O Sub-area 2

\* Sub-area 5

♦ Sub-area 6

▲ Sub-area 3

Line 1 Line 1

CHANNEL S

4

MEAN

2.9024E+02

ST. DEV.

2.7648E+00

TOTAL PTS.

162519.

·			
CURRELATION		1	
1	1.400		
	0,411 1,000	2030 .72	
) 	\$2010\$\$\delta\.		
CHANNELS	1	2	4
WEAM	2.8018F102	2.8901E+02	2.00115102
SI. DEV.	2,50541100	2.5412E+00	2.87017+00
INTAL PIC.	_ 142809.	142699	162510.

CUPRELATION	1 2	
11	1.000	
2	0.756 1.000	
CHANNEL S	2007	
MEAN	2.8821F+02 2.8805E	
SI. DEV.	2.3843F+00 2.4706E	2.88785+00
THEAL PES.	158922. 158922	162519.

CUPRELATION			
<u>L</u>	1.000		or treaments.
2	0.690 1.000	000.2	
<u> </u>	880.1	1884 A	
CHANNELS .			4
MLAN	2.98445102	2.8824F+92	2.88995+02
31. nev.	2.0618F+00	2,0900E+00	2.71245+00
LUTAL PIS.	158922.	158922	162519.

#### PISGAH CRATER TOTAL IMAGE

CHANNELS

4

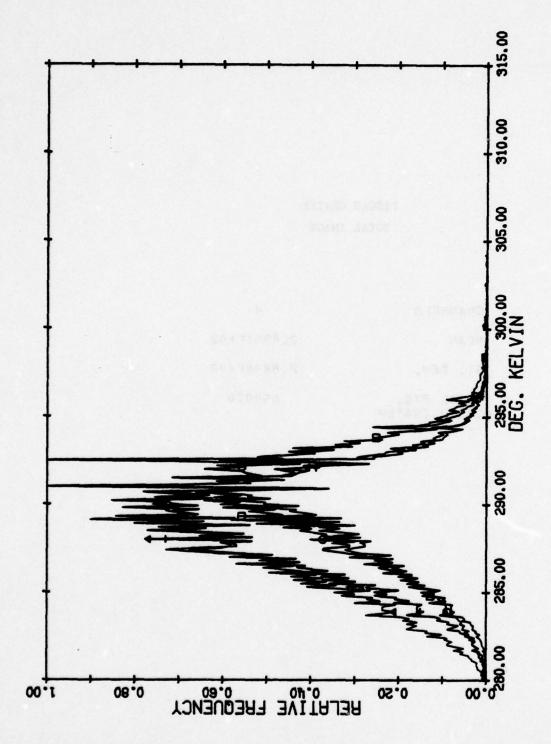
MEAN

2.8951F+02

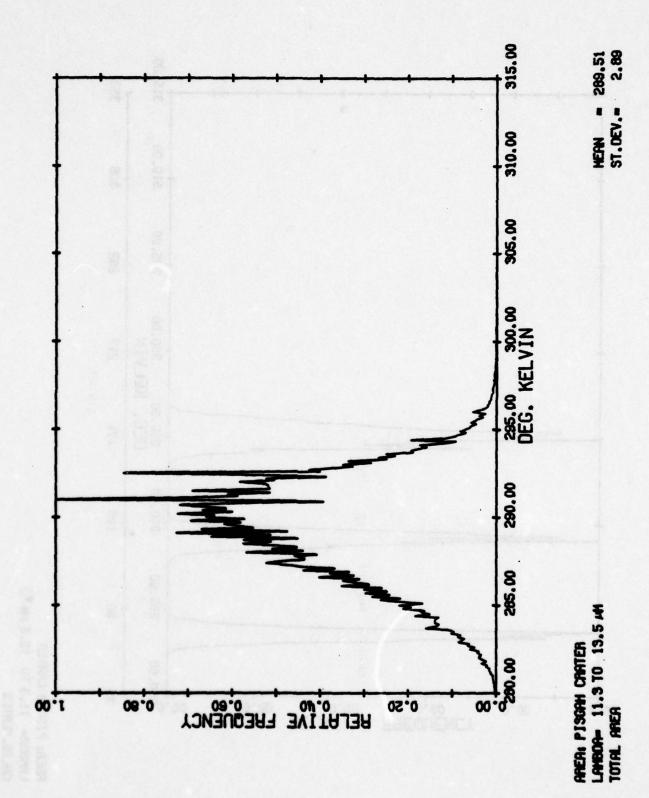
ST. DEV.

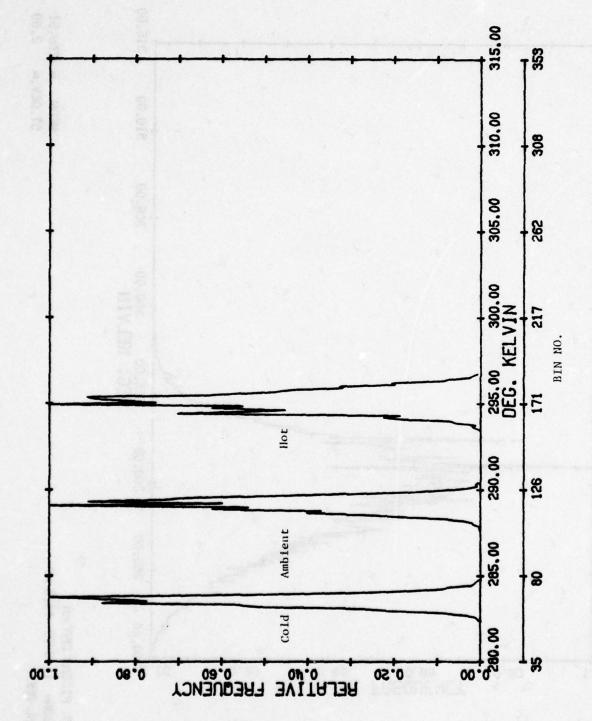
2.8894F+00

TUTAL PTS. PISGAH CRATER 650076

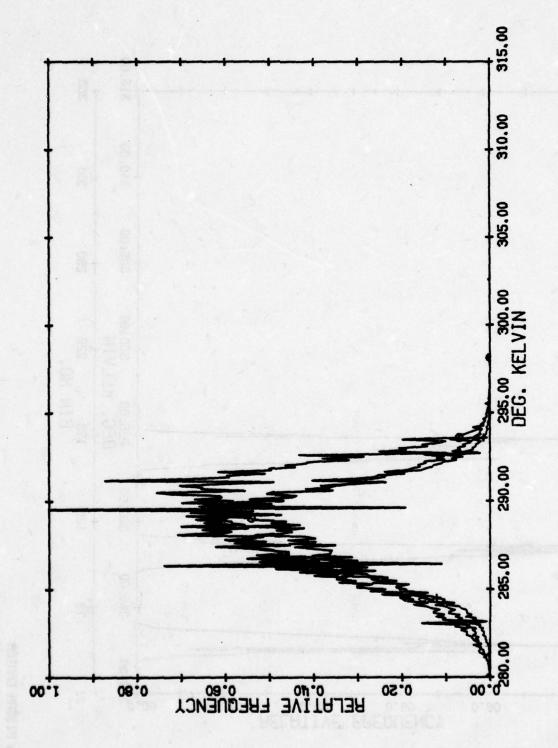


AREA: PISGAH CARTER LAMBOR- 11.3 TO 13.5 JM SUBAREAS

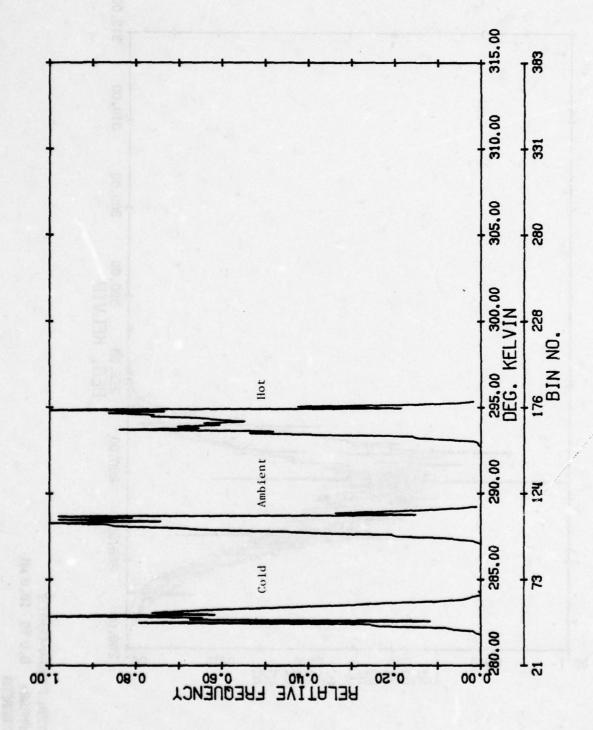




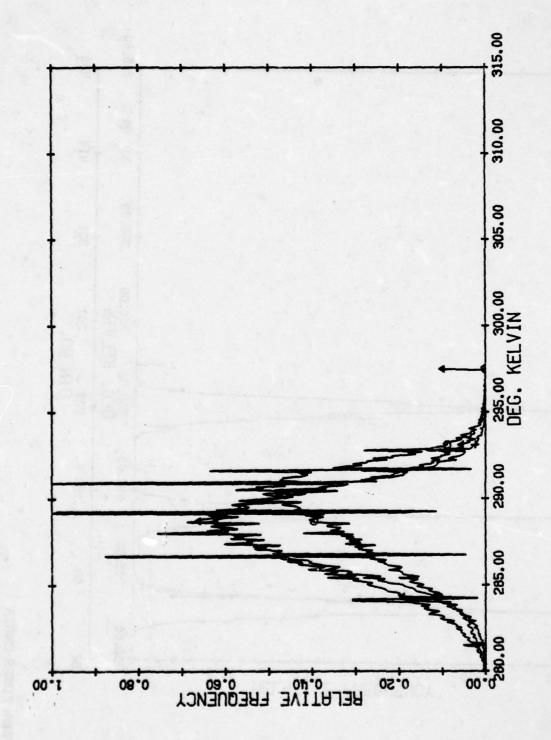
AMERI PISCAN CNATER LAMBOR 11.3 TO 13.5 MM CALIB. PLATES



RREAL PISGRA CRATER LANBOR 8.0 TO 10.9 AM SUBANERS

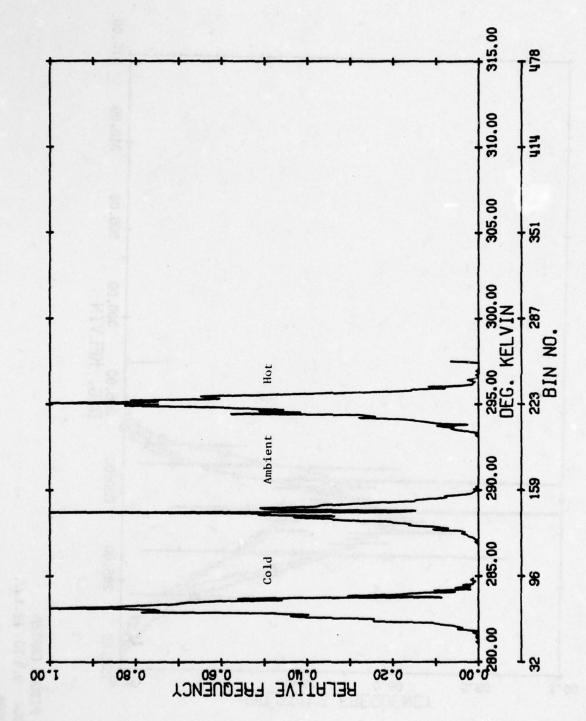


AREA: PISGAH CRATER LAMBOR= 8.0 TO 10.9 JM CALIB.PLATES



AMER: PISGAH CRATER LAMBOR= 9.4 TO 12.1 AM SUBAREAS

0



AREA: PISGAH CRATER LAMBOR= 9.4 TO 12.1 AM CALIB.PLATES

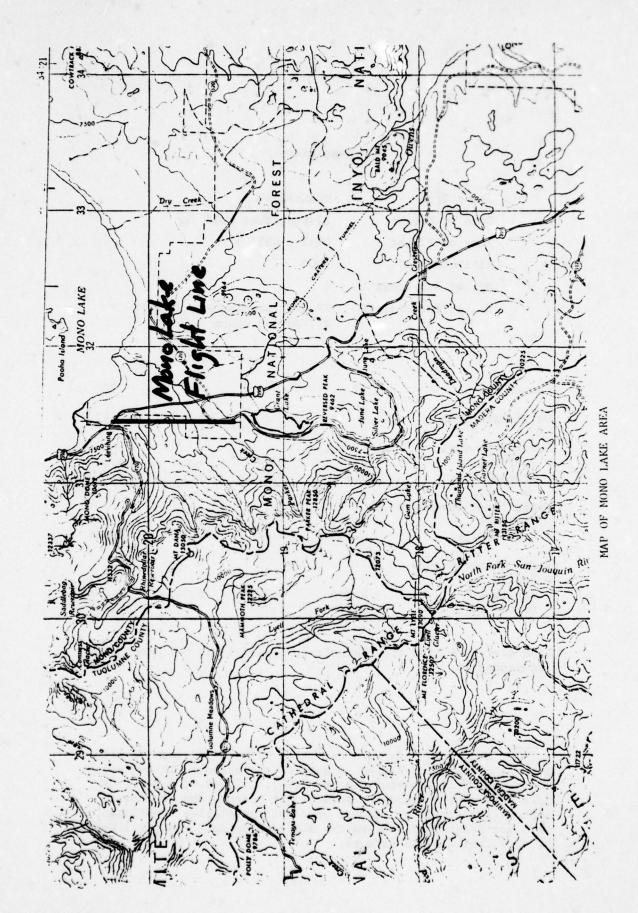
# MONO LAKE\*

Scene Type	Mountains
Date of Flight	23 September 1968
Time of Flight	0952 - 0957
Altitude (Ft)	4000
No. of Sub-Areas	4
No. of Data Points	79,360 for channels 2, 4, 5 87,730 for channel 20

Channels	2	4	5	20
Wavelength (µm)	1.0-1.4	2.0-2.6	4.5-5.5	8.0-13.5
Resolution (mr)				
In-Track	6.6	6.6	6.6	6.6
Cross-Track	3.5	3.5	3.5	6.6
Nadir Pixel Dimension	(m)			
In-Track	8.046	8.046	8.046	8.046
Cross-Track	4.267	4.267	4.267	8.046
Nadir Ground Sample				
Distance (m)				
In-Track	8.046	8.046	8.046	8.046
Cross-Track	3.048	3.048	3.048	3.048

Line Averaging used for channels 2, 4, and 5 and for channel 20 independently.

<sup>\*</sup>The Mono Lake data were collected with an M-5 scanner with thermal calibration plates in part of the scanner field-of-view. The 8.0-13.5  $\mu$ m detector and the 1.0-1.4, 2.0-2.6, 4.5-5.5  $\mu$ m detectors were on opposite ends of the scanner and are not in spatial registration. Hence, spectral correlation coefficients were not determined between the 8.0-13.5  $\mu$ m data and the 1.0-1.4, 2.0-2.6, and 4.5-5.5  $\mu$ m data.



11-166



 $1.0 - 1.4 \mu m$ 



2.0 - 2.6 µm

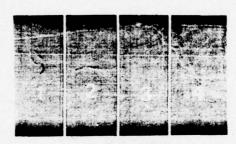


 $4.5 - 5.5 \mu m$ 



8.0 - 13.5 µm

LINE SCAN IMAGES PRODUCED FROM THE VARIOUS INFRARED CHANNELS OF MONO LAKE



Pixel 1

Pixel 311

Line	1	71	142	213	284 -	channel 20
Line	11	67	133	199	266 -	channels 2,4,5

SUB-AREAS DEFINED FOR STATISTICS GENERATION IN THE MONO LAKE IMAGE. Approximate scene dimensions are 7497 ft (2285 m) by 3110 ft (948 m) for channel 20 and 6758 ft (2059 m) by 3110 ft (948 m) for channels 2, 4, 5. Each sub-area as well as the total area have been histogrammed. Histogram plots and their respective sub-areas are identified with the following key:

□ Sub-area	1	+ Sub-area	4
O Sub-area	2	× Sub-area	5
△ Sub-area	3	♦ Sub-area	6

MONO LAKE SUB-AREA 1

CUPREL ATTON	2 4	5	· · · · · · · · · · · · · · · · · · ·	A STATE OF S
2   1.00	1.000	: !		
4	0.931 1.000			
<b>ب</b>	0.842 0.873 1,400	1,000	:	ŧ
* * * * * * * * * * * * * * * * * * * *				
CHANNELS	2	7		8
AL AN	1,97215103	9.1899E+01	2.8510F+02	2. RAINE+112
SI. DFY.	3,5310F+02	1.8744E+#1	1.43246100	1.5897F110
TUTAL PTS.	1798".	17040.	17980.	22010.

MONO LAKE SUB-AREA 2

CHANNELS  CHANNELS  CHANNELS  CHANNELS  S. 0.837 FF 1.000  MIAN  SL. DEV.  20460. 2044. 22044.					
1.000  0.832 0.845 1.000  2.03518173 9.35478401 1.44508102 20460.  2.0460. 20460. 20460.	COPPET AT 1916	See the parties of	. ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) (		
6.901 1.000 6.832 0.835 1.000 2.0351F173 9.3547E+01 2.8533F102 2.8922F 3.2055F102 1.6603F+01 1.4450F+00 1.5805F	2	1.000			
0.832 0.845 1.000 2.0341F173 9.3547E+01 2.8533F1.02 3.2655F102 1.6603F+01 1.4456F+00		0.901 1.prn			
2.0351F173 9.3547E+n1 2.8533F107 3.2655F102 1.6603F+n1 1.4456F+n0	r	0.832 0.845	000*1		
2.0351F173 9.3547E+01 2.8533F102 3.2655F102 1.6603F+01 1.4456F+00 2046C. 20460.		^	=	ď	8
3.2045F102 1.8603F+01 1.4450F+00 5. 2046F. 20460. 20460.		2.03511113	9.3547E+n1	2.8533F102	2.435284.5
200kg. 20460.	SI. DEV.	3.2655F 102	1.4603F+01	1.44561 100	1.5805510
	THIM PTS.	20466	20460.	29464.	224.In.

MONO LAKE SUB-AREA 3

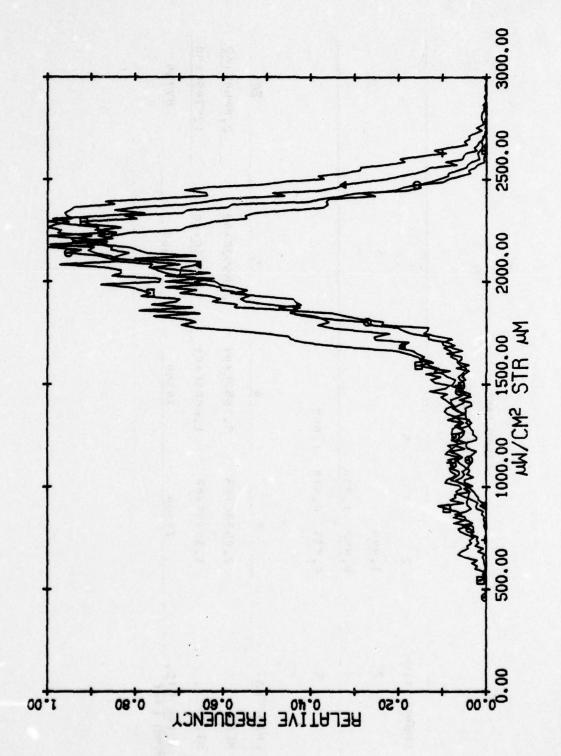
CUPPEL AT ION	2		The state of the s	
~	1.000			
0	0.874 1.000			
æ	0.79% n.75A 1,000	0000*1	:	
CHAMMEL S	2	17	- 5	20
MF.AP.	2.07176+03	10.48198+01	2.85581.102	2. RAGIETOZ
SI. Off.	3,175,46+02	1.40148+01	1.0188F+00	1,24935+00
THIAL PIS.	20466.	20460.	20460.	22010.

MONO LAKE SUB-AREA 4

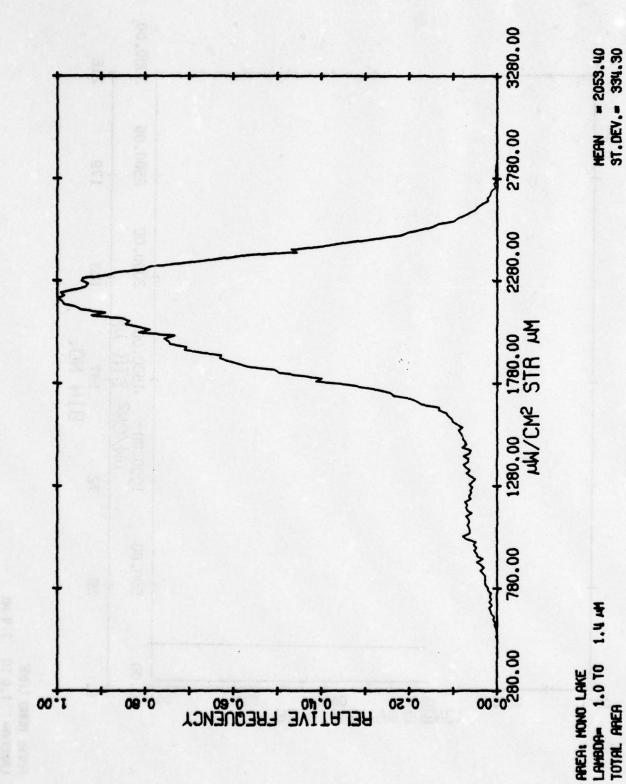
	THE REPORT OF THE PARTY OF THE	3			82	2. A911F+112	1.620AF 100	21760.
		ì		1	\$	2. RG02E+02	1.2632F+00	20460.
			1.000		7	9.8c10E+01	1,53391.401	20460
	1.006	6.856 1.000	0.862 0.780 1.006		٨	2.12485+03	3,29835102	20200
SultV Hadus	2	h	L.		CHAMMEL S	M. A.4	S1. DEV.	TOTAL PIS.

MONO LAKE TOTAL IMAGE

CHRELATION	2	4	. 5		
<b>~</b>	1,000				
, a	50H.0	1.000			
W	0.433 0.414	0.814	0000		i i
n AF		!			
CHAHMFL 3	~		4		20
MEAS	2.05346103	F103	9.4652E+01	2. 8552F+02	2. PM50F102
SI. DEV.	3,3430F+02	F+02	1,68045+01	1.34135+00	1.57895+00
TUTAL PIS.	79560	09	79360	79340	87730

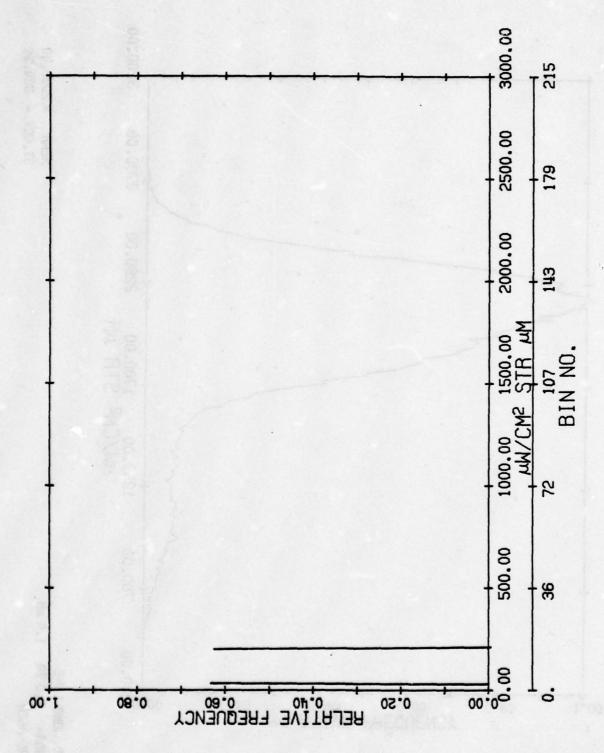


AREA: MONO LAKE
LANBOR 1.0 TO 1.4 AM
SUBAREAS

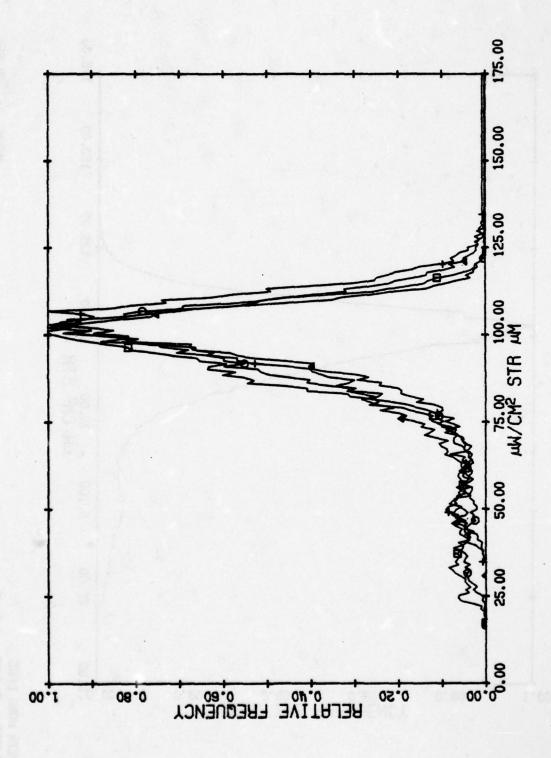


MERN = 2053.40 ST.DEV.= 334.30

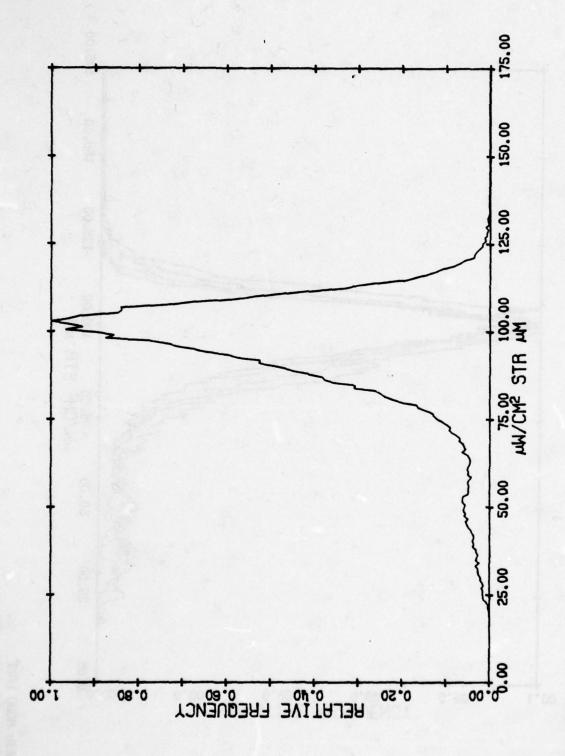
3



AREA: MONO LAKE
LAMBOR= 1.0 TO 1.4 AM
CALIB.PLATES



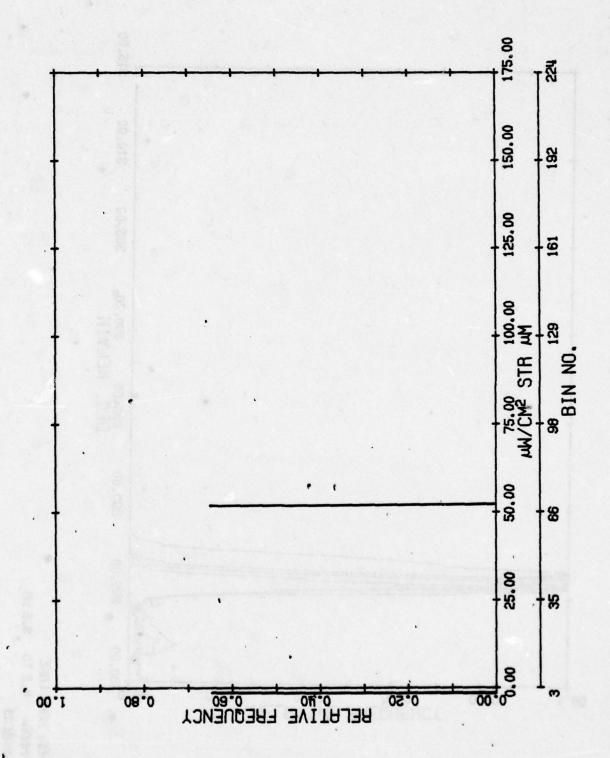
AREA: MONO LAKE
LAMBOR= 2.0 TO 2.6 MM
SUBAREAS



PREA: MONO LAKE LAMBOR= 2.0 TO 2.6 AM TOTAL AREA

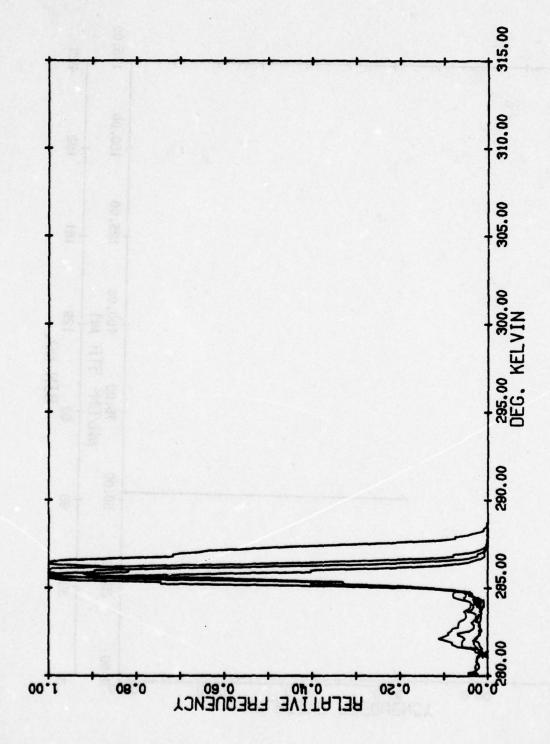
94.65

MERN = ST.DEV.=

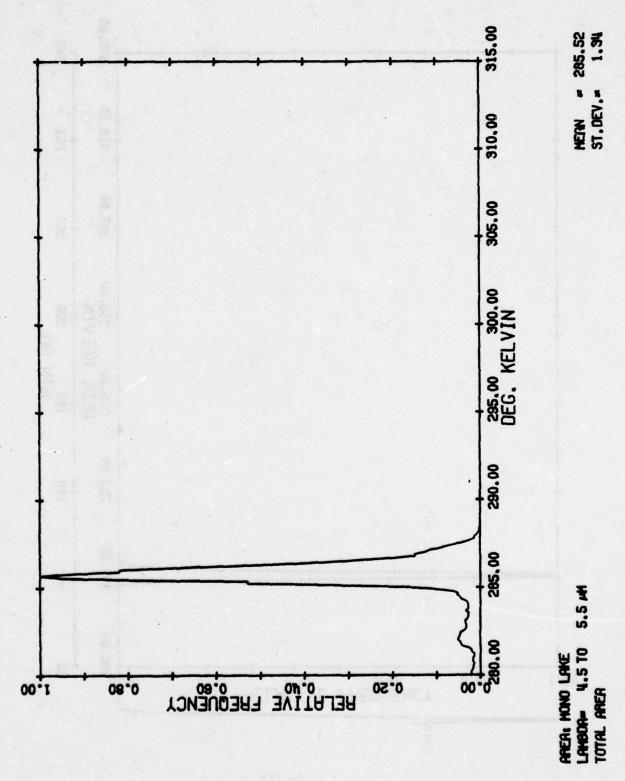


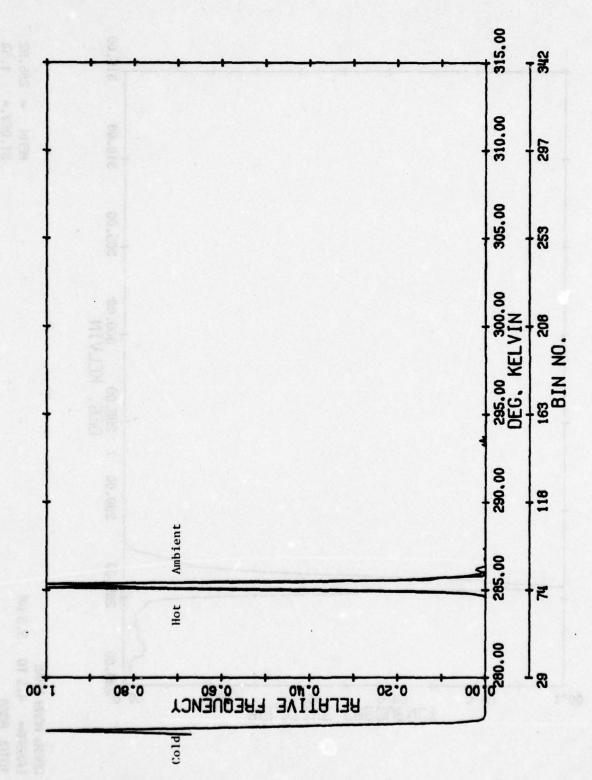
11-179

AREA: HONO LAKE
LAMBOR 2.0 TO
COLTA PLOTES

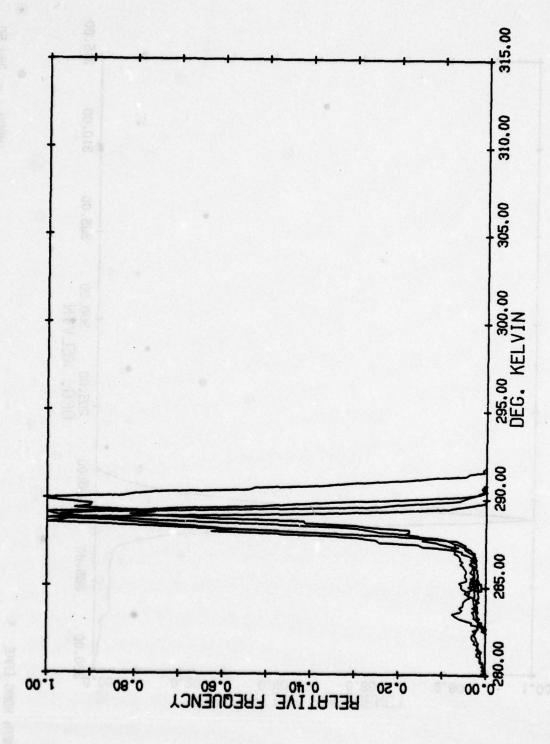


AREA: MONO LAKE LAMBOR- 4.5 TO 5.5 SUBAREAS

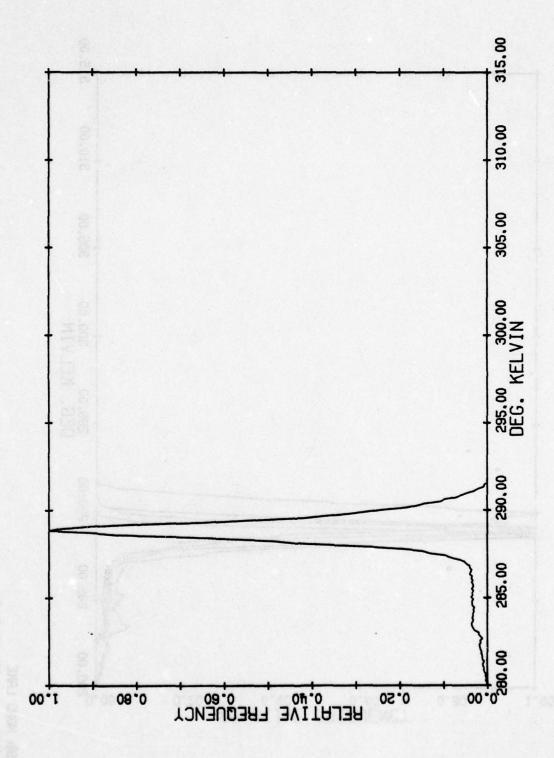




AREA, MONO LAKE LAMBOR- 4.5 TO 5.5 µ CALIB, PLATES

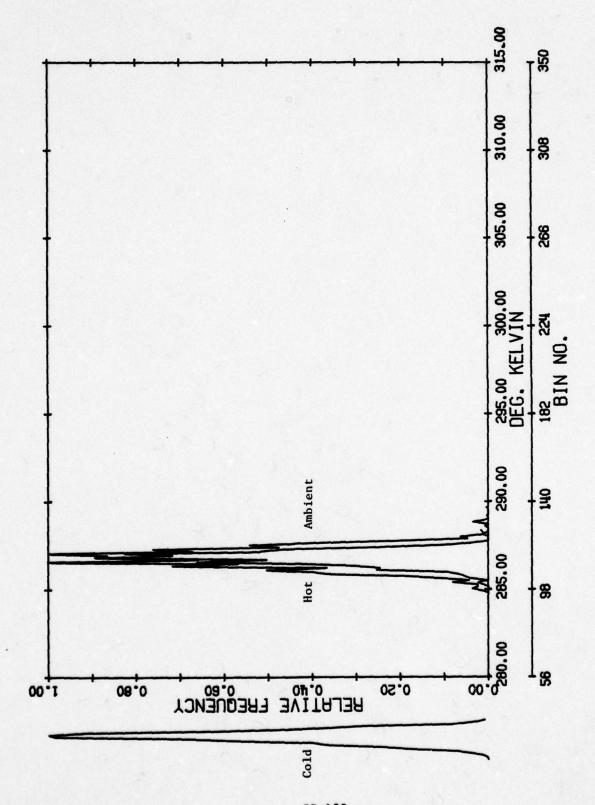


RREA: MONO LAKE
LAMBOR= 8.0 TO 13.5 AM
SUBAREAS



MEAN = 288.50 ST.DEV.= 1.58

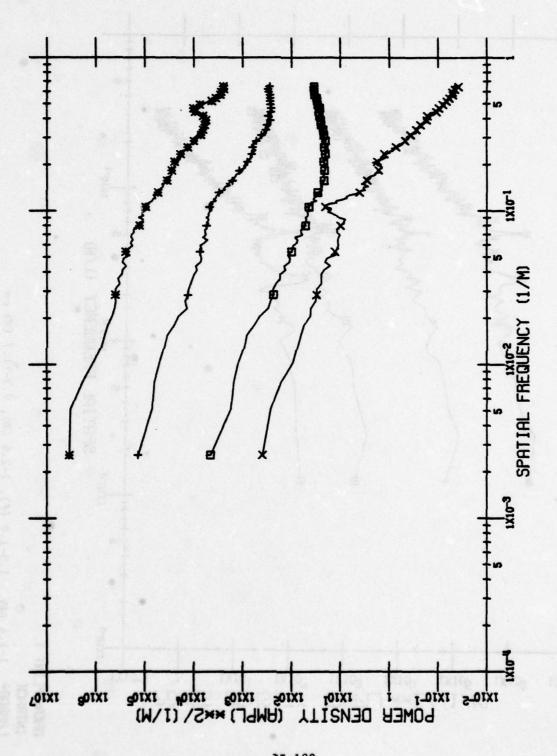
AREA: MONO LAKE LAMBOR= 8.0 TO 13.5 MM TOTAL AREA



AREA: MONO LAKE LAMBOR= 8.0 TO 13.5 MM CALIB.PLATES

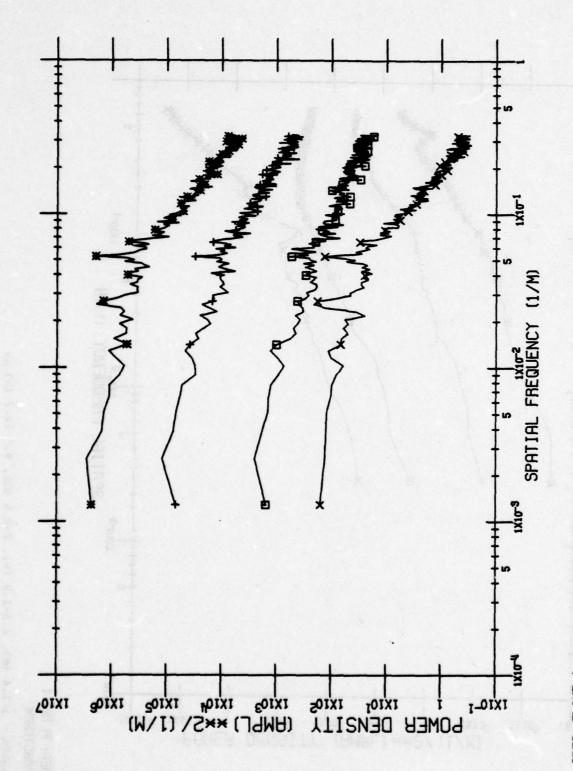
PRECEDING PAGE BLANK-NOT FILMED

WIENER SPECTRA AND AREA/INTENSITY
STATISTICS FOR FLINT-1 AND MILL CREEK

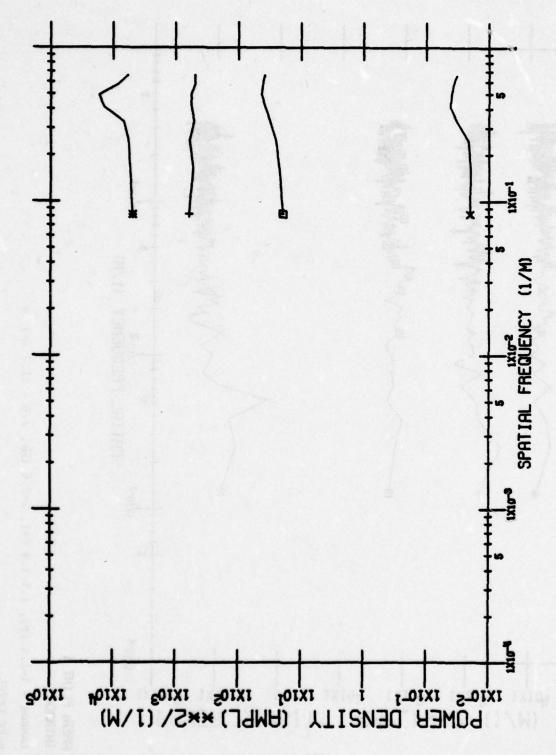


LAMBDA = 1-1.4 (\*), 1.5-1.8 (+), 2-2.6 (Π), 9.3-11.7 (Χ) μm

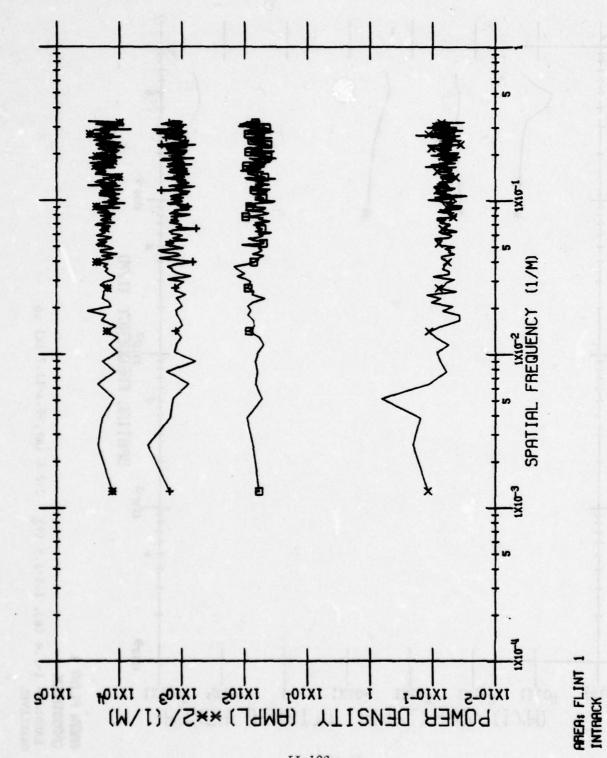
CROSSTRACK



AREA: FLINT 1 INTRACK LAMBOR= 1-1.4 (ж), 1.5-1.8 (+), 2-2.6 (Ш), 9.3-11.7 (X) µm

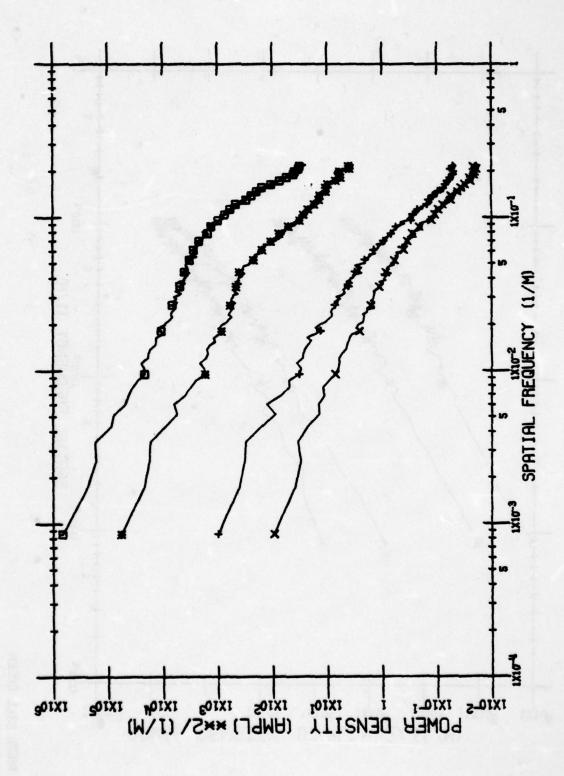


CROSSTRACK
LAMBDA = 1-1.4 (\*), 1.5-1.8 (+), 2-2.6 (E), 9.3-11.7 (X) µm
DARKLEVEL

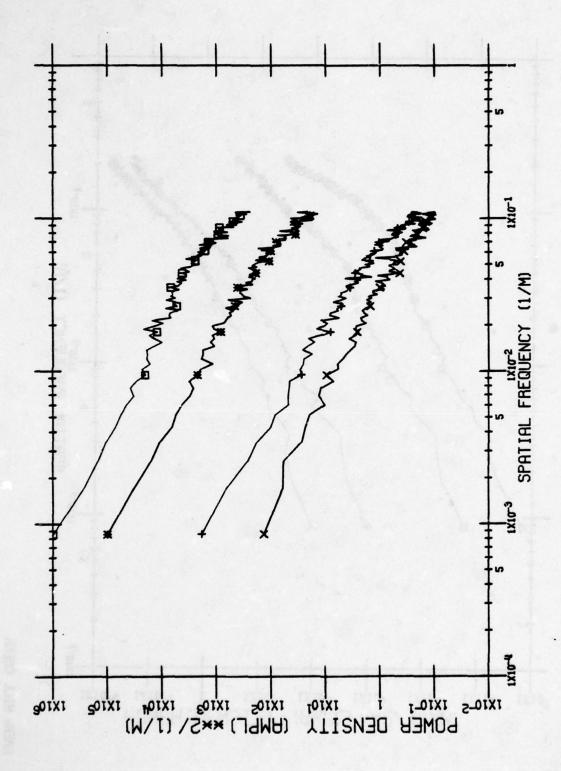


LAMBDA = 1-1.4 (#), 1.5-1.8 (+), 2-2.6 (N), 9.3 - 11.7 (×)  $\mu$  DARK LEVEL

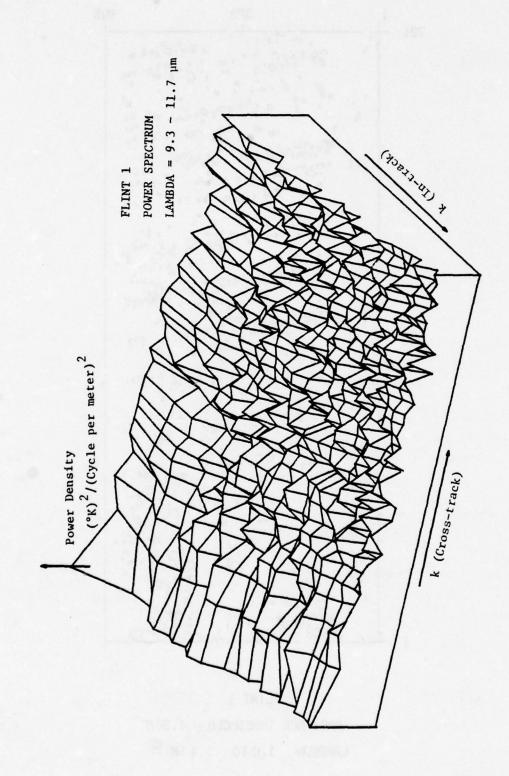
11-192

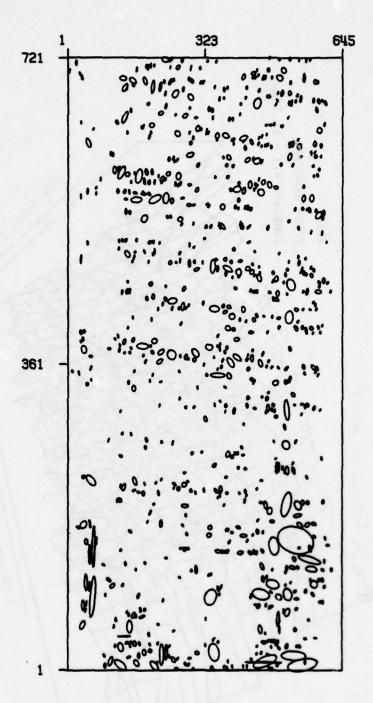


CROSSTRACK
LAMBDA = 1-1.4 (G), 1.5-1.8 (\*\*), 2-2.6 (+), 9.3-11.7 (\*) 1mm



RNEA, MILL CREEK INTRACK LAMBOR= 1-1.4 (E), 1.5-1.8 (#), 2-2.6 ( $\neq$ ), 9.3-11.7 ( $\times$ )  $\mu$ m





FLINT 1

RADIANCE THRESHOLD = 1.500

LAMBOR= 1.0 TO 1.4 MM

FLINT-1

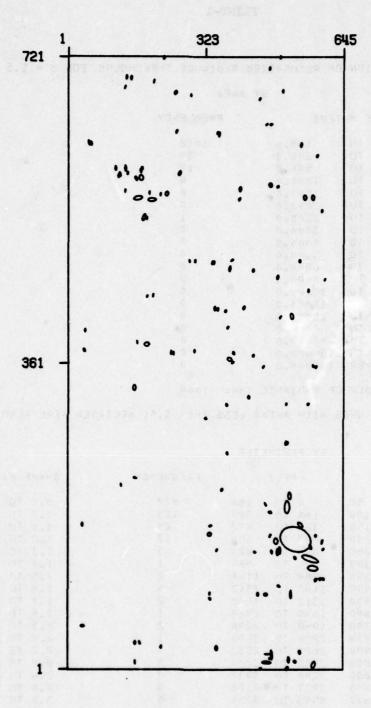
DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR  $\sigma=1.5$ 

-		-	_	
A	, v	R	_	A

SQUARE ME	TERS	FREQUENCY
0.0 TO	100.0	1012
100.0 TO	200.0	30
200.0 TO	500.0	17
500.0 TU	1000.0	4
1000.0 TO	1500.0	0
1500.0 TO	2000.0	0
2000.0 TO	2500.0	1
2500.0 10	3000.0	0 .
3000,0 10	4000.0	0
4000.0 10	5000.0	0
5000.0 TU	6000.0	0
6000.0 TO	8000.0	0
8000.0 10	10000.0	0
10000.0 TO	15000.0	0
15000.0 10	20000.0	0
20000.0 TO	40000.0	0
40000.0 TO	80000.0	0
80000.0 TO	160000.0	0
OVER	160000.0	0

TOTAL NUMBER OF RADIANCE THRE 1064

BY PERIMETER						BY SHAPE			
MET	RS .	FEET		FREQUENCY		SHAPE FACTOR	FREQUENCY		
0 T	50	0 10	164	879		0.0 TO 1.0	2		
50 T	100	164 TO	328	120		1.0 TO 1.1	0		
100 TE	150	328 TO	492	29		1.1 TO 1.2	4.3		
150 T	005 6	492 10	656	17		1.2 10 1.3	41		
200 TI	250	656 TO	820	5		1.3 10 1.4	94		
250 T	300	820 TO	984	1		1.4 TO 1.5	97		
300 T	350	984 TO	1148	2		1.5 TO 1.6	87		
350 T		1148 TO	1312	5		1.6 70 1.7	82		
400 TO	500	1312 10	1640	2		1.7 TO 1.8	94		
500 T	and the second s	1640 TO	1968	1		1.8 TO 1.9	53		
600 T		1968 TO	2296	2		1.9 70 2.0	75		
700 T		2296 TD	2624	1		2.5 OT 0.5	99		
800 T		2624 10	2952	0		2.2 TO 2.4	66		
900 T		2952 TO	3280	0		2.4 10 2.6	52		
	1200	3280 TO	3937	0		2.6 70 2.8	60		
1200 1		3937 TO	0573	0		2.8 TO 3.0	25		
1400 T		4593 TU	5249	0		3.0 TO 3.5	44		
1600 TO		5249 TO	6561	ò		3.5 TO 4.0	55		
- Commence	2000	OVER	6561	0		. OVER 4.0	58		



FLINT 1

RADIANCE THRESHOLD = 2.000

LAMBOA = 1.0 TO 1.4 MM

FLINT-1

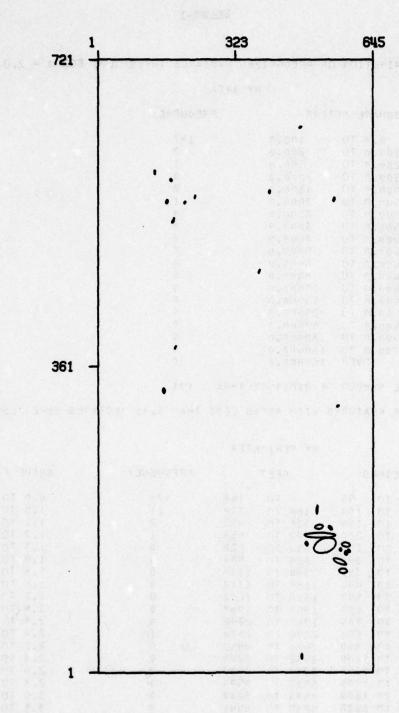
DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR  $\sigma=2.0$ 

#### HY AREA

SQUARE	ME	TERS	FREQUENCY
0.0	TO	100.0	167
100.0	TO	0.005	2
200.0	TO	500.0	1
500.0	TO	1000.0	0
1000.0	TO	1500.0	0
1500.0	TU	2000.0	1
2000.0	TO	2500.0	0
2500.0	10	3000.0	0
3000.0	TU	40,00.0	0
4000.0	10	5000.0	0
5000.0	TU	6900.0	0
6000.0	10	8000.0	0
8000.0	TO	10000.0	0
10000.0	TU	15000.0	0
15600.0	TO	20000.0	0
20000.0	10	40000.0	0
40000.0	TO	80000.0	0
80000.0	TO	150000.0	0
ח	VER	160000.0	0

TOTAL NUMBER OF RADIANCE THRE 191

BY PERIMETER						BY SHAPE .			
МЕ	TE	₹S .		FFFT		FREQUENCY	SHAPE FACTUR	FREQUENCY	
0	TO	50	0	TO	164	176	0.0 TO 1.0	1	
50	TO	100	164	TO	328	11	1.0 70 1.1	0	
100	Th	150	328	TO	492	2	1.1 TO 1.2	8	
150	TO	500	405	TO	656	t	1.2 70 1.3	9	
200	TO	250	656	10	820	0	1.3 TO 1.4	24	
250	TO	300	820	to	984	0	1.4 70 1.5	12	
300	TO	350	984	TO	1118	0	1.5 10 1.6	18	
350	TO	410	1148	TI	1312	0	1.6 TO 1.7	17	
400	TO	500	1312	TO	1640	0	1.7 TO 1.8	18	
500	TT	600	1640	10	1968	0	1.8 TO 1.9	11	
600	10	700	1968	TO	2296	0	1.9 70 2.0	22	
700	TO	800	2296	10	2624	1	2.0 TO 2.2	50	
800	TO	900	2620	TO	2952	0	2.2 TO 2.4	10	
900	TO	1000	2952	Tr	3290	0	2.4 TO 2.6	8	
1000	חד	1200	3280	Tri	3937	0	2.6 TO 2.8	3	
1200	TO	1400	3937	Tn	4593	0	2.8 TO 3.0	1	
1400	TO	1600	1593	Tn	5249	0	3.0 TO 3.5	5	
		2000	5249	Ti	6561	0	3.5 10 4.0	2	
		5000		VER	9591	0	OVER 4.0	1	



FLINT 1

RADIANCE THRESHOLD = 2.500

LAMBDA = 1.0 TO 1.4 MM

FLINT-1

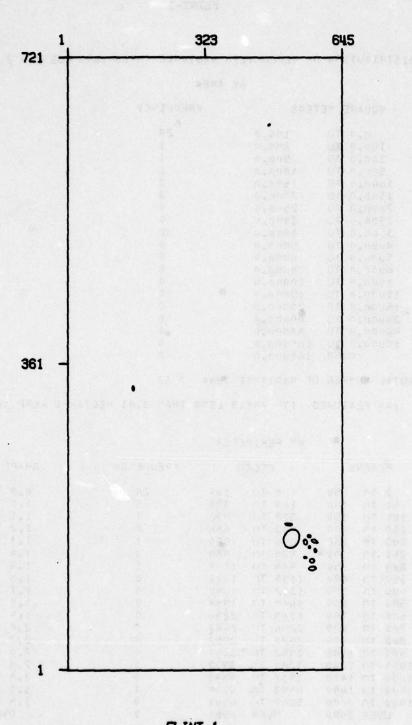
DISTRIBUTION OF RECOGNIZED HADJANCE THRESHOLDS FOR \u00e4 = 2.5

BY AREA

SQUARE	ME	TERS	FRERUENC
0.0	TO	100.0	29
100.0	TU	500.0	1
200.0	TO	500.0	1
500.0	10	1000.0	1
1000.0	TO	1500.0	0
1500.0	10	2000.0	0
2000.0	10	2500.0	0
2500.0	10	3000.0	0
3000.0	TO	4000.0	0
4000.0	TO	5000.0	0
5000.0	10	6000.0	0
6000.0	10	8000.0	0
8000.0	TO	10000.6	0
10000.0	TO	15000.0	0
15000.0	TO	20000.0	. 0
20000.0	10	40000.0	0
40000.0	TO	80000.0	0
80000.0	10	160000.0	0
יח	FR	160000.0	0

TOTAL NUMBER OF PADIANCE THRE 32

HY PERIMETER						BY SHAPE			
ME.	TER	s	,	FEET		FREQUENCY	SHAPE FACTOR	FREQUENCY	
0	TO	50	0	TO	164	24	0.0 TO 1.0	0	
50	TO	100	164	TO	328	5	1.0 TO 1.1	0	
100	Tn	150	328	TO	492	1	1.1 10 1.2	1	
150	רז	200	492	TO	656	0	1.2 to 1.3	5	
200	TO	250	656	TO	058	1	1.3 10 1.4	5	
250	רז	300	820	TO	984	0	1.4 10 1.5	4	
	חד	350	984	TI	1148	1	1.5 70 1.6	5	
350	TO	400	1148	TO	1312	0	1.6 70 1.7	1	
	TO	500	1312	TO	1640	0	1.7 70 1.8	3	
	TO	600	1640	TO	1968	0	1.8 Tn 1.9	1	
	מז	700	1968	TO	2296	0	1.9 10 2.0	4	
700	רז	800	2296	10	2624	0	2.0 10 2.2	5	
800	TO	900	2624	10	2952	0	2.2 10 2.4	4	
900	חז	1000	2952	TO	3240	n	2.4 10 2.6	. 0	
1000	TO	1200	3280	TO	3937	0	2.6 10 2.8	1	
1200	TO	1400	3937	TO	4593	0 .	2.9 70 3.0	1	
	רז	1600	4593	TO	5240	0	3.0 TU 3.5	3	
1600			5249		6501	0	3.5 TO 4.0	1	
		2000		VER	6561	0	OVER 4.0	0	



FLINT 1

RADIANCE THRESHOLD = 3.000

LAMBOR = 1.0 TO 1.4 AM

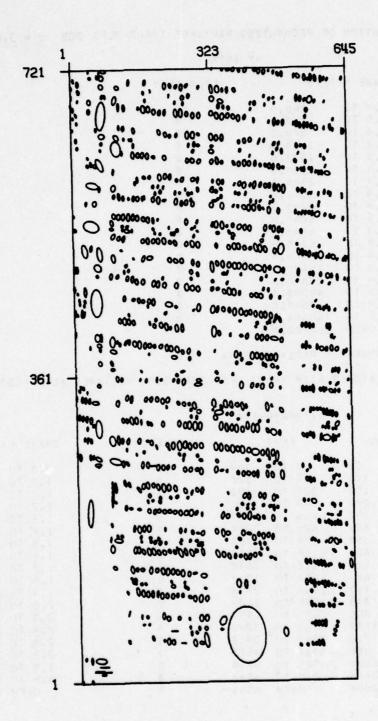
FLINT-1

DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR  $\sigma=3.0$  BY AREA

. 75	TERS	FREDUENCY
TO	100.0	16
TO	200.0	0
TO	500.0	0
TO	1000.0	1
10	1500.0	0
TO	2000.0	0
10	2500.0	0 .
10	3000.0	0
10	4000.0	0
TO	5000.0	0
TU	6000.0	0
10	8000.0	0
TO	10000.0	0
10	15000.0	0
10	20000.0	0
10	40000.0	0
10	80000.0	0
10	160000.0	0
VER	160000.0	0
	10 10 10 10 10 10 10 10 10 10 10 10 10 1	TO 100.0 TO 200.0 TO 200.0 TO 500.0 TO 1000.0 TO 1500.0 TO 2000.0 TO 2500.0 TO 3000.0 TO 4000.0 TO 6000.0 TO 6000.0 TO 10000.0

TOTAL NUMBER OF PADJANCE THRE 17

BY PERIMETER					BY SH	APE
METE	METERS FEET			FREQUENCY	SHAPE FACTOR	FREQUENCY
0 TC	50	o TO	164	12	0.0 TO 1.0	0
50 TO	100	164 10	328	4	1.0 70 1.1	0
100 T	150	328 TO	492	0	1.1 70 1.2	2
150 TC	200	492 10	656	0	1.2 TO 1.3	1
200 T		656 TO	820	0	1.3 TO 1.4	3
250 T		820 TO	984	0	1.4 TO 1.5	1
300 Tr		984 10	1148	0	1.5 10 1.6	3
350 T		1148 TO	1312	0	1.6 70 1.7	0
400 TO	-	1312 TO	1640		1.7 10 1.8	0
500 T		1649 TO	1968	ó	1.8 10 1.9	0
600 TO		1968 TO	2296	0	1.9 TO 2.0	1
700 TO		07 965S	2624	0	2.0 10 2.2	2
800 T		2624 TO	2952	0	2.2 TO 2.4	2
900 Tr		2952 TO	3290	o de la companya de l	2.4 10 2.6	0
	1200	3280 TO	3937	Ŏ	8.5 07 8.5	0
	1400	3937 10	4593	Ŏ	2.8 TO 3.0	
	1600	4593 TO	5249		3.0 TO 3.5	•
	1 10 10 10 10			. 0		0
1600 TO		5249 Til	6561	<u> </u>	3.4 10 4.0	
DAF	5000	OVER	6561	0	OVER 4.0	



FLINT 1
TEMPERATURE THRESHOLD = 1.500
LAMBOR= 9.3 TO 11.7 MM

FLINT-1

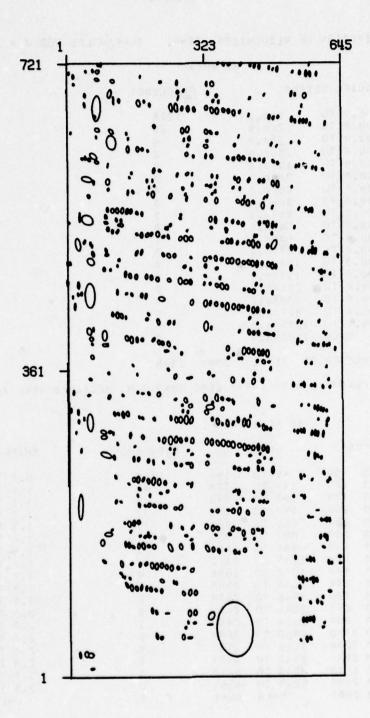
DISTRIBUTION OF RECOGNIZED TEMP. THRESHOLDS FOR 0 = 1.5

BY AREA

ME	TERS		FREQUENCY
TO	100.0		1278
TO	200.0		20
TO	500.0		4
TI	1000.0		5
TU	1500.0		0
10	2000.0		0
TO	2500.0		0 .
TO	3000.0		0
TO	4000.0		0
TO			0
TO	6000.0		1
TO	8000.0		0
TO	10000.0		0
TO	15000.0		0
TU	20000.0		0
TO	40000.0		0
TO	80000.0		0
TO	160000.0		0
ER	160000.0		0
	TO T	TO 200.0 TO 500.0 TO 1000.0 TO 1500.0 TO 2500.0 TO 2500.0 TO 3000.0 TO 4000.0 TO 5000.0 TO 6000.0 TO 10000.0 TO 15000.0 TO 2000.0 TO 3000.0 TO 15000.0 TO 15000.0 TO 15000.0 TO 2000.0 TO 3000.0	TO 100.0 TO 200.0 TO 200.0 TO 500.0 TO 1000.0 TO 1500.0 TO 2500.0 TO 3000.0 TO 4000.0 TO 5000.0 TO 6000.0 TO 10000.0

TOTAL NUMBER OF TEMP. THRE 1305

BY PERIMETER									BY SHAPE			
M	ETEI	es .		FET			FREQUENCY		SHAPE FA	CTOR	FREQUENCY	
0	TO	50	0	TO	164		1254		0.0 TO	1.0	3	
50	Ta	100	154	TO	328		42		1.0 10	1.1	3	
100	10	150	328	TO	492		5		1.1 TO	1.2	104	
150	TO	200	492	TO	656		2		1.2 TO	1.3	186	
200	TO	250	656	TO	620		0		1.3 10	1.4	339	
250	Th	300	820	TO	984		1		1.4 TO	1.5	238	
300		350	984	TO	1148		0		1.5 10	1.6	167	
350		400	1148	TO	1312		0		1.6 10	1.7	96	
400	TO	500	1312	TO	1640		0		1.7 TO	1.8	56	
	TO	600	1640	TO	1968	,	0		1.8 TO	1.9	31	
600	TO	700	1968	TO	2296		0		1.9 TO	2.0	26	
700	TO	800	2296	TO	2624		0		OT 0.5	2.5	33	
800	TO	900	2624	TO	2952		1		2.2 10	2.4	10	
900		1000	2952	TO	3240		0		2.4 10	2.6	4	
1000	TT	1200	3280	TO	3937		0		2.6 TO	2.8	. 3	
1200	TO	1400	3937	Tri	4593		0		2.8 TO	3.0	4	
1400	TO	1600	4593	TO	5249		0		3.0 TO	3.5	1	
		2000	5249		6561		0		3.5 To	4.0	1	
		2000		FR	6561		0		OVER	CHARLES TO SECOND	0	



FLINT 1
TEMPERATURE THRESHOLD = 2.000
LAMBDA = 9.3 TO 11.7 MM

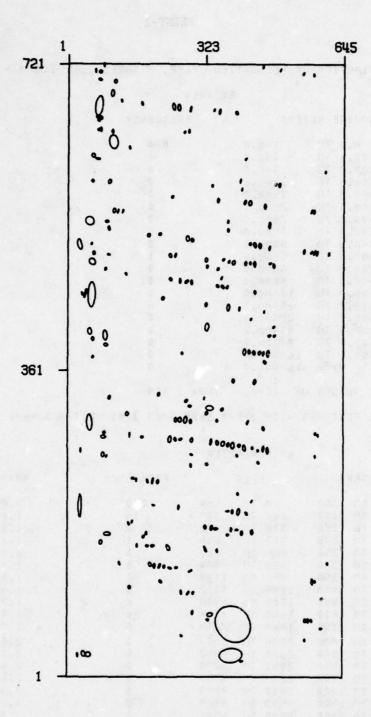
FLINT-1

DISTRIBUTION OF RECOGNIZED TEMP. THRESHOLDS FOR  $\sigma=2.0$  BY AREA

SQUARE	ME	TERS	F	REQUENCY
0.0	TO	100.0		874
100.0	10	200.0		8
200.0	TU	500.0		4
500.0	10	1000.0		2
1000.0	10	1500.0		0
1500.0	TO	2000.0		0
2000.0	TU	2500.0		0 .
2500.0	10	3000.0		0
3000.0	TU	4000.0		0
4000.0	TO	5000.0		1
5000.0	TO	6000.0		0
6000.0	TO	8000.0		0
8000.0	10	10000.0		0
and the second s	TO	15000.0		0
15000.0	10	20000.0		0
20000.0		40000.0		0
40000.0	TO	80000.0		0
	TO	160000.0		0
	ER	160000.0		0

TOTAL NUMBER OF TEMP. THRE 889

		84	PFRI		BY SHAPE			
MET	ERS		FFE	T	FREQUENCY	SHAPE, FA	CTOR	FREQUENCY
0 T	7 5	0	0 10	164	870	0.0 10	1.0	4
50 T	0 10	0 16	A TO	328	14	1.0 TO	1.1	1
100 T	0 15	0 32	B TO	492	2	1.1 10	1.2	63
150 T	J 50	0 49	2 10	656	1	1.2 TO	1.3	133
200 T	n 25	0 65	6 10	820	1		1.4	172
250 T	7 30	0 82	o Tr	984	0	1.4 TO		144
300 T	0 35	0 98	4 10	1148	0	1.5 To	1.6	116
350 T	7 40	0 114	8 10	1312	0		1.7	93
400 T	9 50	0 131	2 Te	1020	0		1.8	47
500 1	7 60	0 164	o To	1968	0		1.9	42
600 T	n 70	0 196	A TO	2296	0		2.0	37
700 T	0 80	0 229	6 Tr	2024	0	2.0 TO	2.2	20
800 T	7 90	0 262	4 TO	2952	0	5.5 10	2.4	10
900 T	0 100	0 295	2 10	3280	0	2.4 TO	2.6	3
1000 T	0 120	0 328	n Tr	3937	1	2.6 10	8.5	2
1200 T	0 140	0 393	7 70	4593	0	OT 8.5	3.0	1
	n 160	0 459	3 T'	5249	0		3.5	0
1600 T	U 500	0 524	9 1"	6501	0	3.5 TO	4.0	0
	R 200		OVER		0	OVER	-	1



FLINT 1
TEMPERATURE THRESHOLD = 2.500
LAMBOA= 9.3 TO 11.7 AM

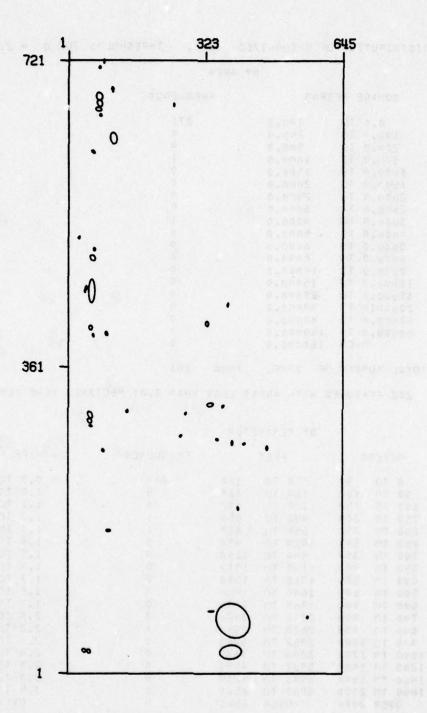
FLINT-1

DISTRIBUTION OF RECOGNIZED TEMP. THRESHOLDS FOR 0 = 2.5

## BY AREA

SQUA	RE ME	TERS	FREQUENCY
0.	0 10	100.0	271
100.	n TO	200.0	4
200.	O TU	500.0	4
	O TO	1000.0	1
1600.		1500.0	0
1500.		2000.0	0
2000.		2500.0	0 .
2500.		3000.0	0
3000.		4000.0	
4000.		5000.0	0
5000.		6000.0	0
6000.		8000.0	0
8000.	100	10000.0	0
1.0000.		15000.0	0
15000.		0.00005	0
20000.		40000.0	0
40000.			0
80000.		160000.0	0
	OVER	160090.0	0
TOTAL NU	MBER	OF TEMP.	THR= 281

. BY PERIMETER						BY SHAPE			
ME	TER	RS	•	FEET		FREQUENCY	SHAPE FAC	TUR	FREQUENCY
0	TO	50	0	TO	164	269	0.0 TO 1	.0	0
50	TN	100	164	TO	328	5	1.0 TO 1	.1	1
100	TO	150	328	TO	492	4	1.1 TO 1	.2	27
150	TO	200	492	TO	656	1	1.2 TO 1	.3	33
200	TO	250	656	TO	820	1	1.3 TO 1	.4	44
250	TO	300	820	TO	994	0		.5	29
	TO	350	984	TO	1148	0		.6	51
350	TO	400	1148	To	1312	0	1.6 TO 1	.7	27
	רז	500	1312	TO	1640	0		.8	85
	TO	600	1640	TO	1968	0		.9	11
	TO	700	1968	TO	2296	0	1.9 TO 2		11
20/10/10	TO	800	2296	TO	2024	0	2.0 TO 2		12
4	TO	900	2624	Tri	2952		2.2 TO 2	N. Carlotte	4
	TO	1000	2952	TO	3290	0	2.4 TO 2		0
	_	1200	3280	TO	3937	0	2.6 10 2	The same	1
		1/100	3937	TO	4573	0	2.8 10 3		1
-	TO	1600	1593	TO	5249	0		.5	0
1600			5249		6561	Ó		.0	0
		5000	1075.157	VER	6561	Ö		.0	i



FLINT 1
TEMPERATURE THRESHOLD = 3.000
LAMBOA = 9.3 TO 11.7 AM

FLINT-1

DISTRIBUTION OF RECOGNIZED TEMP. THRESHOLDS FOR  $\sigma=3.0$  MY APEA

S	DUAR	E M	TER	S	•	REQUEACY
	0.0	TO		100.0		48
1	00.0	TU		200.0		5
2	00.0	10		500.0		1
-	0.00			1000.0		1
10	00.0	10		1500.0		0
	00.0			2000.0		0
	00.0			2500.0		0
	00.0			3000.0		1 .
	00.0			4000.0		0
	00.0			5000.0		0
	00.0			6000.0		0
	00.0			8000.0		0
	00.0	4 00	1	0000.0		0
	00.0			5000.0		0
	00.0			2000.0		0
	00.0		1000	0.000		0
	00.0	TO		0000.0		0
	00.0			0000.0		0
300		VER		0000.0		ő
UTAL	NUM	BER	OF	TEMP.	THR=	53

BY PERIMETER							BY SHAPE		
ME	TER	RS		FEET		FREDHENCY	SHAPE FACTUR	FREQUENCY	
0	TO	50	0	TO	164	40	0.0 70 1.0	0	
50	10	100	164	10	328	3	1.0 70 1.1	1	
100	TO	150	328	Ti	472	0	1.1 70 1.2	3	
150	TO	200	492	TO	656	3	1.2 TO 1.3	11	
200	TO	250	656	TO	820	0	1.3 TO 1.4	9	
250	TO	300	820	TO	984	0	1.4 TO 1.5	6	
300	TO	350	984	TO	1178	0	1.5 TO 1.6	5	
350	17	400	1144	TO	1312	0	1.6 10 1.7	6	
400	10	500	1312	TO	1640	0	1.7 70 1.8	2	
500	TO	600	1640		1968	0	1.8 TO 1.9	5	
600	TO	700	1968	to	2296	0	1.9 70 2.0	0	
700	10	800	2296	TO	2624	0	2.0 TO 2.2	1	
800	TO	900	2624	TO	2952	1	2.2 Ti) 2.4	1	
900	TO	1000	2952	10	3240	0	2.4 10 2.6	1	
1000	19	1200	3290	TO	3937	0	2.6 TO 2.8	0	
1200	10	1400	3937	TO	4595	0	2.8 TO 3.0	0	
1400	10	1000	4593	Tu	5249	0	3.0 To 3.5	1	
1600	In	2000	5249	to	6561	0	3.5 TO 4.0	0	
		5000		VER	6561	0	OVER 4.0	1	

MILLCREEK

RADIANCE THRESHOLD = 1.500

LAMBOR = 1.0 TO 1.4 MM

MILL CREEK

DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR \u00f3 = 1.5

# BY AREA

SQUARE	E ME	TERS	FREQUENCY
0.0	TO	100.0	232
100.0	10	200.0	45
200.0	TU	500.0	25
500.0	10	1000.0	14
1000.0	10	1500.0	5
1500.0		2000.0	3
2000.0	TO	2540.0	0.
2500.0	10	3000.0	0
3000.0	TO	4000.0	2
4000.0	TO	5000.0	3
5000.0	TO	6000.0	
6000.0	TO	8000.0	2
8000.0	TO	10000.0	1
10000.0	TO	15000.0	
15000.0	TO	20000.0	0
20000.0	TU	40000.0	2
40000.0	TO	80000.0	1
80000.0	TO	160000.0	0
	VER	160000.0	0

TOTAL NUMBER OF PADIANCE THRE 337

HY P	Eĸ	I₩	Εī	EH
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## BY SHAPE

HE	TEH	25		FET		FREQUENCY	SHAPE FACTOR	FREQUENCY
0	TO	50		TO	164	229	0.0 TO 1.0	6
50	TO	100	164	TO	328	58	J.0 TO 1.1	5
100	TO	150	328	TO	492	16	1.1 70 1.2	145
150	10	200	492	TO	656	6	1.2 TO 1.3	27
200	TO	250	656	TO	054	7	1.3 10 1.4	43
250	TO	300	820	TO	984	3	1.4 10 1.5	14
300	TO	350	984	TO	1148	2	1.5 70 1.6	11
350	TO	400	1148	TO	1312	1	1.6 70 1.7	5.5
400	TO	500	1312	TO	1640	2	1.7 TO 1.8	15
500	10	600	1640	TO	196A	0	1.8 TO 1.9	7
600	10	700	1968	TO	2296	2	1.9 TO 2.0	12
700	10	800	2296	Tr	2624	0	2.0 70 2.2	9
800	10	900	2624	TO	2952	4	2.2 TU 2.4	3
900	TO	1000	2952	TO	3280	0	2.4 70 2.6	6
1000	TO	1200	3280	TO	3937	0	8.5 nt 6.5	5
1200	TO	1400	3937	Tri	4593	0	2.9 19 3.0	5
1400	10	1600	4593	TII	5249	2	3.0 TO 3.5	1
1600		2000	5249	TO	6561	7	3.5 10 4.0	3
		2000		VEH	6561	Sales administra	OVER 4.0	7

MILLCREEK

RADIANCE THRESHOLD = 2.000 T

LAMBOR = 1.0 TO 1.4 AM

MILL CREEK

# DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR \u00f3 = 2.0

## BY ARFA

SOHARE ME	TERS	FREQUENCY
0.0 TO	100.0	165
100.0 TO	200.0	20
200.0 TO	500.0	26
500.0 TU	1000.0	7
1000.0 TO	1500.0	3
1500.0 10	2000.0	2
2000 n TO	2500.0	1.
2500.0 TO	3000.0	0
3000.0 TU	4000.0	1
4000.0 TU	5000.0	0
5000.0 TO	6000.0	1
6000.0 10	Aunn.n	0
8000.0 TO	10000.0	0
10000.0 TO	15000.0	0
15000.0 TO	20000.0	1
20000.0 10	40000.0	5
40000.0 TO	80000.0	0
80000.0 TO	160000.0	0
OVER	160000.0	0

TOTAL NUMBER OF RADIANCE THRE 229

BY	PERIME	TER		

MI	TF	RS.		FEET		FREQUENCY	SHAPE	FACTUR	FREQUENCY
0	דח	. 50	0	to	164	158	0.0 T	1.0	1
50	TO	100	164	TO	328	34	1.0 7	0 1.1	0
100	17	150	32A	TO	492	15	1.1 T	2.1 0	93
150	In	200	492	TO	656	7	1.2 1	1.3	15
200	Th	250	656		620	3	1.3 7	1.4	56
250	TO	300	820	TO	984	2	1.4 T		16
300	TO	350	984	To	1148	1	1.5 T		15
350	TO	400	1148	TO	1312	0	1.6 T		23
400	In	500	1312	TO	1640	1	1.7 1	1.8	5
500	Th	600	1640	TO	1968	2	1.8 7		4
600	TO	700	1968	Tn	2296	1	1.7 T		4
700	TO	800	2276	TO	2624	1	2.0 T	715 7 2	10
800	TO	900	2621	TI	2452	0	2.2 T	7 2.4	4
900		1000	2952	Tri	3290	0	2.4 11		3
1000		1200	3280	TO	3937	0	2.6 T		3
1200	In	1400	3937	Til	4593	0	.2.8 T	3.0	0
1400	TO	1600	4593	TO	5249	total I	3.0 T		3
1600	1000	2000	5249		6561	1	3.5 1		3
	ALLE STORY	2000		VFR	6501	2		2 4.0	3

BY SHAPE

MILLCREEK

RADIANCE THRESHOLD = 2.500

LAMBOR = 1.0 TO 1.4 AM

## MILL CREEK

DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR  $\sigma=2.5$ 

## BY AREA

SQUARE	METERS	FREQUENCY
0.0 T	0 100.0	138
100.0 T	U 200.0	21
200.0 T	0 500.0	15
500.0 T	U 1000.0	2
1000.0 T	0 1500.0	9
1500.0 T	0 2000.0	0
2000.0 T	U 2500.0	0 .
2500.0 T	U 3000.0	0
3000.0 T	0 4000.0	9
4000.0 1	0 5000.0	1
5000.0 1	0 6000.0	0
6000.0 T	U 8000.0	1
8000.0 T		1
10000.0 1	0 15000.0	0
15000.0 1	U 20000.0	0
20000.0 T	0 40000.0	1
40000.0 T	0 80000.0	0
80000.0 1	0 160000.0	0
DVE	R 160000.0	0

TOTAL NUMBER OF RADIANCE THRE 180

# BY PERIMETER

BY SHAPE

METERS			FEET			FREQUENCY	SHAPE FACTOR	FREQUENCY
0	רז	50	0	To	164	134	0.0 TO 1.0	0
50	10	100	164	TO	328	26	1.0 TO 1.1	0
100	TO	150	328	TO	492	6	1.1 TO 1.2	86
150	TO	200	492	TO	656	6	1.2 TO 1.3	8
200	TO	250	656	TI	820	1	1.3 TO 1.4	50
250	TO	300	820	TO	984	0	1.4 TO 1.5	9
300	TO	350	984	TO	1148	3	1.5 70 1.6	7
350	TO	400	1148	TO	1312	0	1.6 TO 1.7	11
100	TO	500	1312	TO	1640	1	1.7 TO 1.8	10
500	TO	600	1640	TO	1968	0	1.8 TO 1.9	4
600	TO	700	1968	TO	5500	0	1.9 TO 2.0	4
700	TO	800	2296	TO	2624	0	2.0 10 2.2	6
800	TO	900	2624	TO	2952	0	2.2 10 2.4	6
900	TO	1000	2952	TO	3290	1	2.4 70 2.6	0
1000	TO	1200	3280	TO	3937	0 .	2.6 TO 2.8	1
1200	TO	1400	3937	TO	4593	0	2.8 TO 3.0	1
1400	TO	1600	4593	Ti	5249	2	3.0 TO 3.5	5
1600	TO	2000	5249	TO	6501	0	3.5 Til 4.0	5
OVER 2000		5000	OVER		6561	er entere	OVER 4.0	3

MILLCREEK

RADIANCE THRESHOLD = 3.000

LAMBOR= 1.0 TO 1.4 AM

DISTRIBUTION OF RECOGNIZED RADIANCE THRESHOLDS FOR  $\sigma = 3.0$ 

#### HY AREA

SQUARE M	ETERS	FREQUENCY
0.0 10	100.0	173
100.0 TO	200.0	7
200.0 TU	500.0	7
500.0 10	1000.0	3
1000.0 TO	1500.0	0
1500.0 10	2000.0	0
2000.0 TO	2500.0	0 .
2500.0 10	3000.0	0
3000.0 TU	4000.0	0
4000.0 10	5000.0	0
5000.0 TO	6000.0	0
6000.0 TU	8000.0	0
8000.0 TO	10000.0	0
10000.0 10	15000.0	0
15000.0 TO	20000.0	0
20000.0 10	40000.0	0
40000.0 10	80000.0	0
80000.0 10	160000.0	0
OVER		0

TOTAL NUMBER OF RADIANCE THRE 190

3937 10

4593 TO 5249 TO

4593

5249

6561

OVER 6561

1000 TO 1200 1200 TO 1400

1400 TO 1600 1600 TO 2000

DAFS 5000

BY PERIMETER

M	ETE	25	1	FEET		FREGUENCY	SHAPE FACTOR	FREQUENCY
0	TO	50	. 0	TO	164	169	0.0 70 1.0	0
50	TO	100	164	TI	328	11	1.0 TO 1.1	0
100	TO	150	328	TO	492	4	1.1 70 1.2	128
150	TO	200	492	TO	656	5	1.2 10 1.3	3
200	TO	250	656	10	820	0	1.3 TO 1.4	14
250	TO	300	820	TO	984	1	1.4 TO 1.5	2
300	In	350	984	TO	1148	0	1.5 70 1.6	14
350	TO	400	1148	Tn	1312	0	1.6 TO 1.7	14
400	TO	500	1312	TO	1640	0	1.7 70 1.8	4
500	TO	600	1640	Til	1968	0	1.8 TO 1.9	2
600	TO	700	1968	TO	5596	0	1.9 10 2.0	1
700	TO	800	2296	TO	2024	0	2.5 01 0.5	2
800	10	900	2624	T()	2952	0	2.2 TO 2.4	2
900	10	1000	2952	TO	3280	0	2.4 10 2.6	0
1000	TO	1200	3280	TO	3937	0	2.6 TO 2.8	5
			****					

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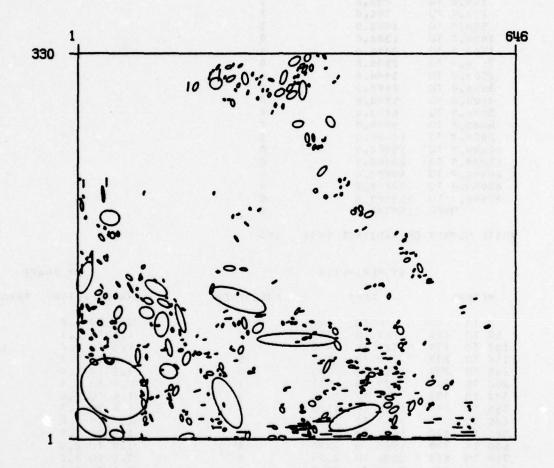
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BY SHAPE .

2.8 TO 3.0

3.0 TO 3.5 3.5 TO 4.0

TVER 4.0



MILL CREEK
TEMPERATURE THRESHOLD = 1.5 σ
LAMBDA= 9.3 TO 11.7 μM

DISTRIBUTION OF PECOGNIZED FEMP. THRESHOLDS FOR  $\sigma=1.5$ BY AREA

SUHAR	E ME	TERS	FREQUENCY
0.0	10	100.0	568
100.0	TO	200.0	70
200.0	70	500.0	54
500.0	10	1000.0	21
1000.0	Tiu	1500.0	8
1500.0	10	2000.0	3
2000.0	TO	2500.0	1 .
2500.0	TO	3000.0	0
3000.0	TO	4000.0	4
4000.0	TU	5000.0	0
5000.0	TO	6000.0	1
6000.0	TU	8000.0	0
8000.0	11	10000.0	1
10000.0	10	15000.0	4
15000.0	10	20000.0	0
20000.0	TO	40000.0	0
40000.0	10	80000.0	1
80000.0	TO	160000.0	0
	VER	160000.0	0

TOTAL NUMBER OF TEMP. THRE 736

		BA BEBI	ETER			BY SH	APE
METE	RS	FEET		FREGUENCY	SHAPE	ACTUR	FREWUENCY
0 10	50	0 10	164	553	0.0 To	1.0	2
50 TO	100	164 TO	324	91	1.0 T	1 1.1	0
100 TO	150	328 TO	495	37	. 1.1 To	1.2	378
150 TO	200	492 TO	656	50	1.2 70	1.3	85
200 17	250	656 TO	820	10	1.3 19		91
250 TO		820 TO	984	3	1.4 7		29
300 TO	350	984 TO	1148	4	1.5 1		25
350 TO		IIAA TO	1312	3	1.5 T		37
400 TO		1312 TO	1640	3	1.7 7		31
500 TO		1640 TO	1968	1		1.9	24
600 TO		1968 TO	2296	2		1 2.0	15
700 TO		2296 TO	2624	3		1 2.2	85
800 TO		2620 TO	2952		2.2 1		17
900 TO		2952 10	3290	ò		2.6	10
	1200	3280 TO	3937	Ŏ		1 2.8	5
	1400	3937 TO	4593	0		3.0	4
1400 77		4593 TO	5249	ŏ	3.0 1		6
1600 TO		5249 TO	6561	0	3.5 TO		4
	2000	DVER	6561	5		2 4.0	5

AD-A077 584

UNCLASSIFIED

ENVIRONMENTAL RESEARCH INST OF MICHIGAN ANN ARBOR IN--ETC F/G 17/5 STATISTICAL ANALYSIS OF TERRAIN BACKGROUND MEASUREMENTS DATA.(U) MAR 77 R SPELLICY, J BEARD, J R MAXWELL N00123-76-C-0708 ERIM-120500-12-F

4 OF 4 AD A 077 584









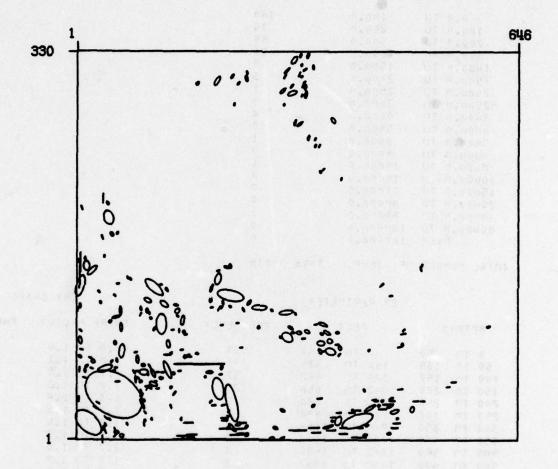








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MILLCREEK

TEMPERATURE THRESHOLD = 2.000

LAMBDA = 9.3 TO 11.7 MM

MILL CREEK

DISTRIBUTION OF RECOGNIZED TEMP. THEFSHOLDS FOR 0 = 2.0

## HY AREA

SQUARE M	FREDUENC	
0.0 10	100.0	383
100.0 TO	200.0	37
200.0 10	500.0	28
500.0 TO	1000.0	10
1000.0 TU	1500.0	3
1500.0 TU	2000.0	2
2000.0 TO	2500.0	5
2500.0 TU		1 .
3000.0 TO	4000.0	1
4000.0 TO		2
5000.0 TO		0
6000.0 TU	8000.0	1
8000.0 TO	10000.0	0
10000.0 10	15000.0	0
.15000.0 TO	20000.0	0
20000.0 TU	40000.0	1
40000.0 TO	80000.0	0
80000.0 TO		0
OVER	160000.0	0

TOTAL NUMBER OF TEMP. THRE 471

Ь	Y	P	Ε	H	1	۳	E	ı	E	7

## HY SHAPE

М	TER	₹5	,	FEET		FREQUENCY	SHAPE FACTU	R FREQUENCY
0	70	50	. 0	TO	164	373	0.0 TO 1.0	0
50	Tn	100	164	TO	328	49	1.0 TO 1.1	0
100	TO	150	328	10	492	20	1.1 70 1.2	255
150	TO	200	492	TO	656	9	1.2 70 1.3	19
200	TO	250	656	TO	820	4	1.3 70 1.4	51
250	TT	300	820	10	984	4	1.4 75 1.5	14
300	TO	350	984	TO	1148	2	1.5 10 1.6	20
350	TO	400	1148	to	1312		1.6 70 1.7	29
400		500	1312	TO	1640		1.7 70 1.8	18
500		600	1640	TO	1968	2	1.8 70 1.9	12
600		700	1968	TI	2296	2	1.9 10 2.0	8
700	TO	800	2296	TO	2624	0	2.0 70 2.2	12
800		900	2624	TO	2952	2	2.2 10 2.4	10
900		1000	2952	10	3280	1	2.4 TO 2.6	
1000	and the later	1200	3280	TO	3937	0	2.6 70 2.8	3
1200		1400	3937	TO	4595	0	2.8 10 3.0	5
	1000	1600	4593	TO	5249	0	3.0 10 3.5	
The second second	The Control	2000	5249		6561	0	3.5 TO 4.0	
		2000		VER	6561	0 0 5 01 = 50	OVER 4.0	

330

MILLCREEK

TEMPERATURE THRESHOLD = 2.500

LAMBDA = 9.3 TO 11.7 MM

DISTRIBUTION OF RECOGNIZED TEMP. THRESHOLDS FOR  $\sigma=2.5$ BY APEA

SQUARE ME	TERS	FREQUENCY
0.0 TO	100.0	229
100.0 10	200.0	16
200.0 10	500.0	11
500.0 TJ	1000.0	5
1000.0 TU	1500.0	3
1500.0 TU	2000.0	2
2000.0 TO	2500.0	1
2500.0 TU	3000.0	1 .
3000.0 TO	4000.0	0
4000.0 TO	5000.0	0
5000.0 TO	6000.0	0
6000.0 10	8000.0	0
8000.0 TO	10000.0	0
10000.0 TO	15000.0	1
15000.0 TO	20000.0	0
20000.0 Ti)	40000.0	0
40000.0 TO	80000.0	0
80000.0 10	160000.0	0
OVER	160000.0	0

TOTAL NUMBER OF TEMP. THRE 266

		BY PERI	ETER		BY SH	APE .
MET	FRS	FEET		FREGUENCY	SHAPE FACTUR	FREQUENCY
0 T	7 50	0 10	164	223	0.0 TO 1.0	0
50 T	100	164 Tr)	328	22	1.0 70 1.1	0
100 T	150	328 TO	492	8	1.1 70 1.2	161
150 T	005 C	492 TO	656	3	1.2 TO 1.3	9
200 1	250	656 TO	059		1.3 70 1.4	2.7
250 T	7 300	820 10	984	1	1.4 10 1.5	10
300 1	350	984 10	1148	2	1.5 TU 1.6	11
350 T	1 400	1148 TO	1312	0	1.6 TO 1.7	15
400 1	500	1312 70	1640	2	1.7 70 1.8	6
500 T	1 600	1640 TO	1968	1	1.8 TO 1.9	2
600 T	700	1968 TU	2296	1	1.9 TO 2.0	6
700 T	800	2296 TO	2624	0	2.5 07 0.5	5
800 T	900	2624 TO	2952	0	2.2 TO 2.4	3
900 1	1000	2952 TO	3280	1	2.4 70 2.6	5
1000 T	0051 0	3280 10	3937	0	2.6 70 2.8	5
1200 T	1400	3937 10	4593	0	2.8 TO 3.0	2
1400 T	1600	4593 TG	5240	0	3.0 TO 3.5	0
1600 T	0000	5249 TO	6501	0	3.5 TO 4.0	3
OVE	R 2000	OVER	6561	DEG LOSSES	OVER 4.0	5

330

and Jan

MILLCREEK
TEMPERATURE THRESHOLD = 3.000
LAMBOA = 9.3 TO 11.7 MM

DISTRIBUTION OF RECOGNIZED TEMP. THRESHOLDS FOR a = 3.0

## BY AREA

SQUAR	E ME	TFRS	F	SEUNENC
0.0	TO	100.0		112
100.0	TO	200.0		15
200.0	10	500.0		7
500.0	TO	1000.0		1
1000.0	TO	1500.0		0
1500.0	TU	2000.0		0
2000.0	TU	2500.0		0
2500.0	10	3000.0		0 .
3000.0	TO	4000.0		0
4000.0	10	5000.0		1
5000.0	TO	6000.0		0
6400.0	TO	8000.0		0
8000.0	10	10000.0		0
10000.0	TU	15000.0		0
15000.0		20000.0		0
20000.0	TO	40000.0		0
40000.0		80000.0		0
80000.0	-	160000.0		0
	VER	160000.0		0
OTAL NUM	BER I	OF TEMP.	THR=	133

## BY PERIMETER

## BY SHAPE

М	TE	RS		FEET		FREGUENCY	SHAPE FACTOR	FREQUENCY
0	רח	50	. 0	TO	164	106	0.0 70 1.0	0
50	TO	100	164	TO	328	17	1.0 70 1.1	0
100	TO	150	328	TO	492	5	1.1 70 1.2	77
150	TO	200	492		656	2	1.2 TO 1.3	4
200	TO	250	656	TO	820	2	1.3 TO 1.4	15
250	TO	300	820	TO	994	0	1.4 TO 1.5	4
300	10	350	984	TU	1148	0	1.5 TO 1.6	6
350	TO	400	1148	TO	1312	0	1.6 TO 1.7	3
400	TO	500	1312	TO	1630	0	1.7 70 1.8	4
500	TO	600	1640	to	1968	0	1.8 10 1.9	4
600	TO	700	1968	TO	5546	0	1.9 TO 2.0	4
700	TO	800	2296	A SECOND STATE OF THE PARTY OF	2624	0	5.5 UT 0.5	3
800	TO	900	2624	10	2952	0	2.2 TO 2.4	1
900	TO	1000	2952	TO	3290	0	2.4 70 2.6	5
1000	TO	1200	3280	TO	3937	0	2.6 TO 2.8	1
1200	TO	1400	3937	TO	11593	1	2.8 10 3.0	1
1400	TO	1600	4595	1000	5249	0	3.0 TO 3.5	0
1600		2000	5249	The state of the s	6561	0	3.5 TO 4.0	0
		2000		VER	6561	0	OVER 4.0	1

# ARTIFICIAL COLOR COMPOSITE IMAGE FOR FLINT-1 AND THE PSEUDO-IMAGE GENERATED USING AREA/INTENSITY STATISTICS

Color	Intensity Range	No. of Ellipses In Pseudo-Image
Red	4σ and Above	9
Yellow	3σ to 4σ	102
Green	2σ to 3σ	1127
Blue	lo to 2o	2163
Brown	Below lo	

Mean = 294 K σ = 3.1 K 1 ..... Yellow = 30% - 307°K Red = 307 - 310°K \*\*\*\*\* .... Blue = 295 - 300°K Green = 301 - 304°K Brown = <296°K .... .... \*\*\* ... .. .. .. .. .. .. \*\*\*\* . ..... \*\* .... .... .... .... .... Tool to make the ....... \*\*\*\*\*\*\* . ... ... \*\*\*\* ....... \* \*\* \*\*\*\*\* \*\*\*\* \*\*\*\*\*\*\*\*\*\*\*

9.3 - 11.7 µm CHANNEL OF FLINT-1.

ARTIFICIAL COLOR REPRESENTATION OF THE PSEUDO-IMAGE GENERATED FROM THE 9.3 - 11.7  $\mu$ m CHANNEL OF FLINT-1.